SECTION 2: ENERGY STORAGE FUNDAMENTALS

ESE 471 – Energy Storage Systems



Energy Storage Performance Characteristics

- Defining performance characteristics of energy storage mechanisms
 - Capacity
 - **D** Power
 - Efficiency

Capacity

Capacity

The amount of energy that a device can store

Total energy capacity, E_t

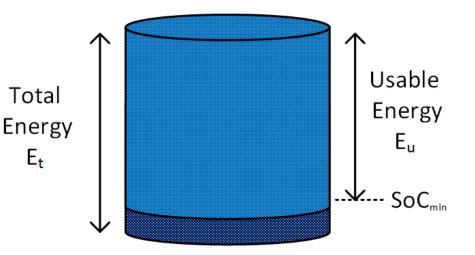
Total energy stored in a device when fully charged

Usable energy capacity, E_u

The total energy that can be extracted from a device for use

- Difference between stored energy at maximum state of charge (SoC) and minimum SoC
- In general, storage devices are not fully discharged, so typically

$$E_u < E_t$$



Capacity

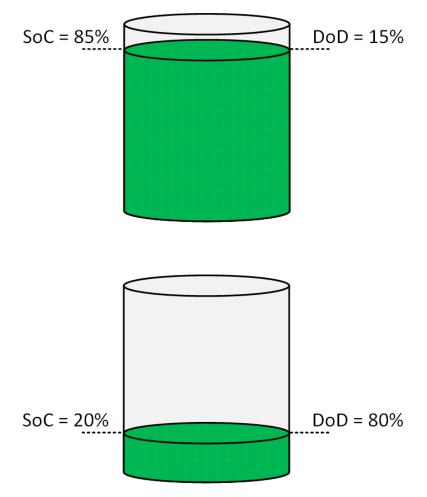
- Units of capacity:
 - Watt-hours (Wh)
 - (Ampere-hours, Ah, for batteries)

State of charge (SoC)

- The amount of energy stored in a device as a percentage of its total energy capacity
 - Fully discharged: SoC = 0%
 - Fully charged: SoC = 100%

Depth of discharge (DoD)

The amount of energy that has been removed from a device as a percentage of the total energy capacity



Capacity

 We can also characterize storage devices in terms of size or mass required for a given capacity

Specific energy

Usable energy capacity per unit mass

Units: Wh/kg

$$e_m = \frac{E_u}{m}$$

Energy density

Usable energy capacity per unit *volume*

■ Units: Wh/m³ or Wh/L

$$e_v = \frac{E_u}{V}$$

□ These are very often used (incorrectly) interchangeably

Power

- **Power** is an important metric for a storage system
 - Rate at which energy can be stored or extracted for use
 - Charge/discharge rate
 - Limited by loss mechanisms

Specific power

Power available from a storage device per unit mass
 Units: W/kg

$$p_m = \frac{P}{m}$$

Power density

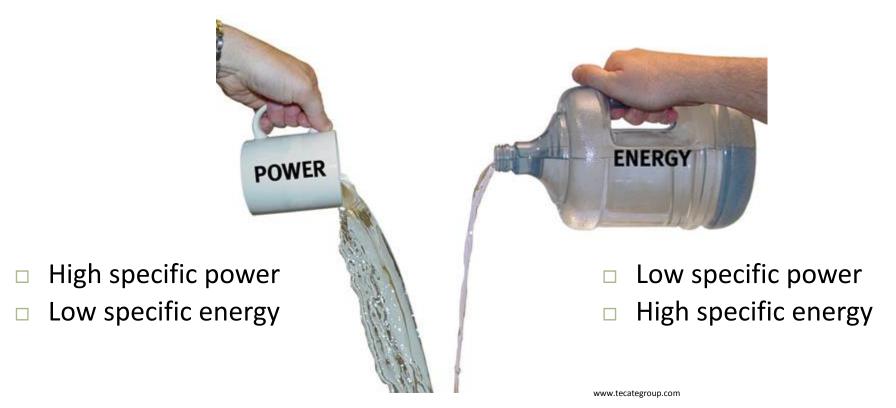
Power available from a storage device per unit volume
 Units: W/m³ or W/L

$$p_v = \frac{P}{V}$$

Power vs. Energy

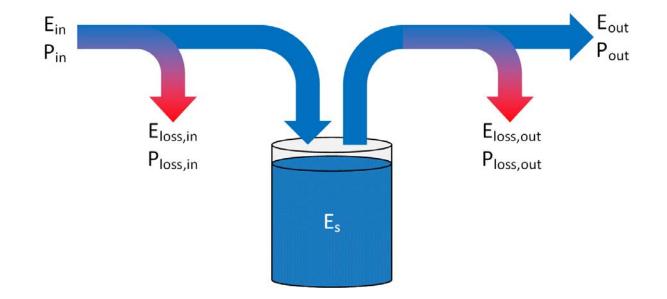
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- Capacity and the rate at which energy can be stored or extracted are different characteristics

