


1




Compute Shaders



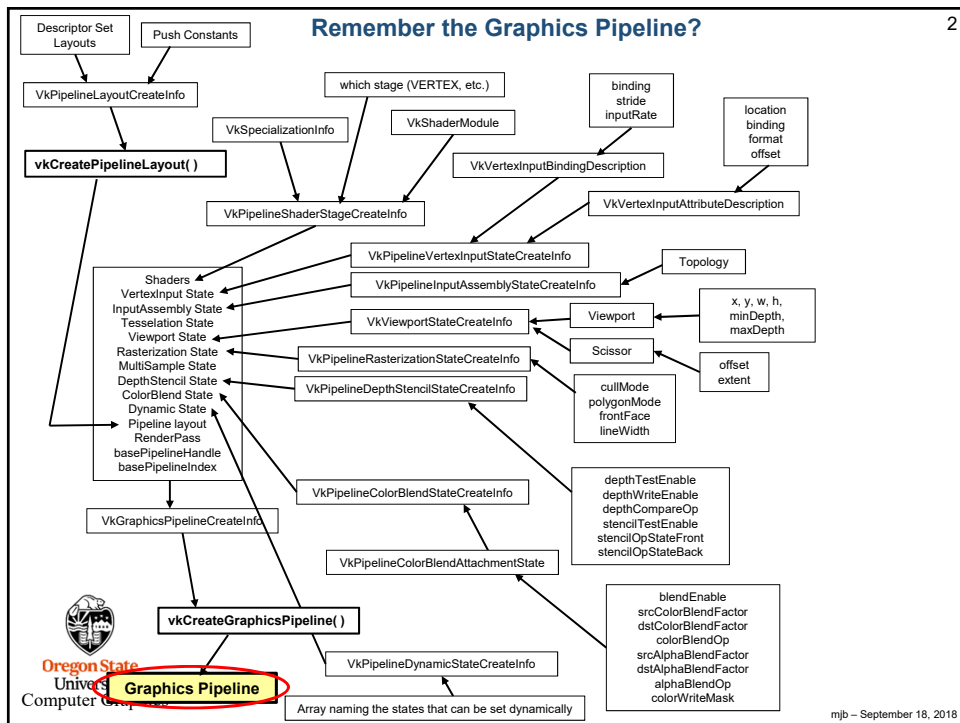
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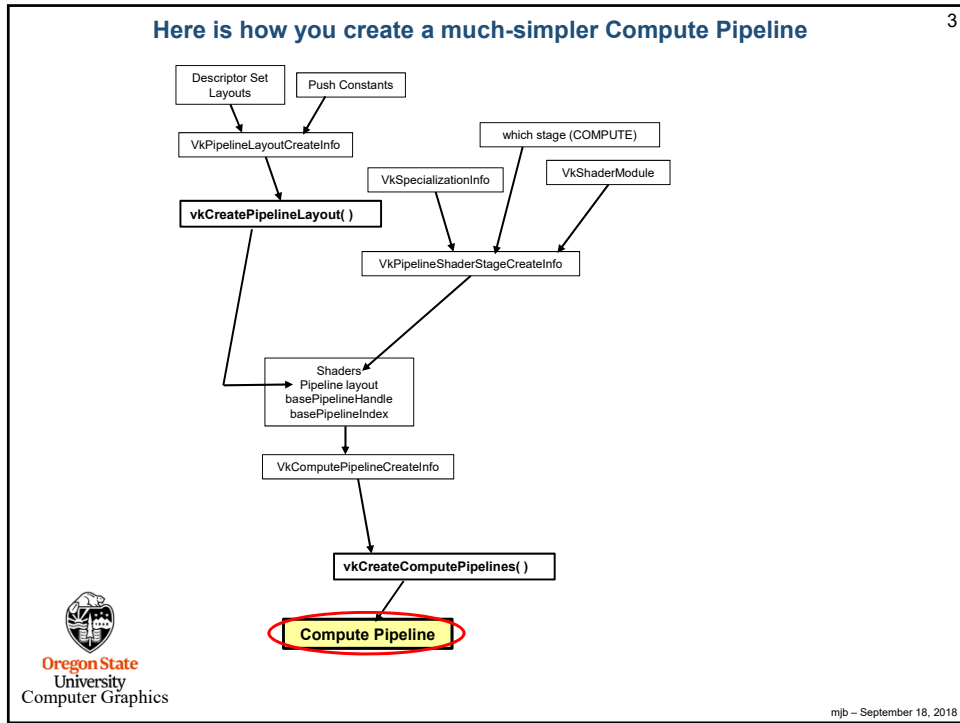


