

Intermodulation Distortion (IMD)

IM occurs when 2 or more sinusoidal inputs are applied to a nonlinear circuit

Recall power series representation:

$$v_o = a_1 v_i + a_2 v_i^2 + a_3 v_i^3 + \dots$$

Let the input be

$$v_i = V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t$$

Then

$$\begin{aligned} v_o = & a_1 (V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t) + \\ & a_2 (V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t)^2 + \\ & a_3 (V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t)^3 + \\ & \dots \end{aligned}$$

Second-Order Term

$$a_2 v_i^2 = a_2 (V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t)^2$$

$$\begin{aligned} = & a_2 V_{1A}^2 \cos^2 \omega_1 t + a_2 V_{2A}^2 \cos^2 \omega_2 t \\ & + 2a_2 V_{1A} V_{2A} \cos \omega_1 t \cos \omega_2 t \end{aligned}$$

$$\begin{aligned} = & \frac{1}{2} a_2 (V_{1A}^2 + V_{2A}^2) + \frac{1}{2} a_2 V_{1A}^2 \cos 2\omega_1 t + \frac{1}{2} a_2 V_{2A}^2 \cos 2\omega_2 t \\ & + a_2 V_{1A} V_{2A} \cos(\omega_1 + \omega_2)t + a_2 V_{1A} V_{2A} \cos(\omega_1 - \omega_2)t \end{aligned}$$

Intermodulation (Quadratic Term)

Frequency	0	$2f_1$	$2f_2$	$f_1 \pm f_2$
Amplitude	$\frac{a_2}{2} [V_{1A}^2 + V_{2A}^2]$	$\frac{a_2}{2} V_{1A}^2$	$\frac{a_2}{2} V_{2A}^2$	$a_2 V_{1A} V_{2A}$

- Second-order term produces a dc shift
- Output has 2nd harmonics of input signals
- Terms at sum/difference frequencies → **beat terms**
- IM_2 refers to 2nd-order terms
- IM_2 produced by even-order terms of power series
- Low input levels IM_2 due to quadratic term

IM_2 Distortion

IM_2 is the ratio of the amplitude of one of the beat terms to the amplitude of the fundamental

$$IM_2 = \frac{a_2 V_{1A} V_{2A}}{a_1 V_{1A}} = \frac{a_2}{a_1} V_{2A}$$

For simplicity, IM_2 is defined for equal amplitudes of the two input signals ($V_{1A} = V_{2A}$)

$$IM_2 = \frac{a_2}{a_1} V_{1A} = 2 \left(\frac{1}{2} \frac{a_2}{a_1} V_{1A} \right) = 2HD_2$$

IM_2 in terms of the fundamental of the output ($V_{oA} \approx a_1 V_{1A}$)

$$IM_2 = \frac{a_2}{a_1^2} V_{oA}$$

Intermodulation (Cubic Term) IM_3

$$\begin{aligned}
 a_3 v_i^3 &= a_3 (V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t)^3 \\
 &= a_3 V_{1A}^3 \cos^3 \omega_1 t + 3a_3 V_{1A} V_{2A}^2 \cos \omega_1 t \cos^2 \omega_2 t \\
 &\quad + 3a_3 V_{1A}^2 V_{2A} \cos^2 \omega_1 t \cos \omega_2 t + a_3 V_{2A}^3 \cos^3 \omega_2 t
 \end{aligned}$$

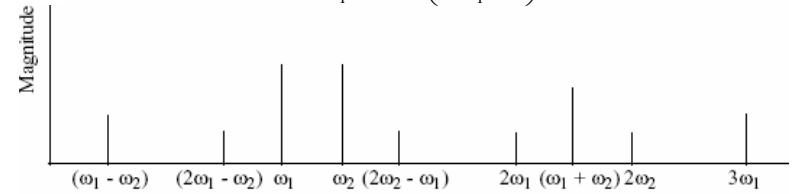
Frequency	f_1	f_2	$2f_1 \pm f_2$	$2f_2 \pm f_1$	$3f_1$	$3f_2$
Amplitude	$\frac{3a_3}{4} [V_{1A}^3 + V_{1A} V_{2A}^2]$	$\frac{3a_3}{4} [V_{2A}^3 + V_{1A}^2 V_{2A}]$	$\frac{3}{4} a_3 V_{1A}^2 V_{2A}$	$\frac{3}{4} a_3 V_{1A} V_{2A}^2$	$\frac{1}{4} a_3 V_{1A}^3$	$\frac{1}{4} a_3 V_{2A}^3$