Applications determine which is most important

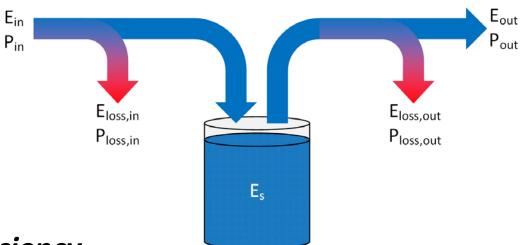


Efficiency

- Another important performance characteristic is efficiency
 - The percentage of energy put into storage that can later be extracted for use
- All storage systems suffer from losses
 - Losses as energy flows into storage
 - Losses as energy is extracted from storage



Round-Trip Efficiency



Round-trip efficiency

Energy extracted from a storage system as a percentage of the energy put into the system

$$\eta_{rt} = \frac{E_{out}}{E_{in}}$$

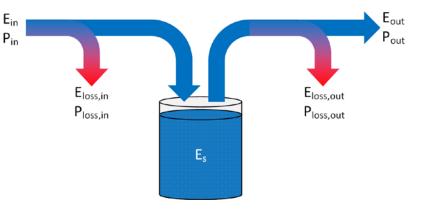
$$\eta_{rt} = \frac{E_{in} - E_{loss,in} - E_{loss,out}}{E_{in}}$$

Round-Trip Efficiency

We can define a *charging efficiency*

Amount of energy stored as a percentage of the energy input

$$\eta_{in} = \frac{E_s}{E_{in}} = \frac{E_{in} - E_{loss,in}}{E_{in}}$$



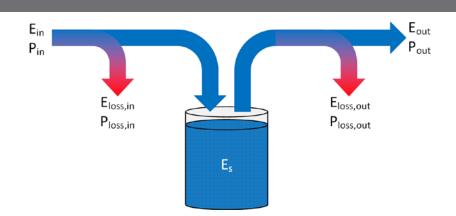
And a *discharging efficiency*

Amount of energy output as a percentage of the energy stored

$$\eta_{out} = \frac{E_{out}}{E_s} = \frac{E_s - E_{loss,out}}{E_s}$$
$$\eta_{out} = \frac{E_{in} - E_{loss,in} - E_{loss,out}}{E_{in} - E_{loss,in}}$$

Round-Trip Efficiency





The round trip for energy in a storage system is a cascade of the *charge* and *discharge* processes

• Round trip efficiency given by:

 $\eta_{rt} = \eta_{in} \cdot \eta_{out}$

- □ In general, efficiency is a function of:
 - Charging/discharging power, P_{in} and P_{out}
 - State of charge

Charging Time

 Typically, what is needed is a certain power for a certain time

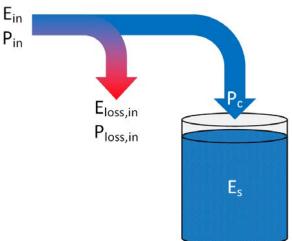
Charging time

- The time it takes to go from minimum SoC to maximum SoC at a given power input
- The time it takes to store the usable energy, E_u

$$t_c = \frac{E_u}{P_c}$$

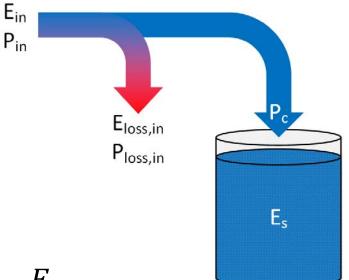
where P_c is the rate of energy storage

 Note that, due to losses, the rate of energy storage, P_c, is less than the input power, P_{in}



Charging Time

- The power we have direct control over is the input power, P_{in}
 - The charging time in terms of input power is



$$t_c = \frac{E_u}{P_{in} - P_{loss,in}} = \frac{E_u}{P_{in} \cdot \eta_{in}}$$

Discharge Time

Discharge time

- The time required to go from maximum SoC to minimum SoC at a given output power
- Due to losses, the rate of discharge, P_d, is greater than the output power, P_{out}

$$t_d = \frac{E_u}{P_d}$$

Again, the power of interest is the power we have direct control over, the output power, P_{out}, so

