

How Have You Been Able to Gain Access to GPU Power? There have been three ways: 1. Write a graphics display program (≥ 1985) 2. Write an application that looks like a graphics display program, but uses the fragment shader to do some per-node computation (≥ 2002) Write in OpenCL or CUDA, which looks like C++ (≥ 2006)

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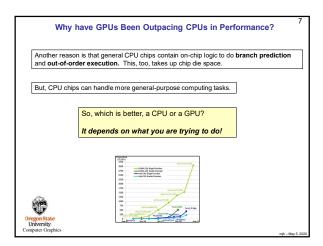
Why do we care about GPU Programming? A History of GPU vs. CPU Performance Theoretica GFLOP/s 3250 GeForceGTX 68 3000 NVIDIA GPU Single Precision
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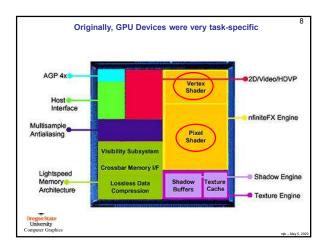
Why do we care about GPU Programming? A History of GPU vs. CPU Performance Note that the top of the graph on the previous page is here, NVIDIA

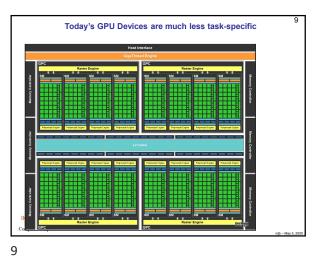


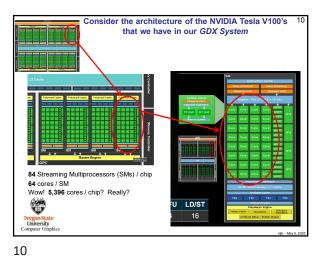
Why have GPUs Been Outpacing CPUs in Performance? Due to the nature of graphics computations, GPU chips are customized to handle **streaming data**. Another reason is that GPU chips do not need the significant amount of **cache** space that occupies much of the real estate on general-purpose CPU chips. The GPU die real estate can then be re-targeted to hold more cores and thus to produce more processing power.

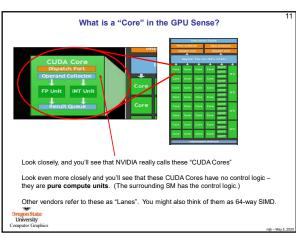
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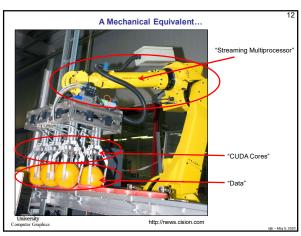




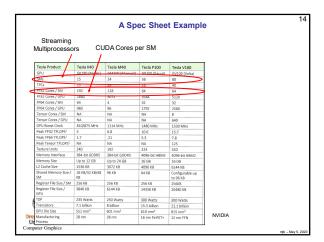












The Bottom Line is This So, the Titan Xp has 30 processors per chip, each of which is optimized to do 128-way SIMD. This is an amazing achievement in computing power. But, it is obvious that it is difficult to directly compare a CPU with a GPU. They are optimized to do different things. So, let's use the information about the architecture as a way to consider what CPUs should be good at and what GPUs should be good at <u>CPU</u> General purpose programming Data parallel programming Multi-core under user control Little user control Irregular data structures Regular data structures Irregular flow control Regular Flow Control The general term in the OpenCL world for an SM is a Compute Unit. The general term in the OpenCL world for a CUDA Core is a Processing Element. University

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Graph

A GPU Platform can have one or more Devices.

A GPU Device is organized as a grid of Compute Units.

Each Compute Unit is organized as a grid of Processing Elements.

So in NVIDIA terms, their new V100 GPU has 84 Compute Units, each of which has 64 Processing Elements, for a grand total of 5,396 Processing Elements.

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Thinking ahead to CUDA and OpenCL...

How can GPUs execute General C Code Efficiently?

• Ask them to do what they do best. Unless you have a very intense Data Parallel application, don't even think about using GPUs for computing.

• GPU programs expect you to not just have a few threads, but to have thousands of them!

• Each thread executes the same program (called the kernel), but operates on a different small piece of the overall data

• Thus, you have many, many threads, all waking up at about the same time, all executing the same kernel program, all hoping to work on a small piece of the overall problem.

• OpenCL has built-in functions so that each thread can figure out which thread number it is, and thus can figure out what part of the overall job it's supposed to do.

