

Vulkan.
Vertex Buffers

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What is a Vertex Buffer?

Vertex Buffers are how you draw things in Vulkan. They are very much like Vertex Buffer Objects in OpenGL, but more detail is exposed to you (a lot more...).

But, the good news is that Vertex Buffers are really just ordinary Data Buffers, so some of the functions will look familiar to you.

First, a quick review of computer graphics geometry . . .

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Geometry vs. Topology

Original Object

change geometry

Geometry = changed
Topology = same (1-2-3-4-1)

Geometry:
Where things are (e.g., coordinates)

change topology

Geometry = same
Topology = changed (1-2-4-3-1)

Topology:
How things are connected

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Vulkan Topologies

```

typedef enum VkPrimitiveTopology
{
    VK_PRIMITIVE_TOPOLOGY_POINT_LIST = 0,
    VK_PRIMITIVE_TOPOLOGY_LINE_LIST = 1,
    VK_PRIMITIVE_TOPOLOGY_LINE_STRIP = 2,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST = 3,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP = 4,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_FAN = 5,
    VK_PRIMITIVE_TOPOLOGY_LINE_LIST_WITH_ADJACENCY = 6,
    VK_PRIMITIVE_TOPOLOGY_LINE_STRIP_WITH_ADJACENCY = 7,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST_WITH_ADJACENCY = 8,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP_WITH_ADJACENCY = 9,
    VK_PRIMITIVE_TOPOLOGY_PATCH_LIST = 10,
} VkPrimitiveTopology;
    
```

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Vulkan Topologies – Some OpenGL Topologies are Missing

VK_PRIMITIVE_TOPOLOGY_POINT_LIST

VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST

VK_PRIMITIVE_TOPOLOGY_LINE_LIST

VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP

VK_PRIMITIVE_TOPOLOGY_LINE_STRIP

VK_PRIMITIVE_TOPOLOGY_TRIANGLE_FAN

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OpenGL Topologies – Polygon Requirements

Polygons must be:

- Convex and
- Planar

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Vulkan Topologies – Requirements and Orientation

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Polygons must be:

- Convex and
- Planar

Polygons are traditionally:

- CCW when viewed from outside the solid object

GL_TRIANGLES

It's not absolutely necessary, but there are possible optimizations if you are **consistent**

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OpenGL Topologies – Vertex Order Matters

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VK_LINE_STRIP

VK_LINE_STRIP

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What does “Convex Polygon” Mean?

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We can go all mathematical here, but let's go visual instead. In a convex polygon, a line between **any** two points inside the polygon never leaves the inside of the polygon.

Convex

Not Convex

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Why is there a Requirement for Polygons to be Convex?

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Graphics polygon-filling hardware can be highly optimized if you know that, no matter what direction you fill the polygon in, there will be two and only two intersections between the scanline and the polygon's edges.

Convex

Not Convex

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What if you need to display Polygons that are not Convex?

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There is an open source library to break a non-convex polygon into convex polygons. It is called **Polypartition**, and is found here:

<https://github.com/ivanfratric/polypartition>

If you ever need to do this, contact me. I have working code ...

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Why is there a Requirement for Polygons to be Planar?

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Graphics hardware assumes that a polygon has a definite front and a definite back, and that you can only see one of them at a time

OK

Not OK

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Vertex Orientation Issues

Thanks to OpenGL, we are all used to drawing in a right-handed coordinate system.

Internally, however, the Vulkan pipeline uses a left-handed system:

The best way to handle this is to continue to draw in a RH coordinate system and then fix it up in the projection matrix, like this:
`ProjectionMatrix[1][1] *= -1;`
 This is like saying "Y = -Y".

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A Colored Cube Example

```
static GLfloat CubeColors[ ][3] =
{
    { 0.0, 0.0, 0.0 },
    { 1.0, 0.0, 0.0 },
    { 0.0, 1.0, 0.0 },
    { 1.0, 1.0, 0.0 },
    { 0.0, 0.0, 1.0 },
    { 1.0, 0.0, 1.0 },
    { 0.0, 1.0, 1.0 },
    { 1.0, 1.0, 1.0 },
};

static GLuint CubeTriangleIndices[ ][3] =
{
    { 0, 2, 3 },
    { 0, 3, 1 },
    { 4, 5, 7 },
    { 4, 7, 6 },
    { 1, 3, 7 },
    { 1, 7, 5 },
    { 0, 4, 6 },
    { 0, 6, 2 },
    { 2, 6, 7 },
    { 2, 7, 3 },
    { 0, 1, 5 },
    { 0, 5, 4 },
};
```

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Triangles in an Array of Structures

```
From the file Sample/VertexData.cpp:
struct vertex
{
    glm::vec3 position;
    glm::vec3 normal;
    glm::vec3 color;
    glm::vec2 texCoord;
};

struct vertex VertexData[ ] =
{
    // triangle 0-2-3:
    // vertex #0:
    { -1.0, -1.0, -1.0 },
    { 0.0, 0.0, -1.0 },
    { 0.0, 0.0, 0.0 },
    { 1.0, 0.0 },
    // vertex #2:
    { -1.0, -1.0, -1.0 },
    { 0.0, 0.0, -1.0 },
    { 0.0, 1.0, 0.0 },
    { 1.0, 1.0 },
    // vertex #3:
    { 1.0, -1.0, -1.0 },
    { 0.0, 0.0, -1.0 },
    { 1.0, 1.0, 0.0 },
    { 0.0, 1.0 },
};
```

Modeled in right-handed coordinates

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Vertex Orientation Issues

This object was modeled such that triangles that face the viewer will look like their vertices are oriented CCW (this is detected by looking at vertex orientation at the start of the rasterization).