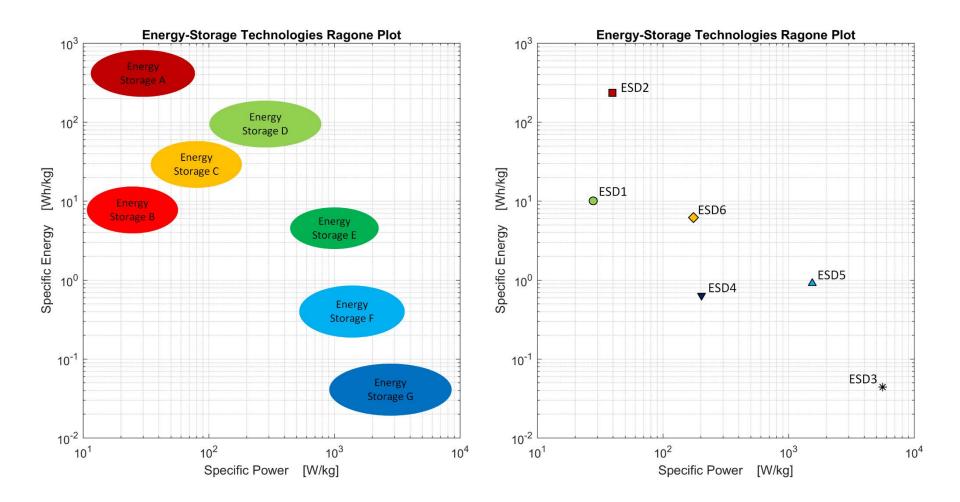
$$t_{d} = \frac{E_{u}}{P_{out} + P_{loss,out}} = \frac{E_{u}}{P_{out}/\eta_{out}} = \frac{E_{u}}{P_{out}} \cdot \eta_{out}$$

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Ragone Plots

- Two primary figures of merit for energy storage systems:
 - Specific energy
 - Specific power
- Often a tradeoff between the two
 - Different storage technologies best suited to different applications depending on power/energy requirements
- Storage technologies can be compared graphically on a *Ragone plot*
 - **D** Specific energy vs. specific power
 - Specific storage devices plotted as points on the plot, or
 - Categories of devices plotted as regions in the Ragone plane

Ragone Plots



Discharge Time

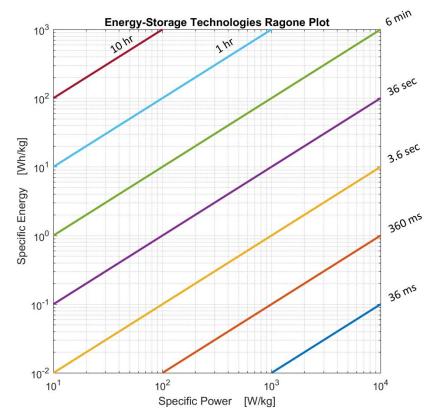
Any given storage system will have a specific energy capacity and a specific power rating

\square A point in the Ragone plane, (p_m, e_m)

 Discharge time at rated power for that point (neglecting losses):

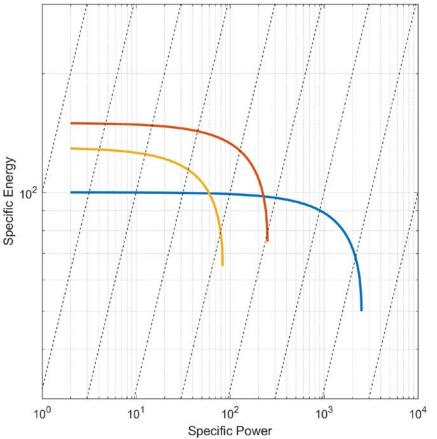
$$t_d = \frac{e_m}{p_m}$$

- Constant discharge time maps to lines with unity slope on a Ragone plot
- Storage systems that lie on the same line have equal discharge times at rated power



Ragone Curves

- Ragone plots we've seen so far plot a storage device at one operating point
 Maximum or rated power
- Can also depict a device's energy capacity over a range of power
 A Ragone curve
- Most curves share a similar characteristic shape
 - Available energy decreases at higher power
 - Fraction of energy lost as heat increases

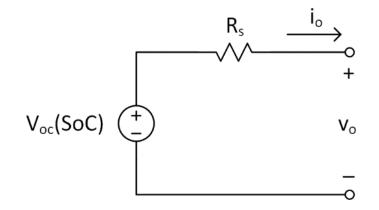


Thévenin Equivalent Model

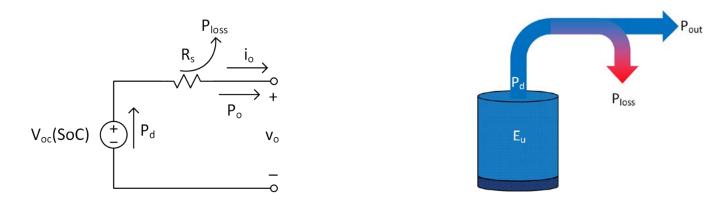
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- What is the reason for the characteristic shape of Ragone curves?
- Consider that we could model a storage device with as an electrical *Thévenin equivalent*

