



Welcome to ACP50 Committee on Traffic Flow Theory and Characteristics

January 9th, 2023 – 1:30pm / 5 pm (max!)







- Please sign on paper (in-person attendees) or through the google sheet (online attendees)!
- For online attendees, please mute yourself. Only questions in the chat will be considered.
- Will skip self-introduction; Please introduce yourself when you speak.
- An electronic vote was organized among the committee in December to approve the minutes of 2022 annual and summer meetings. The final versions are available on the website.
- Please keep you MyTRB account up to date with your latest info



Agenda



	Welcome and Call to Order	L. Leclerco
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TRB Report
 R. Cunard/R. Bertini

Chair ReportL. Leclercq

FHWA Programs & ActivitiesJ. Sturrock/R. James

TFTC Subcommittee Reports

Connected Automated Vehicles (ACP50(3))S. Hamdar

Research Problem StatementsV. Gayah

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Awards.M. Menendez / J. Kim.

Mid-Year MeetingsL. Leclercq

Outreach and Diversity.
 S. Hamdar/A. Talebpour

Subcommittee reshuffling
 L. Leclercq

Liaison with other CommitteesAll Attendees

International Liaison
 International members and attendees

Announcements and Future Meetings
 All Attendees



TRB Report



- Rich Cunard
- Robert Bertini





Chair report - Membership

- Welcome to all our new members (2022 rotation)!!!!
- New international members:
 - Francesco Viti (Univ Luxembourg) Luxembourg
 - Lina Kattan (Univ Calgary) Canada
 - Marco Rinaldi (AMS) Netherlands
- New members:
 - Maria Laura Delle Monache (Berkeley)
 - Ramachandran Balakrishna (Caliper)
 - Biagio Ciuffo (JRC)
 - Tamara Djukic (ERTICO)
 - Silvia Varotto (EPFL)





Chair report - Membership

- New young members
 - Panchamy Krishnakumari (TU Delft)
 - Irene Martinez (TU Delft)
 - Kenan Zhang (ETHZ / EPFL)
 - Rafegh Aghmohammadi (Michigan)
- V. Gayah remains our Comittee Research Coordinator (CRC) and S. Hamdar has been appointed Secretary
- We are still looking for one State DOT Member (suggestions are welcomed)
- Gender ratio in now 31%





Chair Report – TRB activities

Subcommittee Meetings

Traffic Flow Theory and Characteristics Committee Monday, January 09 Ludovic Leclercq, Universite Gustave Eiffel, presiding 1:30 PM-ACP50 Operations and Traffic Management 3:15 PM ET **More Details Traffic Flow Modeling for Connected and Automated Vehicles** Monday, January 09 Subcommittee, ACP50(3) 6:00 PM-Samer Hamdar, George Washington University, presiding **ACP50** ACP50(3) 7:30 PM ET **Operations and Traffic Management** Simulation Subcommittee (SimSub), ACP80(1), Joint Subcommittee of ACP80, ACP20, ACP25, ACP35, ACP40, ACP50, ACP55, AEP40, AMS10

Monday, January 09 7:30 PM-10:00 PM ET ACP80, ACP20, ACP25, ACP35, ACP40, ACP50, ACP55, AEP40, AMS10
Christopher Melson, Oregon Department of Transportation, presiding
John Shaw, Iowa State University, presiding
Operations and Traffic Management, Planning and Forecasting, Environment

ACP80 ACP20 ACP25 ACP35 ACP40 ACP50 ACP55 ACP80(1) AEP40 AMS10

Workshop

	Workshop 1041			
	Connected and Automated Vehicles in Freight, Ridesharing, and			
	(Para)Transit			
	Samer Hamdar, George Washington University, presiding			
Sunday, January 08	Workshop Spotlight Theme PDH	ACP50 ACH30 AED50 AP080		
1:30 PM- 4:30 PM ET	Operations and Traffic Management, Rail, Public Transportation, Spotlight	AR080		
	Theme: Rejuvenation Out of Disruption: Envisioning a Transportation System			
	for a Dynamic Future			