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Start with Creating the Data Buffers

4

This is a Particle System application, so we need Positions, Velocities, and (possibly) Colors

1

2

3


```

layout( std140, set = 0, binding = 0 ) buffer Pos
{
    vec4 Positions[ ]; // array of structures
};

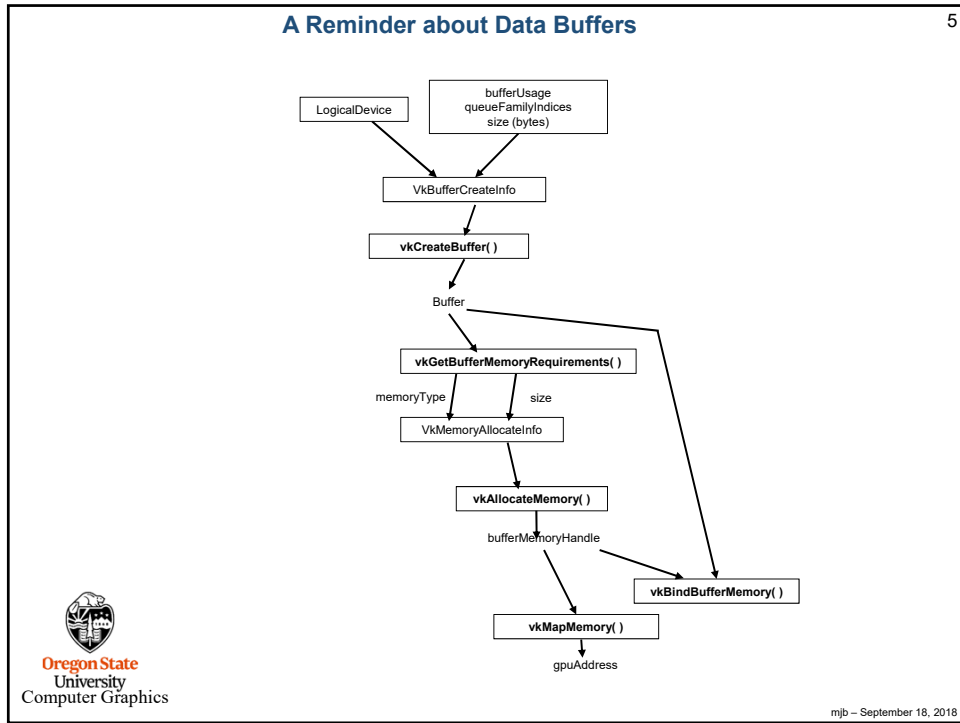
layout( std140, set = 0, binding = 1 ) buffer Vel
{
    vec4 Velocities[ ]; // array of structures
};

layout( std140, set = 0, binding = 2 ) buffer Col
{
    vec4 Colors[ ]; // array of structures
};
        
```

You can use the empty brackets, but only on the *last* element of the buffer. The actual dimension will be determined for you when OpenGL examines the size of this buffer's data store.



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Creating a Shader Storage Buffer


6

```

VkBufferCreateInfo vbci;
vbci.sType = VK_STRUCTURE_TYPE_BUFFER_CREATE_INFO;
vbci.pNext = nullptr;
vbci.flags = 0;
vbci.size = << buffer size in bytes >>;
vbci.usage = VK_USAGE_STORAGE_BUFFER_BIT;
vbci.sharingMode = VK_SHARING_MODE_EXCLUSIVE;
vbci.queueFamilyIndexCount = 0;
vbci.pQueueFamilyIndices = (const int32_t) nullptr;

VkBuffer Buffer;

result = vkCreateBuffer ( LogicalDevice, IN &vbci, PALLOCATOR, OUT &Buffer );
  
```



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Vulkan: Allocating Memory for a Buffer, Binding a Buffer to Memory, and Writing to the Buffer

7

```

VkMemoryRequirements      vmr;
result = vkGetBufferMemoryRequirements( LogicalDevice, Buffer, OUT &vmr );

VkMemoryAllocateInfo      vmai;
vmai.sType = VK_STRUCTURE_TYPE_MEMORY_ALLOCATE_INFO;
vmai.pNext = nullptr;
vmai.flags = 0;
vmai.allocationSize = vmr.size;
vmai.memoryTypeIndex = FindMemoryThatIsHostVisible( );

...

VkDeviceMemory            vdm;
result = vkAllocateMemory( LogicalDevice, IN &vmai, PALLOCATOR, OUT &vdm );

result = vkBindBufferMemory( LogicalDevice, Buffer, IN vdm, 0 );           // 0 is the offset

...

result = vkMapMemory( LogicalDevice, IN vdm, 0, VK_WHOLE_SIZE, 0, &ptr );

<< do the memory copy >>

result = vkUnmapMemory( LogicalDevice, IN vdm );