Need not be an electrical storage device

- Open-circuit voltage is some function of SoC
 - Possibly linear
 - May be highly nonlinear
 - Or, could be constant



Thévenin Equivalent Model



Three power components associated with discharge

D P_d : discharge power

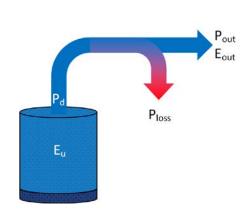
• The rate at which energy leaves storage: $P_d = V_{oc}i_o$

■ *P*_{loss}: power lost during discharge

- Modeled as heat dissipation in the Thévenin resistance: $P_{loss} = i_o^2 R_s$
- *P*_{out}: output power flowing to the external system

$$P_{out} = v_o i_o = (V_{oc} - i_o R_s) i_o$$
$$P_{out} = V_{oc} i_o - i_o^2 R_s = P_d - P_{loss}$$

Thévenin Equivalent Model

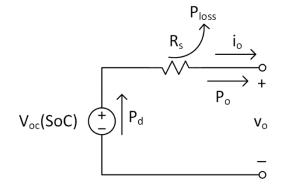


Discharge time:

$$t_d = \frac{E_u}{P_d}$$

Amount of energy extracted from the storage system:

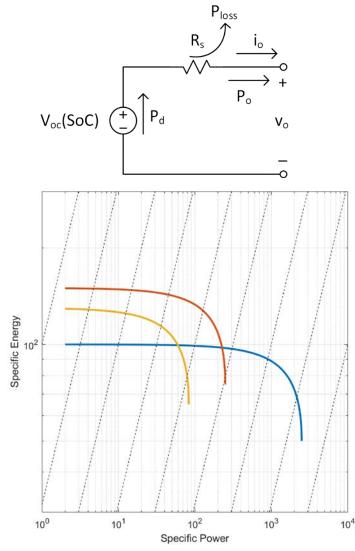
$$E_{out} = P_{out} \cdot t_d = E_u \frac{P_{out}}{P_d}$$



Substituting in expressions for P_{out} and P_d , we have

$$E_{out} = E_u \left[\frac{V_{oc} i_o - i_o^2 R_s}{V_{oc} i_o} \right]$$
$$E_{out} = E_u \left[1 - i_o \frac{R_s}{V_{oc}} \right]$$

Available Energy vs. Output Power



$$E_{out} = E_u \left[1 - i_o \frac{R_s}{V_{oc}} \right]$$

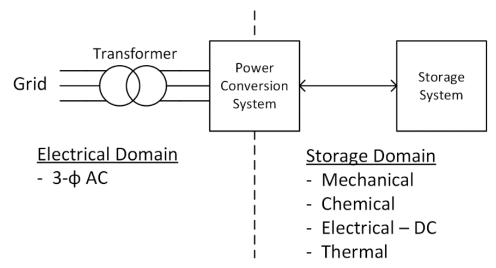
- We can see that the available energy decreases as i_o increases
 Available energy decreases as output power increases
 Illustrated by the characteristic shape of
 - Ragone plots

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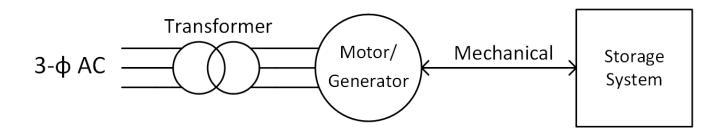
Storage System Configurations

- Our focus is grid-connected energy storage
 - Energy stored in many different domains
 - Input and output energy is electrical
 - Three-phase AC power
- Conversion is required between the storage domain and the electrical domain
 - Transformer
 - Power conversion system (PCS)

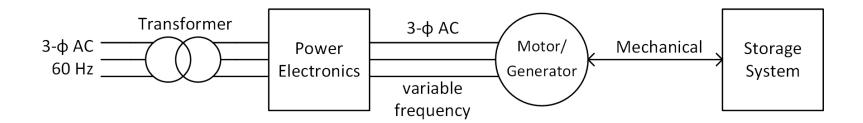


Mechanical storage

- Pumped hydro, flywheels, compressed air
- PCS includes a *motor/generator*
 - Possibly driven by a turbine
- Motor/generator may be connected directly to the grid
 - Synchronous with the grid
 - Runs at *fixed speed*