Chair Report – lecterns

	Lectern Session 2005		
Monday, January 09 8:00 AM- 9:45 AM ET	Recent Advances in Traffic Flow Theory and Characteristics Marco Rinaldi, AMS Institute, presiding Lectern PDH Operations and Traffic Management	ACP50	
Tuesday, January 10 8:00 AM- 9:45 AM ET	Urban Network Modeling and Control Lina Kattan, University of Calgary, Schulich, presiding Lectem PDH Operations and Traffic Management More Details	ACP50	
Tuesday, January 10 10:15 AM- 12:00 PM ET	Lectern Session 3059 Traffic Flow with Connected and Autonomous Vehicles: Behavioral Insights Rachel James, Federal Highway Administration (FHWA), presiding Lectern PDH Operations and Traffic Management, Safety and Human Factors	ACP50	
Wednesday, January 11 8:00 AM- 9:45 AM ET	Lectern Session 4002 Reproducible Research in Traffic Flow Theory Christine Buisson, Université Gustave Eiffel, presiding Lectern PDH Operations and Traffic Management	ACP50	
Wednesday, January 11 10:15 AM- 12:00 PM ET	Lectern Session 4041 Multimodal Traffic Flow Models Tamara Djukic, Aimsun, presiding Lectern PDH Operations and Traffic Management	ACP50	





Chair Report - Posters

Monday, January 09 10:15 AM- 12:00 PM ET	Poster Session 2096 Traffic Flow Theory, Part 1: Network Modeling and On-Demand Mobility (Part 2, Session 3212; Part 3, Session 3213; Part 4, Session 4027) Kenan Zhang, EPFL - École Polytechnique Fédérale de Lausanne, presiding Poster Operations and Traffic Management	ACP50
Tuesday, January 10 6:00 PM- 7:30 PM ET	Traffic Flow Theory, Part 2: Connected and Autonomous Vehicles (Part 1, Session 2096; Part 3, Session 3213; Part 4, Session 4027) Danjue Chen, University of Massachusetts, Lowell, presiding Poster Operations and Traffic Management More Details	ACP50
Tuesday, January 10 6:00 PM- 7:30 PM ET	Poster Session 3213 Traffic Flow Theory, Part 3: Microscopic Traffic Models and Trajectory Analysis (Part 1, Session 2096; Part 2, Session 3212; Part 4, Session 4027) Biagio Ciuffo, JRC: European Commission Joint Research Centre, presiding Poster Operations and Traffic Management	ACP50
Wednesday, January 11 8:00 AM- 9:45 AM ET	Traffic Flow Theory, Part 4: Traffic Modeling, Monitoring, and Control (Part 1, Session 2096; Part 2, Session 3212; Part 3, Session 3213) Maria Laura Delle Monache, University of California, Berkeley, presiding Poster Operations and Traffic Management	ACP50





Chair Report – Posters (2)

Poster Session 2095

Doctoral Student Research in Transportation Operations and Traffic Control

Monday, January 09 10:15 AM-12:00 PM ET Huaguo Zhou, Auburn University, presiding
Michael Knodler, University of Massachusetts, Amherst, presiding
Poster
Operations and Traffic Management, Pedestrians and Bicyclists

ACP00 AC000(1) ACP20 ACP25 ACP50 ACP55





Some insights from the TRB meetings

- Please keep you MyTRB account up to date with your latest info
- MyTRB now includes a mailing system. We are considering transitioning from the Google group to MyTRB system, but we need to be sure that all friends are correctly registered
- Subcommittees should be revisited. They should have a clear purpose, critical tasks and a time horizon (before an evaluation). A key feature of subcommittees is the opportunity to meet during TRB
- Task groups can be created with no time limits but will not have meeting spots during TRB
- Operation and Safety sections have been merged into a single group.
 - Next group chair: Robert Bertini
 - Next section chair: Soyoung Ahn
- Triennal Strategic Plan should be elaborated for all committees. The idea is to identify the critical challenges for the next 3-5 years and the list of priority actions for the committee. TSPs will help sections/groups to foster collaborations between committees.







- Jim Sturrock
- Rachel James



Federal Highway Administration (FHWA) Analysis, Modeling, and Simulation (AMS) Research Updates

Rachel James, Ph.D.
FHWA Office of Safety and Operations
Research and Development



Agenda

- Connected and Automated Vehicle (CAV) AMS Research Program.
- Ongoing project updates:
 - Advanced driver assistance system (ADAS) data collection projects.
 - ADAS and automated driving system (ADS) modeling gap report.*
- Published reports:
 - CAV AMS cornerstone framework.²
 - CAV model improvement.^{3,4,5}
 - CAV case studies.^{6,7,8}
 - ▶ Multiresolution modeling for traffic analysis. 9,10,11

*FHWA. Advanced Driver Assistance System and Automated Driving System Modeling Gap Report. Forthcoming. Washington, DC: FHWA.