Because this 3D object is closed, Vulkan can save rendering time by not even bothering with triangles whose vertices look like they are oriented CW. This is called **backface culling**.

Vulkan's change in coordinate systems can mess up the backface culling. So I recommend, at least at first, that you do no culling.

```
VkPipelineRasterizationStateCreateInfo vprsci;
...
vprsci.cullMode = VK_CULL_MODE_NONE
vprsci.frontFace = VK_FRONT_FACE_COUNTER_CLOCKWISE;
```

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Filling the Vertex Buffer

```
MyBuffer MyVertexBuffer;

Init05MyVertexBuffer( sizeof(VertexData), &MyVertexBuffer );
Fill05DataBuffer( MyVertexBuffer, (void *)VertexData );

VkResult
Init05MyVertexBuffer( IN VkDeviceSize size, OUT MyBuffer * pMyBuffer )
{
    VkResult result = Init05DataBuffer( size, VK_BUFFER_USAGE_VERTEX_BUFFER_BIT, pMyBuffer );
    return result;
}
```

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What Init05DataBuffer Does

```
VkResult
Init05DataBuffer( VkDeviceSize size, VkBufferUsageFlags usage, OUT MyBuffer * pMyBuffer )
{
    VkResult result = VK_SUCCESS;
    VkBufferCreateInfo vbci;
    vbci.sType = VK_STRUCTURE_TYPE_BUFFER_CREATE_INFO;
    vbci.pNext = nullptr;
    vbci.flags = 0;
    vbci.size = pMyBuffer->size - size;
    vbci.usage = usage;
    vbci.sharingMode = VK_SHARING_MODE_EXCLUSIVE;
    vbci.queueFamilyIndexCount = 0;
    vbci.pQueueFamilyIndices = (const uint32_t *)nullptr;
    result = vkCreateBuffer( LogicalDevice, IN &vbci, PALLOCATOR, OUT &pMyBuffer->buffer );

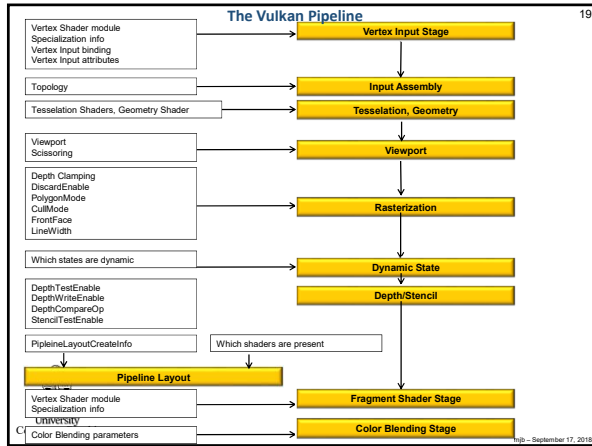
    VkMemoryRequirements vmr;
    vkGetBufferMemoryRequirements( LogicalDevice, IN pMyBuffer->buffer, OUT &vmr ); // fills vmr

    VkMemoryAllocateInfo vmai;
    vmai.sType = VK_STRUCTURE_TYPE_MEMORY_ALLOCATE_INFO;
    vmai.pNext = nullptr;
    vmai.allocationSize = vmr.size;
    vmai.memoryTypeIndex = FindMemoryThatIsHostVisible();

    VkDeviceMemory vdm;
    result = vkAllocateMemory( LogicalDevice, IN &vmai, PALLOCATOR, OUT &vdm );
    pMyBuffer->vdm = vdm;

    result = vkBindBufferMemory( LogicalDevice, pMyBuffer->buffer, IN vdm, 0 ); // 0 is the offset
    return result;
}
```

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Telling the Pipeline about its Input

We will come to the Pipeline later, but for now, know that a Vulkan pipeline is essentially a very large data structure that holds (what OpenGL would call) the **state**, including how to parse its input.