Common test condition for IM_3 is to have equal amplitudes of the two input signals ($V_{1A} = V_{2A}$)

$$V_o(IM_3) = \frac{3}{4} a_3 V_{1A}^3 \quad IM_3 = \frac{3}{4} \frac{a_3 V_{1A}^3}{a_1 V_{1A}} = \frac{3}{4} \frac{a_3}{a_1} V_{1A}^2$$

IM3 Distortion

$$IM_3 = \frac{3}{4} \frac{a_3}{a_1} V_{1A}^2 = 3 \left(\frac{1}{4} \frac{a_3}{a_1} V_{1A}^2 \right) = 3HD_3$$



- Third-order IM components ($2\omega_1 - \omega_2$ and $2\omega_2 - \omega_1$) are close to the fundamentals if ω_1 is close to ω_2
- This commonly occurs with broadcast receiver applications
- IM3 terms may fall in the passband of the receiver and cannot be filtered out

Triple Beat (TB) Distortion

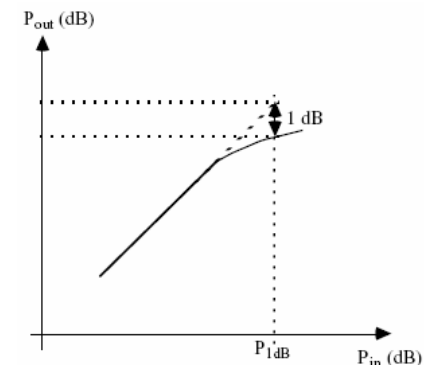
- When three or more input signals are present at the input of an amplifier, more beat terms are obtained
- For the case of three input signals, a 'triplebeat' results

$$V_o(TB) = \frac{3}{2} a_3 V_{1A} V_{2A} V_{3A} \cos(\omega_1 \pm \omega_2 \pm \omega_3) t$$

$$TB = \frac{3}{2} \frac{a_3}{a_1} V_{1A}^2 = 2IM_3 = 6HD_3$$

Compression and Intercept Points for Characterizing Distortion in RF Circuits

The **1 dB compression point** is defined as the input power for which the fundamental output power is 1 dB below the extrapolated small-signal fundamental power



Calculation of 1-dB Compression Point

Fundamental term from power series analysis is

$$b_1 \approx a_1 V_{iA} + \frac{3}{4} a_3 V_{iA}^3$$

Fundamental power is

$$P_{fund} = 20 \log \left(a_1 V_{iA} - \frac{3}{4} |a_3| V_{iA}^3 \right)$$

Extrapolated small-signal power

$$P_{ss} = 20 \log (a_1 V_{iA})$$

1 dB compression point given by

$$P_{fund} = P_{ss} - 1 \text{ dB}$$

Input Voltage for 1-dB Compression Point

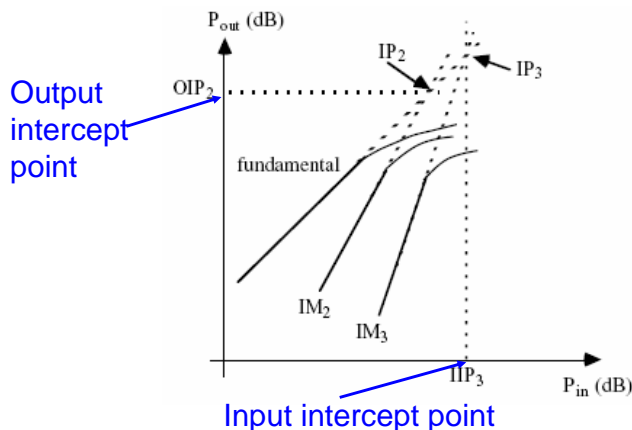
$$\begin{aligned} 20 \log \left(a_1 V_{iA} - \frac{3}{4} |a_3| V_{iA}^3 \right) &= 20 \log (a_1 V_{iA}) - 1 \text{ dB} \\ &= 20 \log \left(\frac{a_1 V_{iA}}{1.12} \right) \end{aligned}$$

Input voltage corresponding to 1 dB compression point given by

$$V_{iA} = \sqrt{0.145 \left| \frac{a_1}{a_3} \right|}$$

Intercept Points

The **intercept points (IP)** are defined as the intercept of the extrapolated small-signal power of the intermodulation terms with the fundamental