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CAV AMS Research Program



CAV AMS Program Vision and Goals

- Vision: Help State and local agencies understand the most likely impacts of CAVs on their roadways according to key performance metrics to support improved operational and investment decisionmaking.
- Goals: Coordinate CAV AMS efforts across FHWA disciplines:
 - ▶ Accelerate development of AMS tools and models, including improved functionality and validation.



Summary of Activities by Stakeholders

Develop Guidance

modeling, cost/benefit, scenario planning, calibration, measures of effectiveness, assumptions

Collect and Disseminate Data

trajectory, storage, standardization, lane change, car following

Engage Stakeholders

industry, academia, State/local, education, collaboration, expert panel, facilitation

Conduct Behavioral Research

human drivers, automated vehicles, work zone safety, fleet penetration

Characterize System Impacts

penetration, mixed, capacity, demand, extreme conditions, infrastructure

Research and Develop Use Cases and Pilot Projects

emerging technologies, vulnerable road users, impacts

Establish and Update Standards

shared data format, CAV definitions, cybersecurity

Map Research Needs To Potential Tools and Workflows

open behavior model, tool library

Research Human Factors

adoption rates, decisionmaking

CAV AMS Program Plan Desired Outcomes

ID	Title	Description
1	Active CAV AMS community	Establish a dynamic and engaged CAV AMS community that connects key CAV stakeholders, AMS stakeholders, and FHWA personnel to identify essential issues, focus resources and attention, and foster participation in CAV AMS program activity.
2	Track CAV technology capabilities and distribution	Track the functions and capabilities of CAV vehicle and infrastructure technology, including the distribution (both fleet and infrastructure penetration) of these technologies across the nation's surface transportation system.
3	Observe human behavioral responses to various types of CAV technology	Conduct and synthesize research on the behavior of human travelers and drivers, as observed and reported by individuals interacting with different types of CAV technologies in different environments.
4	Collect and share validated system data for CAV AMS	Share validated system data for CAV modeling in a standard format to support CAV AMS tool development efforts.
5	Regularly update available CAV AMS tools and resources	CAV AMS tools and resources provide possible future mixed fleet and technology scenarios but come with a range of uncertainties. It is essential to determine how CAVs and other emerging technology can be incorporated into existing AMS tools to analyze their potential benefits and impacts.



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Ongoing Projects



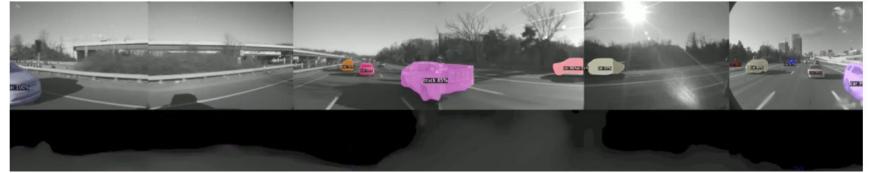
CARMASM Data Collection

Research team:

- Collected data in Northern Virginia, including in an active work zone.
- Collected data using both a readily identifiable, ADAS-equipped SAE International (SAE) Level 2 vehicle and an inconspicuous, manually driven Level 1 vehicle (MDV).¹
- Collected 61 runs, or about 30 terabytes, of raw vehicle sensor data.



Source: FHWA

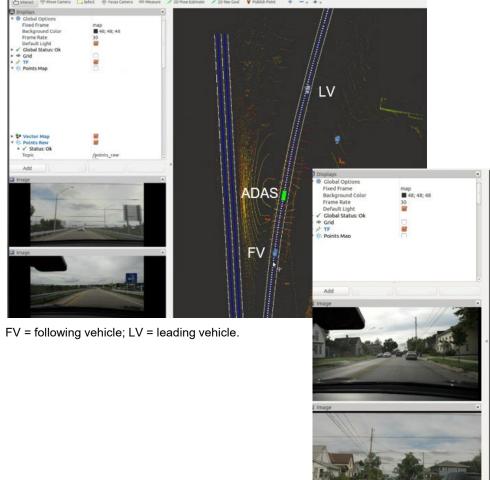


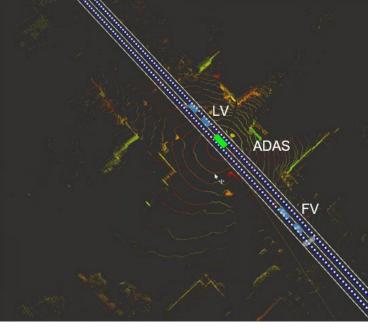
Source: FHWA.