C/C++

```
struct vertex
{
    glm::vec3 position;
    glm::vec3 normal;
    glm::vec3 color;
    glm::vec2 texCoord;
};
```

→

GLSL

```
layout( location = 0 ) in vec3 aVertex;
layout( location = 1 ) in vec3 aNormal;
layout( location = 2 ) in vec3 aColor;
layout( location = 3 ) in vec2 aTexCoord;
```

vviad

```
VkVertexInputBindingDescription vviad[1]; // one of these per buffer data buffer
vviad[0].binding = 0; // which binding # this is
vviad[0].stride = sizeof( struct vertex ); // bytes between successive structs
vviad[0].inputRate = VK_VERTEX_INPUT_RATE_VERTEX;
```

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Telling the Pipeline about its Input

C/C++

```
struct vertex
{
    glm::vec3 position;
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    glm::vec3 color;
    glm::vec2 texCoord;
};
```

→

GLSL

```
layout( location = 0 ) in vec3 aVertex;
layout( location = 1 ) in vec3 aNormal;
layout( location = 2 ) in vec3 aColor;
layout( location = 3 ) in vec2 aTexCoord;
```

```
VkVertexInputAttributeDescription vviad[4]; // array per vertex input attribute
// 4 = vertex, normal, color, textureCoord
vviad[0].location = 0; // location in the layout decoration
vviad[0].binding = 0; // which binding description this is part of
vviad[0].format = VK_FORMAT_VEC3; // x, y, z
vviad[0].offset = offsetof( struct vertex, position ); // 0

vviad[1].location = 1;
vviad[1].binding = 0;
vviad[1].format = VK_FORMAT_VEC3; // nx, ny, nz
vviad[1].offset = offsetof( struct vertex, normal ); // 12

vviad[2].location = 2;
vviad[2].binding = 0;
vviad[2].format = VK_FORMAT_VEC3; // r, g, b
vviad[2].offset = offsetof( struct vertex, color ); // 24

vviad[3].location = 3;
vviad[3].binding = 0;
vviad[3].format = VK_FORMAT_VEC2; // s, t
vviad[3].offset = offsetof( struct vertex, texCoord ); // 36
```

vviad has 4 elements because we have 4 per-vertex pipeline inputs

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Telling the Pipeline about its Input

We will come to the Pipeline later, but for now, know that a Vulkan Pipeline is essentially a very large data structure that holds (what OpenGL would call) the **state**, including how to parse its input.

```
VkPipelineVertexInputStateCreateInfo vpvisci; // used to describe the input vertex attributes
vpvisci.sType = VK_STRUCTURE_TYPE_PIPELINE_VERTEX_INPUT_STATE_CREATE_INFO;
vpvisci.pNext = nullptr;
vpvisci.flags = 0;
vpvisci.vertexBindingDescriptionCount = 1;
vpvisci.vertexBindingDescriptions = vviad;
vpvisci.vertexAttributeDescriptionCount = 4;
vpvisci.pVertexAttributeDescriptions = vviad;
```

```
VkPipelineInputAssemblyStateCreateInfo vpiasci;
vpiasci.sType = VK_STRUCTURE_TYPE_PIPELINE_INPUT_ASSEMBLY_STATE_CREATE_INFO;
vpiasci.pNext = nullptr;
vpiasci.flags = 0;
vpiasci.topology = VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST;;
```

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Telling the Pipeline about its Input

We will come to the Pipeline later, but for now, know that a Vulkan Pipeline is essentially a very large data structure that holds (what OpenGL would call) the **state**, including how to parse its input.

```
VkGraphicsPipelineCreateInfo vgpcci;
vgpcci.sType = VK_STRUCTURE_TYPE_GRAPHICS_PIPELINE_CREATE_INFO;
vgpcci.pNext = nullptr;
vgpcci.flags = 0;
vgpcci.stageCount = 2; // number of shader stages in this pipeline
vgpcci.pStages = vpsasci;
vgpcci.pVertexInputState = &vpvisci;
vgpcci.pInputAssemblyState = &vpiasci;
vgpcci.pTessellationState = (VkPipelineTessellationStateCreateInfo*) nullptr; // &vptsci
vgpcci.pViewportState = &vpvsci;
vgpcci.pRasterizationState = &vprasci;
vgpcci.pMultisampleState = &vpmsci;
vgpcci.pDepthStencilState = &vpdscsi;
vgpcci.pColorBlendState = &vpbcsci;
vgpcci.pDynamicState = &vpdsci;
vgpcci.layout = IN GraphicsPipelineLayout;
vgpcci.renderPass = IN RenderPass;
vgpcci.subpass = 0; // subpass number
vgpcci.basePipelineHandle = (VkPipeline) VK_NULL_HANDLE;
vgpcci.basePipelineIndex = 0;
```

```
result = vkCreateGraphicsPipelines( LogicalDevice, VK_NULL_HANDLE, 1, IN &vgpcci,
                                  PALLOCATOR, OUT pGraphicsPipeline );
```

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Telling the Command Buffer what Vertices to Draw

We will come to Command Buffers later, but for now, know that you will specify the vertex buffer that you want drawn.

```
VkBuffer buffers[1] = MyVertexDataBuffer.buffer;
vkCmdBindVertexBuffers( CommandBuffers[nextImageIndex], 0, 1, buffers, offsets );
```

```
const uint32_t vertexCount = sizeof(VertexData) / sizeof(VertexData[0]);
const uint32_t instanceCount = 1;
const uint32_t firstVertex = 0;
const uint32_t firstInstance = 0;
```

```
vkCmdDraw( CommandBuffers[nextImageIndex], vertexCount, instanceCount, firstVertex, firstInstance );
```

Better to do this than to hard-code a number

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