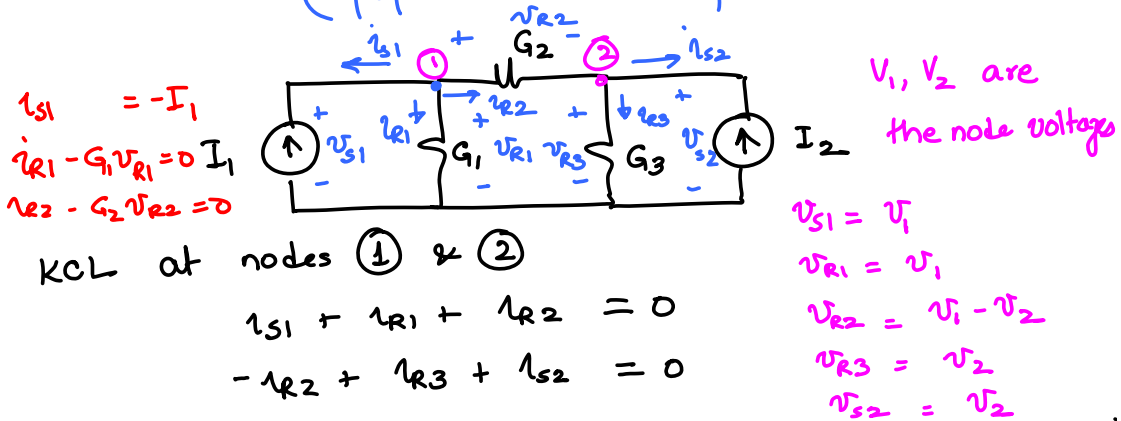


Office Hours: Tu/Th 5-6 pm KEC 4095
 & by appointment

Formulation of circuit equations

- Nodal analysis (NA)
- **Modified** nodal analysis (MNA)
 (paper on MNA posted on class website)



$$\underbrace{\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1 & 1 \end{bmatrix}}_A \begin{bmatrix} I_{S1} \\ I_{R1} \\ I_{R2} \\ I_{R3} \\ I_{S2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

incidence matrix

General form $AI_b = 0$ KCL

Branch to node voltage relations

$$\begin{bmatrix} V_{S1} \\ V_{R1} \\ V_{R2} \\ V_{R3} \\ V_{S2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 1 & -1 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

$V_b = A^T V_n$

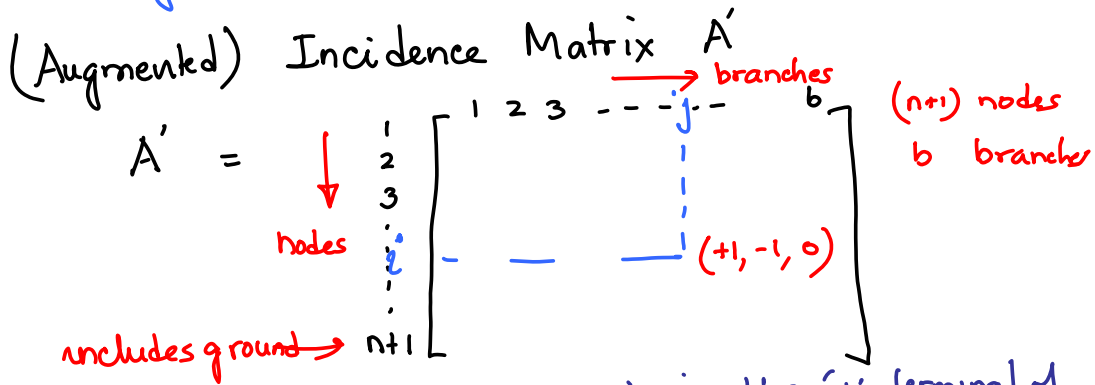
BCR or BCE

$$\begin{bmatrix} I_{S1} \\ I_{R1} \\ I_{R2} \\ I_{R3} \\ I_{S2} \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & G_1 & 0 & 0 & 0 \\ 0 & 0 & G_2 & 0 & 0 \\ 0 & 0 & 0 & G_3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} V_{S1} \\ V_{R1} \\ V_{R2} \\ V_{R3} \\ V_{S2} \end{bmatrix} = \begin{bmatrix} I_1 \\ 0 \\ 0 \\ 0 \\ -I_2 \end{bmatrix}$$