Acquiring CAV Performance Datasets

Research team:

- Collected data in central Ohio to leverage many of the active CAV deployments in the region.
- Collected data using both readily identifiable and discreet ADAS-equipped Level 2 vehicles.
- Collected 120 h of driving data.





All photos source: FHWA.

Third-Generation Simulation

Research team:

- Collected data during rush hour in multiple locations in Chicago, IL and Washington, DC.
- Collected ADAS-equipped vehicle data (Level 1 and Level 2 functionality).
- Collected accompanying aerial data by using both moving and stationary helicopters and high-altitude fixed cameras.





All photos source: FHWA.



Source: FHWA.

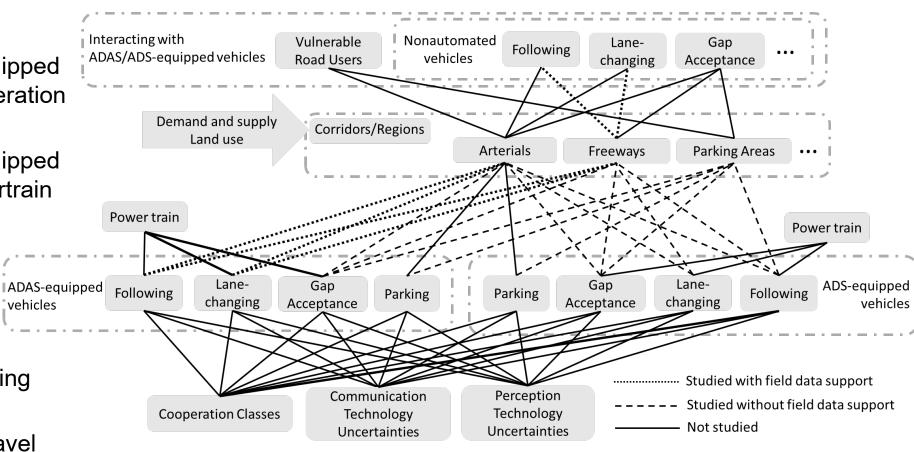
ADAS and ADS Modeling Gap Report*

Methodological Gaps:

- Impacts of technology.
- Behavior of ADAS/ADS-equipped vehicles with different cooperation classes.
- 3. Behavior of ADAS/ADS-equipped vehicles with different powertrain systems.

vehicles

- Interactions between ADAS/ADS-equipped vehicles, infrastructure, and other road users.
- 5. Behavior of vehicles in parking areas.
- Investigations of regional travel behavior.



Source: FHWA







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CAV AMS Research Products



CAV AMS Cornerstone Framework Report

Provides an architecture for CAV AMS framework.

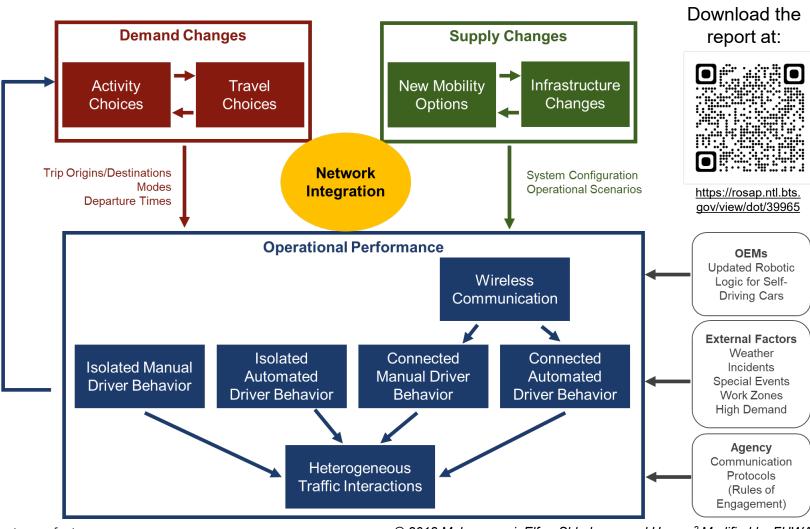
Performance Measures:
Throughput

Flow Stability
Dynamic Travel Time

iramework.

