

ECE 468 / CS 519: Digital Image Processing

Spatial Sharpening

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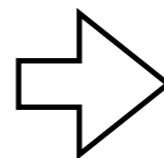
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Outline

- MATLAB
- Sharpening spatial filters (Textbook: 3.5)

Image Sharpening



Second Derivative



Original signal

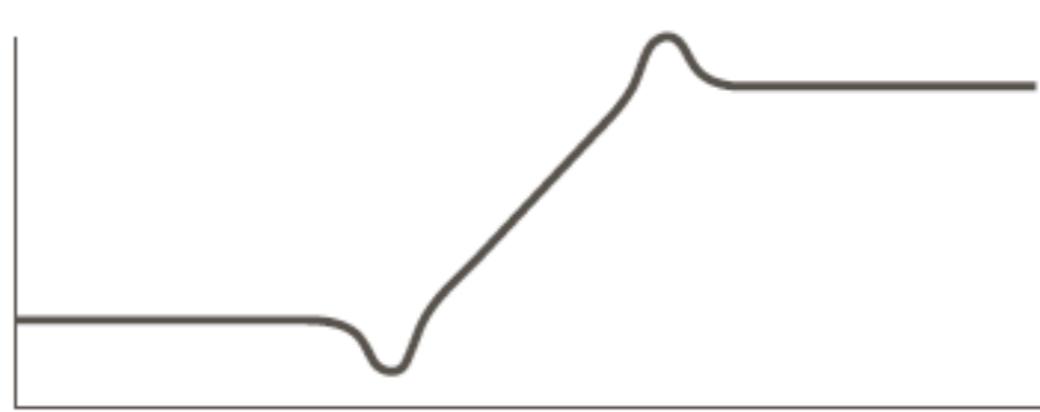


2nd derivative

Second Derivative



Original signal



Original signal - 2nd derivative

Image Derivatives

$$\frac{\partial f(x, y)}{\partial x} \approx f(x + 1, y) - f(x, y)$$

$$\frac{\partial f(x, y)}{\partial y} \approx f(x, y + 1) - f(x, y)$$

Image Derivatives

Image Derivatives

$$\frac{\partial^2 f(x, y)}{\partial^2 x} \approx f(x + 1, y) + f(x - 1, y) - 2f(x, y)$$

$$\frac{\partial^2 f(x, y)}{\partial^2 y} \approx f(x, y + 1) + f(x, y - 1) - 2f(x, y)$$

Laplacian

$$\nabla^2 f(x, y) = \frac{\partial^2 f(x, y)}{\partial^2 x} + \frac{\partial^2 f(x, y)}{\partial^2 y}$$

$$\begin{aligned}\nabla^2 f(x, y) &\approx f(x+1, y) + f(x-1, y) \\ &\quad + f(x, y+1) + f(x, y-1) \\ &\quad - 4f(x, y)\end{aligned}$$

0	1	0
1	-4	1
0	1	0

Sharpening Spatial Filters

Variants of the Laplacian filter

0	1	0
1	-4	1
0	1	0

1	1	1
1	-8	1
1	1	1

0	-1	0
-1	4	-1
0	-1	0

-1	-1	-1
-1	8	-1
-1	-1	-1

Image Sharpening

$$g(x, y) = f(x, y) \pm c \cdot \nabla^2 f(x, y)$$

- Blur the original image
- **Subtract** the Laplacian

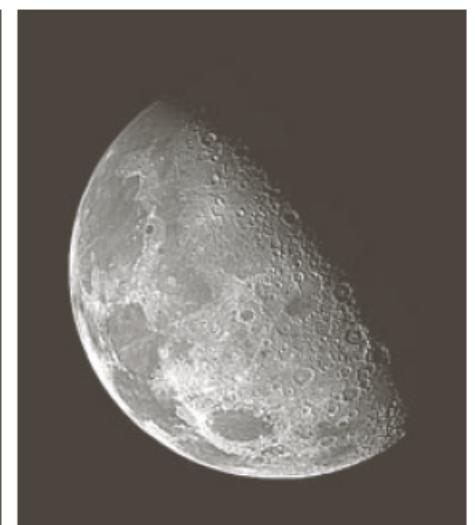
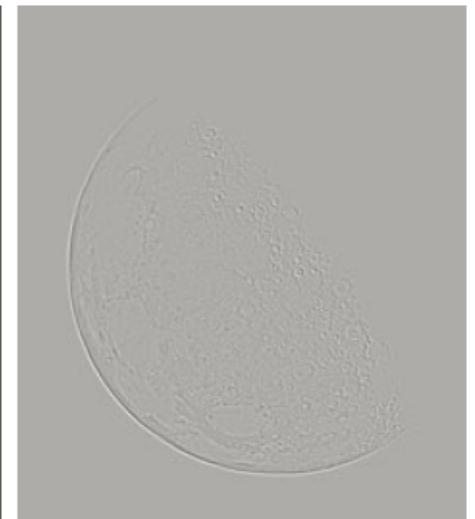
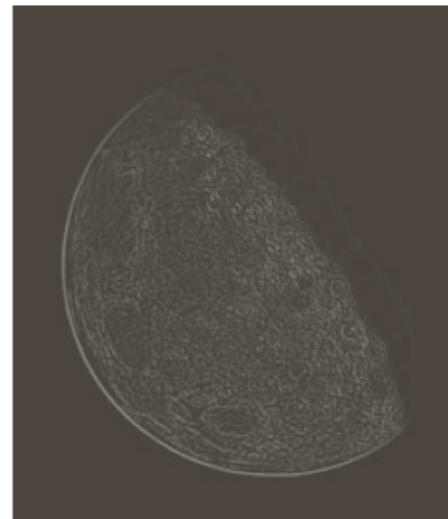