$$I_b - G_b V_b = S$$

In general:

$$K_i I_b + K_v V_b = S$$



$$A_{ij} = +1 \quad \text{if node } i \text{ is the '+' terminal of branch } j$$

$$A_{ij} = -1 \quad \text{if node } i \text{ is the '-' terminal of branch } j$$

$$A_{ij} = 0 \quad \text{if node } i \text{ is not connected to branch } j$$

All columns will have 2 entries
 \hookrightarrow sum up to zero

The Sparse Tableau Analysis (STA) 1969-71 by IBM research

KCL $A I_b = 0$

$$\begin{matrix} \uparrow \\ n \text{ nodes} \\ \downarrow \end{matrix} \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} I_1 \\ \vdots \\ I_b \end{bmatrix} = 0$$

KVL $V_b = A^T V_n \Rightarrow V_b - A^T V_n = 0$

BCR $K_i I_b + K_v V_b = S$

Ex R: $I_b - G V_b = 0$

V: $0 I_b - V_b = V_s$

$$A I_b = 0$$

$$V_b - A^T V_n = 0$$

$$K_i I_b + K_v V_b = S$$

$$\begin{bmatrix} I_b \\ \hline V_b \\ \hline V_n \end{bmatrix}$$

$$\begin{bmatrix}
 \begin{array}{ccc|ccc}
 \xrightarrow{b} & \xrightarrow{b} & \xrightarrow{n} & & & \\
 A & 0 & 0 & I_{b1} & & \\
 \hline
 0 & I & -A^T & I_{b2} & & \\
 \hline
 K_i & K_v & 0 & I_{bb} & & \\
 \hline
 & & & V_{b1} & \vdots & \\
 & & & V_{nb} & & \\
 & & & V_{n1} & & \\
 & & & V_{nn} & &
 \end{array}
 & = &
 \begin{bmatrix}
 0 \\
 0 \\
 S
 \end{bmatrix}
 \end{bmatrix}$$

$n + 2b$ unknowns; $n + 2b$ equations;
 A has at most $2b$ non zero entries
 A^T " " " $2b$ " "
 I has b nonzeros
 K_i, K_v have at most b non zero entries

Maximum # of non zero entries $2b + 2b + b + b + b = 7b$
 Matrix size $(n + 2b) \times (n + 2b) \Rightarrow$ very sparse matrix

Summary of STA :

- can be applied to any circuit
- Equations can be assembled by inspection
- STA matrix is very sparse

Derive NA from STA

$$A I_b = 0$$

$$V_b - A^T V_n = 0$$

$$K_i I_b + K_v V_b = S$$

For NA
$$I_b = \underbrace{K_i^{-1}}_{K_i \text{ is invertible}} [S - K_v V_b]$$

$$A I_b = A K_i^{-1} [S - \underbrace{K_v V_b}_{A^T V_n}] = 0$$

$$A K_i^{-1} [S - K_v A^T V_n] = 0$$

$$\underbrace{A K_i^{-1} K_v A^T}_{\text{NA matrix}} \underbrace{V_n}_{\text{node voltages}} = \underbrace{A K_i^{-1} S}_{\text{NA source}}$$

General Form

$Ax = b$ is a system of equations
 ↑
 not the incidence matrix

$x = A^{-1} b$ A is a nonsingular matrix

Solution methods

- 1) Direct methods
 - Gaussian Elimination
 - LU Decomposition
- 2) Indirect methods (iterative methods)
 - Gauss Jacobi/Seidel
 - ⋮