Discusses results of a modeling gap analysis.

Transportation System
Attributes:
Comfort
Safety



OEMs = original equipment manufacturers.

© 2018 Mahmassani, Elfar, Shladover, and Huang.² Modified by FHWA.

CAV Model Improvement: Tool Development

The report documents new open-source tools that capture CAV driving behavior in microsimulation models:

- Automated vehicle lane-changing algorithm.
- Cooperative adaptive cruise control and connected vehicle algorithms.
- Speed harmonization algorithm.
- Cooperative merge algorithm.



Source: FHWA.3

https://www.fhwa.dot.gov/publications/ research/operations/21077/21077.pdf

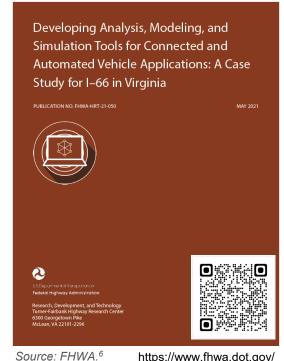


Open-Source Code:

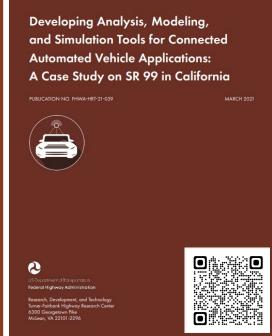
its.dot.gov/code/
or
github.com/STOL
AMS/4,5

CAV Impact Assessment: Case Studies

- Discuss developing realistic simulations by involving local agencies while defining assumptions.
- Identify likely impacts of CAVs on freeways and arterials through case studies conducted using existing tools and capabilities.







Source: FHWA.7

https://www.fhwa.dot.gov/ publications/research/ operations/21039/21039.pdf



Source: FHWA.8

https://www.fhwa.dot.gov/ publications/research/ operations/21085/21085.pdf

Multiresolution Modeling (MRM) for Traffic Analysis: State-of-Practice and Gap Analysis Report

- Documents consistent definitions for MRM concepts.
- Discusses a unified modeling framework to help transportation professionals better understand the opportunities and challenges associated with MRM.



Source: FHWA.9

https://www.fhwa.dot.gov/publications/ research/operations/21082/index.cfm

MRM for Traffic Analysis: Case Studies Report

- Provides a blueprint of the successful pilot studies conducted for the MRM project.
- Presents lessons learned to agencies to facilitate successful MRM adoption.



Source: FHWA.¹⁰

https://www.fhwa.dot.gov/publications/ research/operations/22054/index.cfm

MRM for Traffic Analysis: Guidebook

- Supports transportation professionals in assessing the level of effort needed for MRM.
- Assists agencies in understanding the benefits of developing multiresolution models for their analyses.
- Provides guidance for developing multiresolution models.



Source: FHWA.11

https://www.fhwa.dot.gov/publications/research/operations/22055/index.cfm

Questions?

References

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- 2. Mahmassani, H. S., A. Elfar, S. Shladover, and Z. Huang. 2018. *Development of an Analysis/Modeling/Simulation (AMS) Framework for V2I and Connected/Automated Vehicle Environment*. Report No. FHWA-JPO-18-725. Washington, DC: FHWA.
- 3. Lu, X., H. Liu, H., X. Li, Q. Li. H. Mahmassani, A. Talebpour, M. Hosseini, Z. Huang, D.K. Hale, and S. E. Shladover. 2021. *Developing Analysis, Modeling, and Simulation Tools for Connected and Automated Vehicle Applications*. Report No. FHWA-HRT-21-077. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/21077/index.cfm, last accessed October 26, 2021.
- 4. U.S. Department of Transportation. n.d. "ITS CodeHub" (web page). https://its.dot.gov/code/, last accessed November 3, 2021.
- 5. GitHub, Inc. 2021. "STOL-AMS" (web page). https://github.com/STOL-AMS/, last accessed November 3, 2021.
- 6. Ma, J., Y. Guo, and Z. Huang. 2021. *Developing Analysis, Modeling, and Simulation (AMS) Tools for Connected and Automated Vehicle Applications: A Case Study for I-66 in Virginia*. Report No. FHWA-HRT-21-050. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/21050/index.cfm, last accessed October 26, 2021.
- 7. Liu, H., X. Lu, S. E. Shladover, and Z. Huang. 2021. *Developing Analysis, Modeling, and Simulation Tools for Connected Automated Vehicle Applications: A Case Study on SR 99 in California*. Report No. FHWA-HRT-21-039. Washington DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/21039/index.cfm, last accessed October 26, 2021.