```

Fill the Data Buffer

8

```

VkResult
Fill05DataBuffer( IN MyBuffer myBuffer, IN void * data )
{
    // the size of the data had better match the size that was used to init the buffer!

    void * pGpuMemory;
    vkMapMemory( LogicalDevice, IN myBuffer.vdm, 0, VK_WHOLE_SIZE, 0, OUT &pGpuMemory );
    // 0 and 0 are offset and flags
    memcpy( pGpuMemory, data, (size_t)myBuffer.size );
    vkUnmapMemory( LogicalDevice, IN myBuffer.vdm );
    return VK_SUCCESS;
}

```

And, since we have Data Buffers, we will need Descriptor Sets to Create the Pipeline Layout

```

    graph TD
      DSL[Descriptor Set Layouts] --> VPLCI[VkPipelineLayoutCreateInfo]
      PC[Push Constants] --> VPLCI
      VPLCI --> vkCPL[ vkCreatePipelineLayout( ) ]
      VSP[ VkSpecializationInfo ]
    
```

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Create the Compute Pipeline Layout

```

VkDescriptorSetLayoutBinding    ComputeSet[1];
ComputeSet[0].binding          = 0;
ComputeSet[0].descriptorType   = VK_DESCRIPTOR_TYPE_STORAGE_BUFFER;
ComputeSet[0].descriptorCount  = 3;
ComputeSet[0].stageFlags       = VK_SHADER_STAGE_COMPUTE_BIT;
ComputeSet[0].pImmutableSamplers = (VkSampler *)nullptr;

VkDescriptorSetLayoutCreateInfo vdslc;
vdslc.sType = VK_STRUCTURE_TYPE_DESCRIPTOR_SET_LAYOUT_CREATE_INFO;
vdslc.pNext = nullptr;
vdslc.flags = 0;
vdslc.bindingCount = 1;
vdslc.pBindings = &ComputeSet[0];

result = vkCreateDescriptorSetLayout( LogicalDevice, &vdslc, PALLOCATOR, OUT &ComputeSetLayout );

VkPipelineLayoutCreateInfo vplci;
vplci.sType = VK_STRUCTURE_TYPE_PIPELINE_LAYOUT_CREATE_INFO;
vplci.pNext = nullptr;
vplci.flags = 0;
vplci.setLayoutCount = 1;
vplci.pSetLayouts = ComputeSetLayout;
vplci.pushConstantRangeCount = 0;
vplci.pPushConstantRanges = (VkPushConstantRange *)nullptr;

result = vkCreatePipelineLayout( LogicalDevice, IN &vplci, PALLOCATOR, OUT &ComputePipelineLayout );
    
```

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Create the Compute Pipeline

11

```

VkPipelineShaderStageCreateInfo      vpssci;
vpssci.sType = VK_STRUCTURE_TYPE_PIPELINE_SHADER_STAGE_CREATE_INFO;
vpssci.pNext = nullptr;
vpssci.flags = 0;
vpssci.stage = VK_SHADER_STAGE_COMPUTE_BIT;
vpssci.module = computeShader;
vpssci.pName = "main";
vpssci.pSpecializationInfo = (VkSpecializationInfo *)nullptr;

VkComputePipelineCreateInfo          vcpci[1];
vcpci[0].sType = VK_STRUCTURE_TYPE_COMPUTE_PIPELINE_CREATE_INFO;
vcpci[0].pNext = nullptr;
vcpci[0].flags = 0;
vcpci[0].stage = vpssci;
vcpci[0].layout = ComputePipelineLayout;
vcpci[0].basePipelineHandle = VK_NULL_HANDLE;
vcpci[0].basePipelineIndex = 0;

result = vkCreateComputePipelines( LogicalDevice, VK_NULL_HANDLE, 1, &vcpci[0], PALLOCATOR, &ComputePipeline );

```



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The Particle System Compute Shader -- Setup