Gaussian Elimination (GE)

$$Ax = b$$

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$\text{row 2} = \text{row 2} - \frac{a_{21}}{a_{11}} \text{row 1}$$

$$\begin{array}{l} \xrightarrow{a_{22}} \\ \xrightarrow{a_{n2}} \end{array} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} - \frac{a_{21}}{a_{11}} a_{12} & \dots & a_{2n} - \frac{a_{21}}{a_{11}} a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a_{n2} - \frac{a_{n1}}{a_{11}} a_{12} & \dots & a_{nn} - \frac{a_{n1}}{a_{11}} a_{1n} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2^{(2)} - \frac{a_{21}}{a_{11}} b_1 \\ \vdots \\ b_n^{(2)} - \frac{a_{n1}}{a_{11}} b_1 \end{bmatrix}$$

multiples

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22}^{(2)} & \dots & a_{2n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a_{n2}^{(2)} & \dots & a_{nn}^{(2)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1^{(2)} \\ b_2^{(2)} \\ \vdots \\ b_n^{(2)} \end{bmatrix}$$

⋮

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22}^{(2)} & \dots & a_{2n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn}^{(n)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1^{(2)} \\ b_2^{(2)} \\ \vdots \\ b_n^{(n)} \end{bmatrix}$$

This is an upper triangular system

Solve for $x_n = \frac{b_n^{(n)}}{a_{nn}^{(n)}}$

$$x_{n-1} = \frac{b_{n-1}^{(n-1)} - a_{n-1,n}^{(n-1)} x_n}{a_{n-1,n-1}^{(n-1)}}$$

$$\vdots$$

$$x_i = \frac{b_i - \sum_{j=2}^n a_{ij} x_j}{a_{ii}}$$

This process is called backward substitution

- Overall GE:
- 1) triangularization
 $A \rightarrow$ Upper triangular matrix U
 - 2) backward substitution/solve

Triangularization (assume $A[i][i] \neq 0$)

- For $i = 1$ to n $\left\{ \begin{array}{l} \text{each row } \alpha = 1/A[i][i] \\ \text{each row below row } i \\ m = \alpha * A[j][i] \end{array} \right.$
- ⊥ division
 $(n-i)$ mult
- For $k = i+1$ to n $\left\{ \text{traverse row } j \right.$
- $A[j][k] = A[j][k] - m * A[i][k]$
- $(n-i)(n-i)$ mult
 $(n-i)(n-i)$ addition

$$(n-i) \text{ mult} \quad \left. \begin{array}{l} \{ \\ \} \end{array} \right\} b[j] = b[j] - m * b[i]$$

$$\text{Total \# of mult/div} \quad \left. \begin{array}{l} \{ \\ \} \end{array} \right\} 1 + \frac{(n-i) + (n-i)(n-i) + \underbrace{(n-i)}_{\text{RHS}}}{(n-i)(n-i+1)}$$

$$\sum_{i=1}^n (n-i)(n-i+1) + (n-i) + 1$$

$$\frac{n^3 - n}{3} \quad \frac{n^2 - n}{2} \quad \sim \frac{n^3}{3}$$

Backward substitution $\sim n^2/2$

What about solving $Ax = b$

$$= b_A$$

$$= b_B$$

$$\vdots$$

$$= b_x$$

$$A \rightarrow \begin{bmatrix} \diagup & U \\ 0 & \diagdown \end{bmatrix} [x] = \text{RHS}$$

LU Factorization (or Decomposition)

$$A \rightarrow \begin{bmatrix} \diagup & U \\ L & \diagdown \end{bmatrix} [x] = b$$

$$b_1^{(1)} = b_1$$

$$b_2^{(2)} = b_2 - \frac{a_{21}}{a_{11}} b_1^{(1)}$$

$$\vdots$$

$$b_n^{(n)} = b_n - \frac{a_{n1}}{a_{11}} b_1^{(1)} - \frac{a_{n2}}{a_{22}} b_2^{(2)} - \dots - \frac{a_{n,n-1}}{a_{n-1,n-1}} b_{n-1}^{(n-1)}$$

$$\begin{bmatrix} 1 & & & & \\ l_{21} & 1 & & & \\ l_{31} & l_{32} & 1 & & \\ \vdots & \vdots & \vdots & \ddots & \\ l_{n1} & l_{n2} & \dots & l_{n,n-1} & 1 \end{bmatrix} \begin{bmatrix} b_1^{(1)} \\ b_2^{(2)} \\ \vdots \\ b_n^{(n)} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$Ax = b$$