Calculation of IIP3

From definition and power series analysis

$$|a_1| V_{iA} = \frac{3}{4} |a_3| V_{iA}^3$$

or

$$V_{iA} = \sqrt{\frac{4}{3} \left| \frac{a_1}{a_3} \right|}$$

Relation between 1-dB compression and IIP3

$$\text{1 dB compression} \left\{ V_{iA} = \sqrt{0.145 \left| \frac{a_1}{a_3} \right|} \right. \quad \text{IIP3} \left\{ V_{iA} = \sqrt{\frac{4}{3} \left| \frac{a_1}{a_3} \right|} \right.$$

$$\frac{V_{iA}(1\text{dB})}{V_{iA}(\text{IIP3})} = \sqrt{\frac{0.145}{4/3}} = \sqrt{0.11} = -9.6 \text{ dB}$$

Cross Modulation (CM)

Cross modulation is due to the transfer of the modulation from an unwanted AM signal to a signal of interest due to circuit nonlinearities

$$v_i = v_1 + v_2 = V_{1A} \cos \omega_1 t + V_{2A}(1 + m \cos \omega_m t) \cos \omega_2 t$$

m < 1 is the modulation index

Due to the cubic term of the nonlinearity the ω_1 term is

$$a_1 V_{1A} \left(1 + \frac{3a_3 V_{2A}^2 m}{a_1} \cos \omega_m t \right) \cos \omega_1 t$$

CM is defined as

$$CM = \frac{3a_3 V_{2A}^2}{a_1}$$

Blocking

Consider a weak signal in the presence of a strong interferer

$$v_i = V_{1A} \cos \omega_1 t + V_{2A} \cos \omega_2 t$$

Due to the cubic term of the nonlinearity the ω_1 term is

$$\left(a_1 V_{1A} + \frac{3}{4} a_3 V_{1A}^3 + \frac{3}{2} a_3 V_{1A} V_{2A}^2 \right) \cos \omega_1 t$$

For $V_{1A} \ll V_{2A}$ $\left(a_1 + \frac{3}{2} a_3 V_{2A}^2 \right) V_{1A} \cos \omega_1 t$

- For $a_3 < 0$, gain reduces as V_2 increases and the signal is “blocked”
- **Need to withstand blockers 60-70dB larger**

Differential Error Approach

- **Useful for estimating small distortions**
 - Find small-signal gain at
 - Quiescent operating point
 - Positive peak of input
 - Negative peak of input
 - Define new parameters
 - Develop expressions for HD2 and HD3

Differential Error Distortion Analysis

Consider the power series expression

$$v_o = a_1 v_i + a_2 v_i^2 + a_3 v_i^3 + \dots$$

The small-signal gain is

$$a = \frac{dv_o}{dv_i} = a_1 + 2a_2 v_i + 3a_3 v_i^2 + \dots$$

At the quiescent operating point $v_i = 0 \Rightarrow \text{gain} = a_1$

For input $v_i = V_{iA} \cos \omega_1 t$

$$a^+ = a_1 + 2a_2 V_{iA} + 3a_3 V_{iA}^2 + \dots$$

$$a^- = a_1 + 2a_2 (-V_{iA}) + 3a_3 (-V_{iA})^2 + \dots$$

Distortion Factors

Define two new coefficients

$$E^+ = \frac{a^+ - a_1}{a_1} = \frac{2a_2V_{iA} + 3a_3V_{iA}^2 + \dots}{a_1}$$

$$E^- = \frac{a^- - a_1}{a_1} = \frac{-2a_2V_{iA} + 3a_3V_{iA}^2 + \dots}{a_1}$$

From this

$$E^+ - E^- \approx \frac{4a_2V_{iA}}{a_1} \quad \Rightarrow \quad a_2 = \frac{a_1(E^+ - E^-)}{4V_{iA}}$$

$$E^+ + E^- \approx \frac{6a_3V_{iA}^2}{a_1} \quad \Rightarrow \quad a_3 = \frac{a_1(E^+ + E^-)}{6V_{iA}^2}$$

$$HD_2 \approx \frac{1}{2} \frac{a_2}{a_1} V_{iA} \quad \Rightarrow \quad HD_2 = \frac{E^+ - E^-}{8}$$

$$HD_3 \approx \frac{1}{4} \frac{a_3}{a_1} V_{iA}^2 \quad \Rightarrow \quad HD_3 = \frac{E^+ + E^-}{24}$$