12

```

#version 430
#extension GL_ARB_compute_shader : enable

layout( std140, set = 0, binding = 0 ) buffer Pos
{
    vec4 Positions[ ];           // array of structures
};

layout( std140, set = 0, binding = 1 ) buffer Vel
{
    vec4 Velocities[ ];         // array of structures
};

layout( std140, set = 0, binding = 2 ) buffer Col
{
    vec4 Colors[ ];             // array of structures
};

layout( local_size_x = 64, local_size_y = 1, local_size_z = 1 ) in;

```



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The Particle System Compute Shader – The Physics

13

```

#define POINT          vec3
#define VELOCITY      vec3
#define VECTOR        vec3
#define SPHERE        vec4

const VECTOR G       = VECTOR( 0., -9.8, 0. );
const float  DT      = 0.1;

const SPHERE Sphere = vec4( -100., -800., 0., 600. );    // x, y, z, r

...

uint gid = gl_GlobalInvocationID.x;    // the .y and .z are both 1 in this case

POINT  p = Positions[ gid ].xyz;
VELOCITY v = Velocities[ gid ].xyz;

POINT  pp = p + v*DT + .5*DT*DT*G;
VELOCITY vp = v + G*DT;

Positions[ gid ].xyz = pp;
Velocities[ gid ].xyz = vp;

```

$$p' = p + v \cdot t + \frac{1}{2} G \cdot t^2$$

$$v' = v + G \cdot t$$

The Particle System Compute Shader –
How About Introducing a Bounce?

14

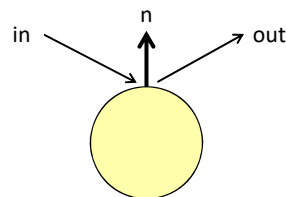
```

VELOCITY
Bounce( VELOCITY vin, VECTOR n )
{
    VELOCITY vout = reflect( vin, n );
    return vout;
}

VELOCITY
BounceSphere( POINT p, VELOCITY v, SPHERE s )
{
    VECTOR n = normalize( p - s.xyz );
    return Bounce( v, n );
}

bool
IsInsideSphere( POINT p, SPHERE s )
{
    float r = length( p - s.xyz );
    return ( r < s.w );
}

```



The Particle System Compute Shader – How About Introducing a Bounce?

15

```

uint gid = gl_GlobalInvocationID.x;           // the .y and .z are both 1 in this case

POINT   p = Positions[ gid ].xyz;
VELOCITY v = Velocities[ gid ].xyz;

POINT   pp = p + v*DT + .5*DT*DT*G;
VELOCITY vp = v + G*DT;

if( !IsInsideSphere( pp, Sphere ) )
{
    vp = BounceSphere( p, v, S );
    pp = p + vp*DT + .5*DT*DT*G;
}

Positions[ gid ].xyz = pp;
Velocities[ gid ].xyz = vp;

```

$$p' = p + v \cdot t + \frac{1}{2} G \cdot t^2$$

$$v' = v + G \cdot t$$

Graphics Trick Alert: Making the bounce happen from the surface of the sphere is time-consuming. Instead, bounce from the previous position in space. If DT is small enough (and it is), nobody will ever know...



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Dispatching the Compute Shader from the Command Buffer

16

```

const int NUM+PARTICLES = 1000000;
const int NUM_WORK_ITEMS = 64;
const int NUM_WORK_GROUPS = NUM_PARTICLES / NUM_WORK_ITEMS;

...

vkCmdBindPipeline( CommandBuffer, VK_PIPELINE_BIND_POINT_COMPUTE, ComputePipeline );
vkCmdDispatch( CommandBuffer, NUM_WORK_GROUPS, 1, 1 );

```

Or,

```

vkCmdBindPipeline( CommandBuffer, VK_PIPELINE_BIND_POINT_COMPUTE, ComputePipeline );
vkCmdDispatchIndirect( CommandBuffer, Buffer, 0 );           // offset

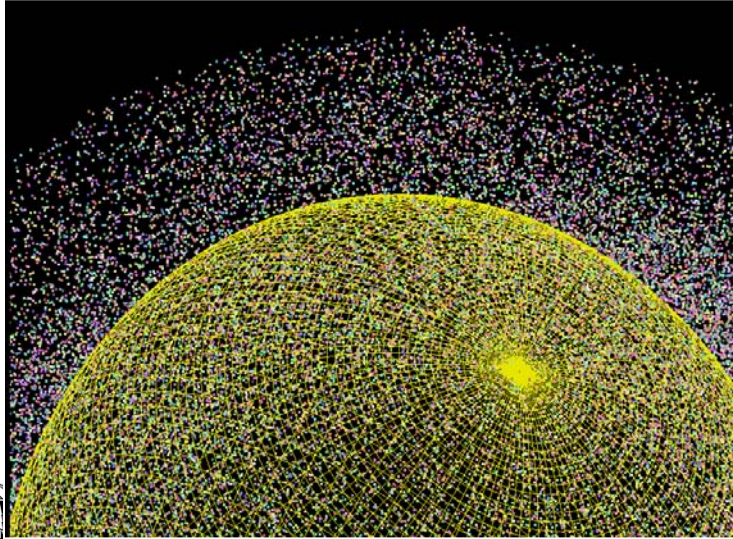
```