$$L(Ux) = b$$



$$\sim n^2/2$$

$$\sim n^2/2$$

$$Ly = b.$$

$$Ux = y$$

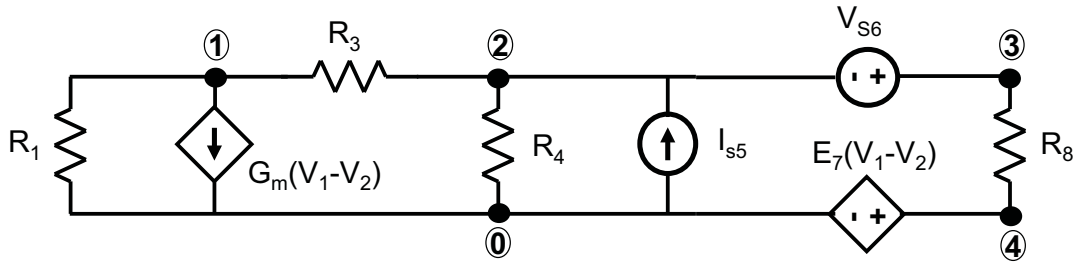
Forward Substitution

Backward Substitution

One time operation LU Factorization $\sim n^3/3$

Repeated Forward/Back solves for different
RHS $\sim n^2$

MNA Example



$$\begin{bmatrix} \frac{1}{R_1} + G_m + \frac{1}{R_3} & -\left(G_m + \frac{1}{R_3}\right) & 0 & 0 & 0 & 0 \\ -\frac{1}{R_3} & \frac{1}{R_3} + \frac{1}{R_4} & 0 & 0 & -1 & 0 \\ 0 & 0 & \frac{1}{R_8} & -\frac{1}{R_8} & 1 & 0 \\ 0 & 0 & -\frac{1}{R_8} & \frac{1}{R_8} & 0 & 1 \\ 0 & -1 & 1 & 0 & 0 & 0 \\ E_7 & -E_7 & 0 & -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ i_6 \\ i_7 \end{bmatrix} = \begin{bmatrix} 0 \\ I_{s5} \\ 0 \\ 0 \\ V_{s6} \\ 0 \end{bmatrix}$$

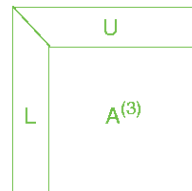
$$\begin{bmatrix} Y_n & B \\ C & 0 \end{bmatrix} \begin{bmatrix} v \\ i \end{bmatrix} = S$$

From: A. Nardi

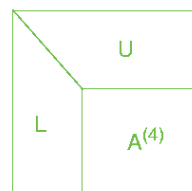
Pivoting for Accuracy

Example 1: After two steps of G.E. MNA matrix becomes:

$$\begin{bmatrix} x & x & 0 & 0 & 0 & 0 \\ 0 & x & 0 & 0 & x & 0 \\ 0 & 0 & \frac{1}{R} & -\frac{1}{R} & 1 & 0 \\ 0 & 0 & -\frac{1}{R} & \frac{1}{R} & 0 & 1 \\ 0 & 0 & x & 0 & x & 0 \\ 0 & 0 & 0 & x & x & 0 \end{bmatrix}$$



$$\begin{bmatrix} x & x & 0 & 0 & 0 & 0 \\ 0 & x & 0 & 0 & x & 0 \\ 0 & 0 & \frac{1}{R} & -\frac{1}{R} & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & x & x & 0 & 0 \\ 0 & 0 & x & x & 0 & 0 \end{bmatrix}$$



$$l_{i4} = \frac{a_{i4}^{(4)}}{a_{44}^{(4)}} = \infty !!!$$

Solution:

Interchange rows and/or columns to bring non-zero element into position (k,k):

$$\begin{bmatrix} 0 & 1 & 1 \\ x & x & 0 \\ x & x & 0 \end{bmatrix} \rightarrow \begin{bmatrix} x & x & 0 \\ 0 & 1 & 1 \\ x & x & 0 \end{bmatrix}$$