Negative Feedback - Advantages

- Stabilize gain of an amplifier against parameter changes in devices due to supply voltage variation, temperature changes, or device aging
- Modify input and output impedances to suit needs
 - e.g., voltage amplifier: large input impedance and small output impedance
- Reduce distortion in amplifiers (the input-output transfer characteristics become more linear)
 - All audio amplifiers
- Increase bandwidth of circuits
 - Widely used in broadband amplifiers

Negative Feedback - Disadvantages

- Gain is reduced in almost direct proportion to other benefits (add extra gain stages)
- Feedback causes instability and there is a tendency for oscillation
 - ⇒ An amplifier may become an oscillator!

Review of Feedback Terminology

$$\frac{S_o}{S_i} = A = \frac{a}{1 + af}$$

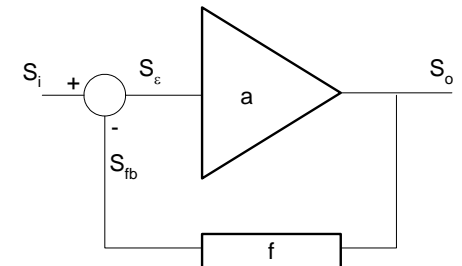
a = open-loop gain

$T = af$ = loop gain

A = closed-loop gain

$$A = \frac{a}{1 + T}$$

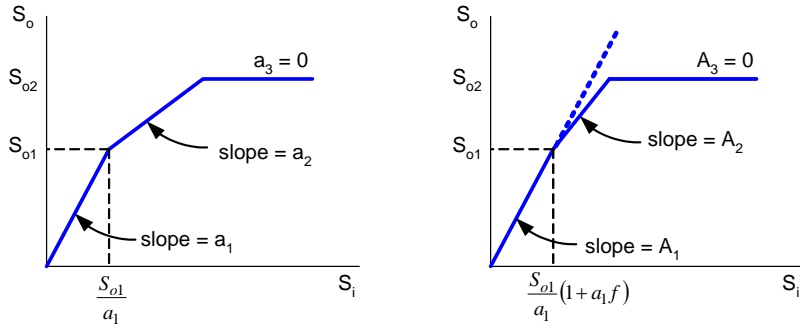
For $T \gg 1$ $A \cong \frac{1}{f}$



Effect on Distortion

Negative feedback keeps overall gain A approximately constant

⇒ it should be effective in reducing distortion, because distortion is caused by changes in 'a'

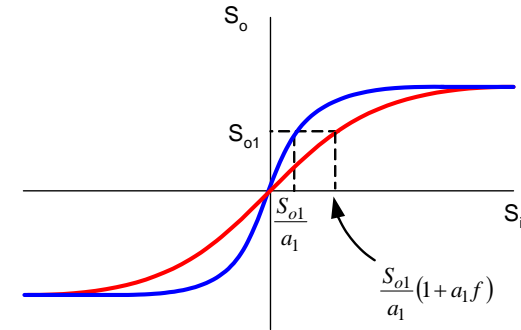


With feedback the slopes of the transfer function curves are

$$A_1 = \frac{a_1}{1 + a_1 f} = \frac{1}{f + \frac{1}{a_1}} \cong \frac{1}{f}$$

$$A_2 = \frac{a_2}{1 + a_2 f} = \frac{1}{f + \frac{1}{a_2}} \cong \frac{1}{f}$$

Effect on Distortion



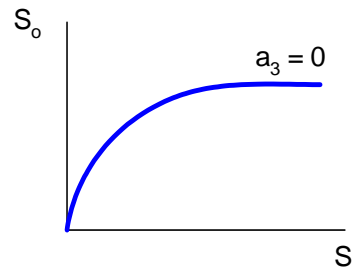
The transfer characteristic is much less nonlinear than that for the original amplifier

Negative feedback reduces the gain but improves the linearity

What About a Hard Nonlinearity?