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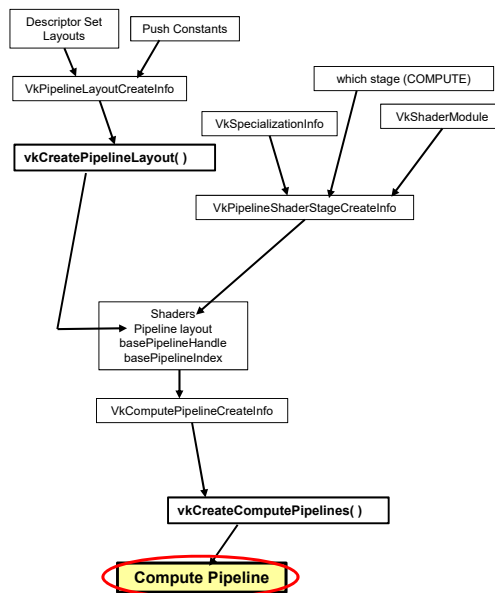
The Bouncing Particle System Compute Shader – What Does It Look Like?

17



Remember the Compute Pipeline?

18



Specialization Constants

- A Specialization Constant is a way of injecting an integer or Boolean constant into an .spv-compiled version of a shader right before the final compilation.
- That final compilation happens when you call **vkCreateComputePipelines()**
- Without Specialization Constants, you would have to commit to a final value before the SPIR-V compile was done, which could have been a long time ago

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Specialization Constants

In the compute shader

```
layout( constant_id = 0 ) const int numXworkItems = 32;
layout( local_size_x = numXworkItems, local_size_y = 1, local_size_z = 1 ) in;
```

In the C/C++ program:

```
VkSpecializationMapEntry vsme[1]; // one array element for each // Specialization Constant
    vsme.constantID = 0;
    vsme.offset = 0; // # bytes into the Specialization Constant // array this one item is
    vsme.size = sizeof(int); // size of just this Specialization Constant

int numXworkItems = 64;

VkSpecializationInfo vsi;
    vsi.mapEntryCount = 1;
    vsi.pMapEntries = &vsme[0];
    vsi.dataSize = sizeof(int); // size of all the Specialization Constants together
    vsi.pData = &numXworkItems; // array of all the Specialization Constants
```

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Linking the Specialization Constants into the Compute Pipeline

21

```

VkSpecializationMapEntry vsme[1];
    vsme.constantID = 0;
    vsme.offset = 0;
    vsme.size = sizeof(int);

int numXworkItems = 64;

VkSpecializationInfo vsi;
    vsi.mapEntryCount = 1;
    vsi.pMapEntries = &vsme[0];
    vsi.dataSize = sizeof(int);
    vsi.pData = &numXworkItems;

VkPipelineShaderStageCreateInfo vpssci;
    vpssci.sType = VK_STRUCTURE_TYPE_PIPELINE_SHADER_STAGE_CREATE_INFO;
    vpssci.pNext = nullptr;
    vpssci.flags = 0;
    vpssci.stage = VK_SHADER_STAGE_COMPUTE_BIT;
    vpssci.module = computeShader;
    vpssci.pName = "main";
    vpssci.pSpecializationInfo = &vsi;

VkComputePipelineCreateInfo vcpci[1];
    vcpci[0].sType = VK_STRUCTURE_TYPE_COMPUTE_PIPELINE_CREATE_INFO;
    vcpci[0].pNext = nullptr;
    vcpci[0].flags = 0;
    vcpci[0].stage = vpssci;
    vcpci[0].layout = ComputePipelineLayout;
    vcpci[0].basePipelineHandle = VK_NULL_HANDLE;
    vcpci[0].basePipelineIndex = 0;

result = vkCreateComputePipelines( LogicalDevice, VK_NULL_HANDLE, 1, &vcpci[0], PALLOCATOR, &ComputePipeline );

```

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