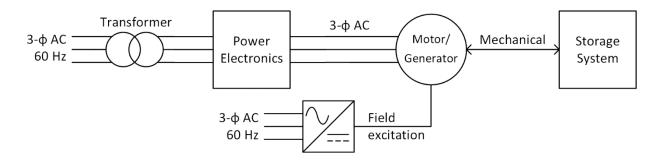


- Alternatively, motor/generator can be run at variable speed
 Maximize efficiency
 - Interface to grid through power electronic converter
- Two options for variable-speed operation:
 - Singly-fed motor/generator
 - Doubly-fed motor/generator



Singly-fed motor/generator

- **D** Synchronous machine
- Stator driven with variable-frequency AC from power electronic converter
- Field windings on rotor supplied with DC excitation voltage
 - Same as for fixed-speed synchronous machine

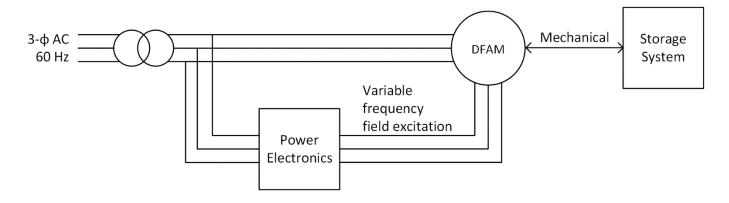


Converter must be rated for full motor/generator power

Large, expensive

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- Doubly-fed motor/generator
 - Doubly-fed asynchronous machine (DFAM)
 - Stator connected to grid-frequency AC
 - Field windings on rotor supplied with variable-frequency excitation voltage



- Converters need not be sized for rated motor/generator power
 - Only supply lower-power excitation to the rotor

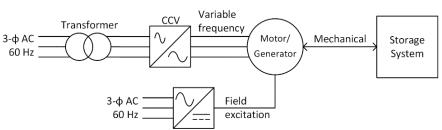
Power Electronic Converters

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- Variable-speed motors/generators require a *static frequency converter* (SFC)
 - Both for singly- and doubly-fed configurations
 - Power electronic switching converter
 - Convert between grid-frequency to other frequencies
- Common SFC topologies
 - **Cycloconverter** (CCV)
 - AC-AC converter
 - Voltage-source converter (VSC)
 - AC-DC-AC converter

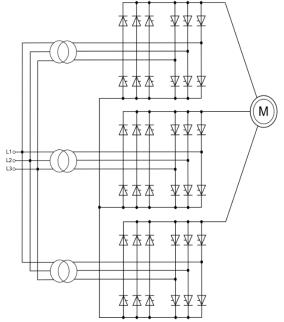
Cycloconverter

Cycloconverter AC-to-AC frequency converter



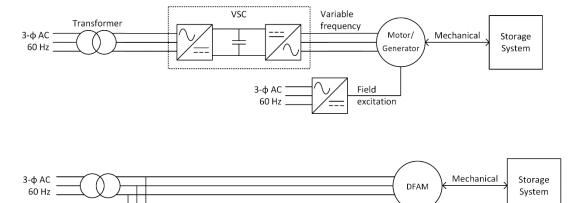
3-¢ AC 60 Hz DFAM Mechanical Storage Variable ccv frequency field excitation

- Direct conversion between grid and variable frequency AC
 No intermediate DC link
- Switching thyristor bridge circuits
 - Controllable connections between all input and output phases



Voltage Source Converter

- Voltage source converter (VSC)
 - Back-to-back AC/DC converters
 - DC link between converters
 - Variable frequency AC on motor/generator side
- VSC topologies include:
 - Two-level PWM
 - Multi-level PWM
 - Multi-level modular converter (MMC)



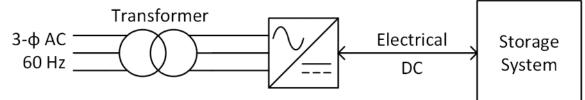
VSC

Variable

frequency field excitation

System Configurations – Electrical/Electrochemical

- Electrical and electrochemical storage
 - Ultracapacitors, batteries
- Output from storage device is already in the *electrical* domain, but it is *DC*
 - Need AC/DC conversion to interface with the grid



- AC/DC conversion
 - Charging: AC-to-DC *rectification*
 - Discharging: DC-to-AC *inversion*
- Voltage source converter is a common choice here
 Independent control of real and reactive power control
 Allows storage to provide black start capability