Image Sharpening

$$g(x, y) = f(x, y) \pm c \cdot \nabla^2 f(x, y)$$

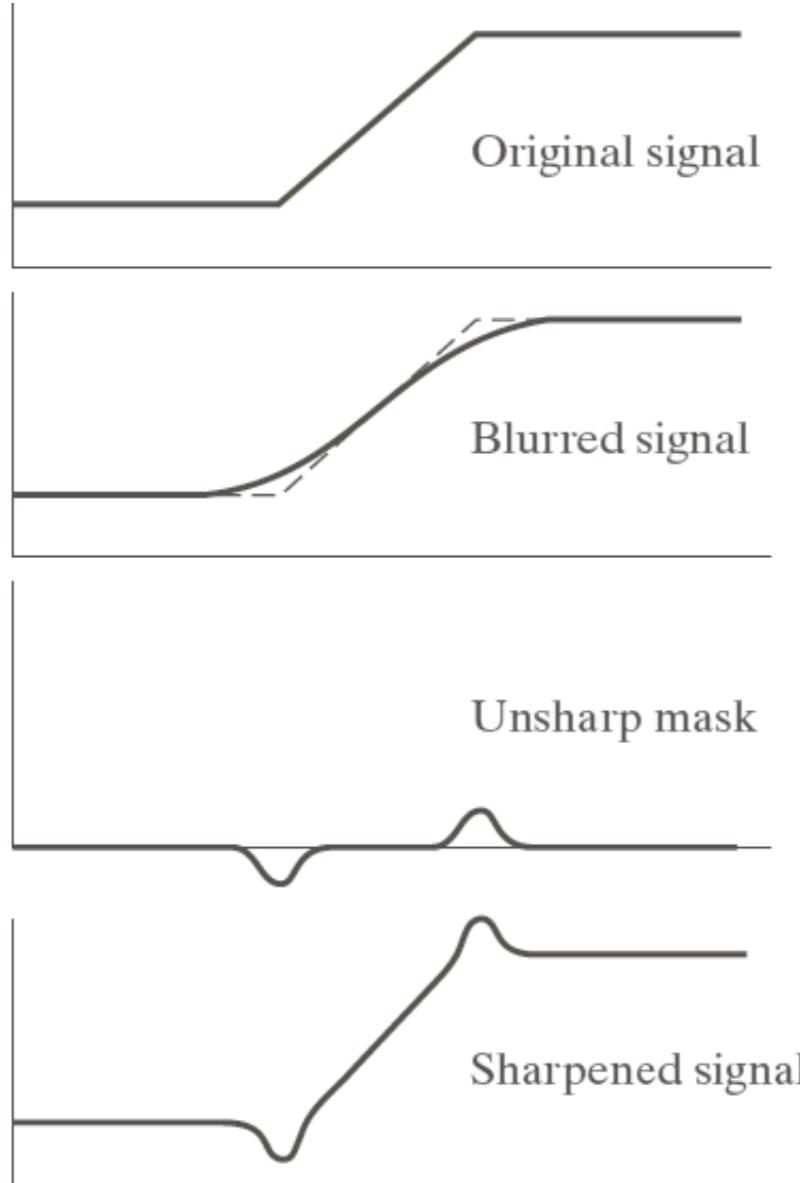
use $c = -1$ for

0	1	0	1	1	1
1	-4	1	1	-8	1
0	1	0	1	1	1

use $c = +1$ for

0	-1	0	-1	-1	-1
-1	4	-1	-1	8	-1
0	-1	0	-1	-1	-1

Unsharp Masking



- Blur the original image
- Subtract the blurred image from the original
- Add the resulting mask to the original

$$g(x, y) = f(x, y) + k(f(x, y) - \overline{f(x, y)})$$

$k = 1$ unsharp masking

$k > 1$ highboost filtering

Unsharp Masking



input



blurred



input - blurred



input + (input - blurred)



input + 4.5 (input - blurred)

MATLAB

MATLAB

- `g = imfilter(f, w, 'corr', 'replicate')`

MATLAB

- `g = imfilter(f, w, 'corr', 'replicate')`
- `f = padarray(f, [delta_row delta_col], 'replicate', 'post')`

MATLAB

- `g = imfilter(f, w, 'corr', 'replicate')`
- `f = padarray(f, [delta_row delta_col], 'replicate', 'post')`
- `w = fspecial('type', parameters)`

MATLAB

- `g = imfilter(f, w, 'corr', 'replicate')`
- `f = padarray(f, [delta_row delta_col], 'replicate', 'post')`
- `w = fspecial('type', parameters)`
 - `fspecial('gaussian', [r c], sigma)`