When the output shows hard saturation then the gain is zero and negative feedback cannot improve the situation

$$A_3 = \frac{a_3}{1 + a_3 f} = \frac{0}{1} = 0$$



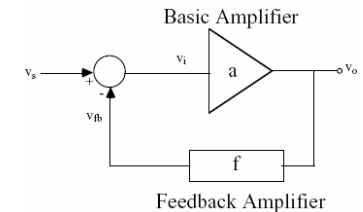
Distortion Analysis with Feedback

Consider the power series expression

$$v_o = a_1 v_i + a_2 v_i^2 + a_3 v_i^3 + \dots$$

With feedback

$$v_i = v_s - v_{fb} = v_s - f v_o$$



The output voltage with feedback is

$$v_o = a_1 (v_s - f v_o) + a_2 (v_s - f v_o)^2 + \dots$$

Therefore, the output voltage is a power series in v_s

$$v_o = a'_1 v_s + a'_2 v_s^2 + \dots$$

Power Series with Feedback

Since the power series is a Taylor's series

$$v_o = \left. \frac{dv_o}{dv_s} \right|_{0,0} v_s + \frac{1}{2} \left. \frac{d^2 v_o}{dv_s^2} \right|_{0,0} v_s^2 + \dots$$

The coefficients of the power series are evaluated using the fact that $v_s = 0 \Rightarrow v_o = 0$

$$\left. \frac{dv_o}{dv_s} \right|_{0,0} = a'_1$$

$$\left. \frac{d^2 v_o}{dv_s^2} \right|_{0,0} = 2a'_2$$

$$\left. \frac{d^3 v_o}{dv_s^3} \right|_{0,0} = 6a'_3$$

Distortion Factors with Feedback

The coefficients are

$$a'_1 = \frac{a_1}{(1 + a_1 f)} \quad \leftarrow \text{Usual small-signal case } T = af$$

$$a'_2 = \frac{a_2}{(1 + a_1 f)^3}$$

$$a'_3 = \frac{a_3(1 + a_1 f) - 2a_2^2 f}{(1 + a_1 f)^5}$$

Harmonic distortion factors are

$$HD_2 \approx \frac{1}{2} \frac{a'_2}{a'_1} V_{sA} = \frac{1}{2} \frac{a_2}{a_1} V_{sA} \frac{1}{(1 + a_1 f)^2}$$

$$\approx \frac{1}{(1 + a_1 f)^2} HD_2|_{w/o \text{ fb}}$$

$$HD_3 \approx \frac{1}{4} \frac{a'_3}{a'_1} V_{sA}^2 = \frac{1}{4} \frac{a_3}{a_1} V_{sA}^2 \frac{\left| 1 - \frac{2a_2^2 f}{a_3(1 + a_1 f)} \right|}{(1 + a_1 f)^3}$$

$$\approx \frac{\left| 1 - \frac{2a_2^2 f}{a_3(1 + a_1 f)} \right|}{(1 + a_1 f)^3} HD_3|_{w/o \text{ fb}}$$

Distortion Factors for Constant V_{oA}

Open loop

$$HD_2 \approx \frac{1}{2} \frac{a_2}{a_1^2} V_{oA}$$

$$HD_3 \approx \frac{1}{4} \frac{a_3}{a_1^3} V_{oA}^2$$

Closed loop

$$HD_2 \approx \frac{1}{2} \frac{a'_2}{a'_1} V_{oA} = \frac{1}{2} \frac{a_2}{a_1^2} V_{oA} \frac{1}{1 + a_1 f}$$

$$\approx \frac{1}{1 + a_1 f} HD_2|_{w/o \text{ fb}}$$

$$HD_3 \approx \frac{1}{4} \frac{a'_3}{a_1^3} V_{oA}^2 = \frac{1}{4} \frac{a_3}{a_1^3} V_{oA}^2 \frac{\left| 1 - \frac{2a_2^2 f}{a_3(1 + a_1 f)} \right|}{1 + a_1 f}$$

$$\approx \frac{\left| 1 - \frac{2a_2^2 f}{a_3(1 + a_1 f)} \right|}{1 + a_1 f} HD_3|_{w/o \text{ fb}}$$

Observations on HD2 and HD3

- HD2 is reduced by $(1 + a_1 f)^2$ when input voltage is held constant and is reduced by $(1 + a_1 f)$ when output voltage is kept constant
- If $a_2 = 0$, i.e., no second-order distortion then HD3 is also reduced by $(1 + a_1 f)$ for a constant output
- Cancellation of third-order distortion occurs for

$$\frac{2a_2^2 f}{a_3(1 + a_1 f)} = 1$$

– Important when IM3 needs to be reduced