Example 2:

$$\begin{bmatrix} 1.25 \times 10^{-4} & 1.25 \\ 12.5 & 12.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 \end{bmatrix}$$

solution to 5 digit accuracy

$$x_1 = 1.0001$$

$$x_2 = 5.0000$$

13

From: A. Sangiovanni-Vincentelli

Problem with Small Pivots

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 12.5 & 12.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 \end{bmatrix}$$

GE

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 0 & 12.5 - 1.25 \cdot 10^5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 - 6.25 \cdot 10^5 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_{5 \text{ digits}} = \begin{bmatrix} 1.0001 \\ 4.9999 \end{bmatrix}$$

From: A. Nardi

Problem with Small Pivots

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 12.5 & 12.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 \end{bmatrix}$$

GE

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 0 & 12.5 - 1.25 \cdot 10^5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 - 6.25 \cdot 10^5 \end{bmatrix}$$

Rounded to 3 digits

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 0 & -1.25 \cdot 10^5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ -6.25 \cdot 10^5 \end{bmatrix}$$

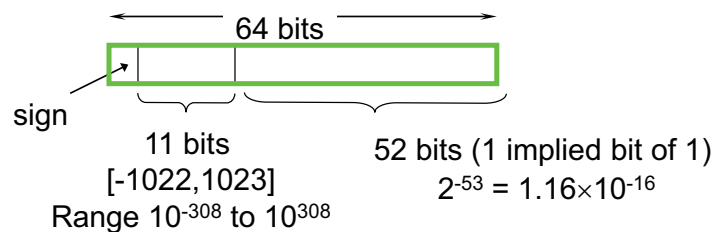
From: A. Nardi

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_{3\text{digits}} = \begin{bmatrix} 0 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_{5\text{digits}} = \begin{bmatrix} 1.0001 \\ 4.9999 \end{bmatrix}$$

Floating Point Arithmetic

Double precision number (IEEE Representation)



Machine precision: $\varepsilon \cong 10^{-16}$

$\Rightarrow 1 + \varepsilon = 1$

Avoid sum/subtraction of large and tiny numbers

\Rightarrow Avoid big multipliers

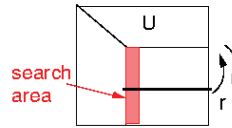
\Rightarrow Do NOT use equalities in floating point arithmetic

Pivoting Strategies

1. Partial Pivoting: (row interchange only)

choose r as the smallest integer such that

$$|a_{rk}^{(k)}| = \max_{j=k, \dots, n} |a_{jk}^{(k)}|$$

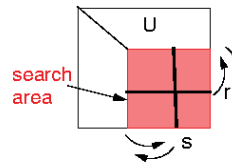


2. Complete Pivoting

(row and column interchange)

Choose r and s as the smallest integers such that

$$|a_{rk}^{(k)}| = \max_{\substack{i=k, \dots, n \\ j=k, \dots, n}} |a_{ij}^{(k)}|$$



3. Threshold Pivoting

a. Apply partial pivoting only if $|a_{kk}^{(k)}| < \varepsilon_p |a_{rk}^{(k)}|$

b. Apply complete pivoting only if $|a_{kk}^{(k)}| < \varepsilon_p |a_{rs}^{(k)}|$

15

From: A. Sangiovanni-Vincentelli

Partial Pivoting for Small Pivots

$$\begin{bmatrix} 1.25 \cdot 10^{-4} & 1.25 \\ 12.5 & 12.5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 6.25 \\ 75 \end{bmatrix}$$

swap

↙

$$\begin{bmatrix} 12.5 & 12.5 \\ 1.25 \cdot 10^{-4} & 1.25 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 75 \\ 6.25 \end{bmatrix}$$

GE

$$\begin{bmatrix} 12.5 & 12.5 \\ 0 & 1.25 - 12.5 \cdot 10^{-5} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 75 \\ 6.25 - 75 \cdot 10^{-5} \end{bmatrix}$$

Rounded to 3 digits

$$\begin{bmatrix} 12.5 & 12.5 \\ 0 & 1.25 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 75 \\ 6.25 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_{3 \text{ digits}} = \begin{bmatrix} 1 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_{5 \text{ digits}} = \begin{bmatrix} 1.0001 \\ 4.9999 \end{bmatrix}$$

From: A. Nardi