• When a thread gets blocked somehow (a memory access, waiting for information from another thread, etc.), the processor switches to executing another thread to work on.

Description

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So, the Trick is to Break your Problem into Many, Many Small Pieces

Particle Systems are a great example.

1. Have one thread per each particle.

2. Put all of the initial parameters into an array in GPU memory.

3. Tell each thread what the current Time is.

4. Each thread then computes its particle's position, color, etc. and writes it into arrays in GPU memory.

5. The CPU program then initiates OpenGL drawing of the information in those arrays.

Note: once setup, the data never leaves GPU memory!

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What is Fused Multiply-Add?

Many scientific and engineering computations take the form:
D = A + (B*C);

A "normal" multiply-add would likely handle this as:
tmp = B*C;
D = A + tmp;

A "fused" multiply-add does it all at once, that is, when the low-order bits of B*C are ready, they are immediately added into the low-order bits of A at the same time the higher-order bits of B*C are being multiplied.

Consider a Base 10 example: 789 + (123*456)

123

x 456
738
615
492
+ 789
Can start adding the 9 the moment the 8 is produced!
56,877

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Note: "Normal" A+(B*C) ≠ "FMA" A+(B*C)

There are Two Approaches to Combining CPU and GPU Programs

1. Combine both the CPU and GPU code in the same file. The CPU compiler compiles its part of that file.

2. Have two separate programs: a .cpp and a .somethingelse that get compiled separately.

Advantages of Each

1. The CPU and GPU sections of the code know about each others' intents. Also, they can share common structs, #define's, etc.

2. It's potentially cleaner to look at each section by itself. Also, the GPU code can be easily used in combination with other CPU programs.

Who are we Talking About Here?

1 = NVIDIA'S CUDA

2 = Khronos's OpenCL

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Looking ahead:

If threads all execute the same program, what happens on flow divergence?

If (a > b)
Do This;
else
Do That;

1. The line "if (a > b)" creates a vector of Boolean values giving the results of the if-statement for each thread. This becomes a "mask".

2. Then, the GPU executes all parts of the divergence:
Do This;
Do That;
3. During that execution, anytime a value wants to be stored, the mask is consulted and the storage only happens if that thread's location in the mask is the right value.

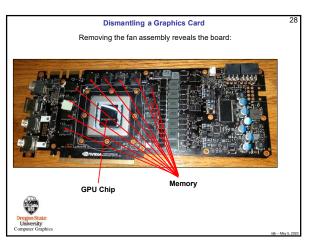
GPUs were originally designed for the streaming-ness of computer graphics
 Now, GPUs are also used for the streaming-ness of data-parallel computing
 GPUs are better for some things. CPUs are better for others.

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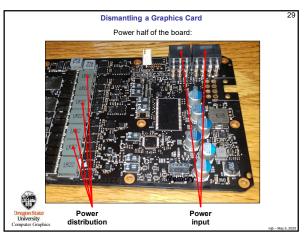


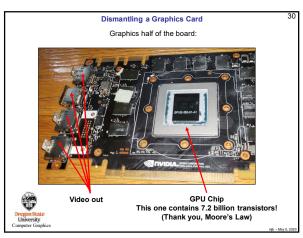






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Dismantling a Graphics Card

Underside of where the GPU chip attaches:

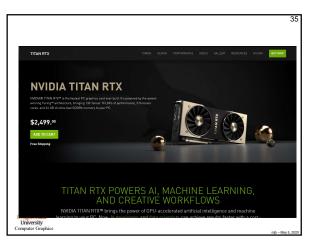
Here is a fun video of someone explaining the different parts of this same card:

https://www.youtube.com/watch?v=dSCN/9DIBGE

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GPU	Kepler GK180	Maxwell GM200	Pascal GP100	Volta GV100
Compute Capability	3.5	5.2	6.0	7.0
Threads / Warp	32	32	32	32
Max Warps / SM	64	64	64	64
Max Threads / SM	2048	2048	2048	2048
Max Thread Blocks / SM	16	32	32	32
Max 32-bit Registers / SM	65536	65536	65536	65536
Max Registers / Block	65536	32768	65536	65536
Max Registers / Thread	255	255	255	255 ¹
Max Thread Block Size	1024	1024	1024	1024
FP32 Cores / SM	192	128	64	64
Ratio of SM Registers to FP32 Cores	341	512	1024	1024
Shared Memory Size / SM	16 KB/32 KB/ 48 KB	96 KB	64 KB	Configurable up to 96 KB

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