References (continued)

- 8. Huang, Z., J. Ma, Y. Guo, N. Matout, Y. Feng, D. Florence, and K. Balke, et al. 2021. *Developing Analysis, Modeling, and Simulation Tools for Connected Automated Vehicle Applications: Traffic Optimization for Signalized Corridors—Case Studies in Ann Arbor, MI, and Conroe, TX*. Report No. FHWA-HRT-21-085. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/21085/21085.pdf, last accessed October 26, 2021.
- 9. Zhao, X., M. Hadi, and D. Hale. 2021. *Multiresolution Modeling for Traffic Analysis: State-of-Practice and Gap Analysis Report*. Report No. FHWA-HRT-21-082. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/21082/index.cfm, last accessed March 24, 2022.
- 10. Hadi, M., X. Zhao, and D. Hale. 2021. *Multiresolution Modeling for Traffic Analysis: Case Studies Report*. Report No. FHWA-HRT-22-054. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/22054/index.cfm, last accessed March 24, 2022.
- 11. Hadi, M. X. Zhao, and D. Hale. 2021. *Multiresolution Modeling for Traffic Analysis: Guidebook*. Report No. FHWA-HRT-22-055. Washington, DC: FHWA. https://www.fhwa.dot.gov/publications/research/operations/22055/index.cfm, last accessed March 24, 2022.

Contacts

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https://highways.dot.gov/research/operations/analysis-modelingsimulation/analysis-modeling-simulation-overview



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Paper ReviewL. Leclercq

Awards.M. Menendez / J. Kim.

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Outreach and Diversity.
 S. Hamdar/A. Talebpour

Subcommittee reshuffling
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Liaison with other CommitteesAll Attendees

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Subcommittees



1. Connected Automated Vehicles (ACP50(3))

S. Hamdar

2. Research Problem Statements

V. Gayah

3. Paper Review

L. Leclercq

4. Awards.

M. Menendez / J. Kim

5. Mid-Year Meetings

L. Leclercq

6. Outreach and Diversity.

S. Hamdar / A. Talebpour

Committee Communications

S. Hamdar

TFTC Webinar

J. Laval

TFTC Journal Club

A. Talebpour

Committee Website

R. Bertini & A. Zockaie

7. Subcommittee reshuffling

L. Leclercq



Meeting



ACP50(3) Subcommittee: Connected and Automated Traffic Flow (CAT-Flow) Subcommittee

ACP50(3) Report

Transportation Research Board Annual Meeting January the 9th, 2023



TRB January 2023 (acceptable number of CAV related papers):

18 handled by ACP50-3 directly; 13 submitted to new Special Call for Papers:

Behavioral Studies in the Presence of Autonomous Vehicles: From Human Factor Research to Modeling and Simulation

CFP's organizers:

- Danjue Chen (<u>danjue chen@uml.edu</u>)
- Samer Hamdar (<u>hamdar@gwu.edu</u>)
- Lina Kattan (lkattan@ucalgay.ca)
- Ludovic Leclercq (<u>ludovic.leclercq@univ-eiffel.fr</u>)
- Michail Makridis (mmakridis@ethz.ch)
- Anshuman Sharma (<u>anshuman.sharma@uq.net.au</u>)
- Meng Wang (<u>meng.v.wang@gmail.com</u>)
- Zuduo Zheng (<u>zuduo.zheng@uq.edu.au</u>)

1 Lectern Session (Dr. Rachel James) and 1 Poster Session (Dr. Danjue Chen)

Thank you for CAT-Flow members and friends for your reviews and contributions – please continue engaging us and supporting us with your time and responsiveness





TRB January 2023 - Workshop (held on Sunday – 1:30 pm – 4:30 pm)

Title: Connected and Automated Vehicles' (CAVs') Adoption in Freight, Ride-Share, Transit and Paratransit Services: From Behavioral Modeling to Fleet Deployment Studies.

Co-Sponsoring Committees/Leeds:

- ACH30 Committee on Human Factors of Vehicles (Dr. Jing Feng jfeng2@ncsu.edu)
- AED50 Committee on Artificial Intelligence and Advanced Computing Applications (Dr. Mecit Cetin MCetin@odu.edu)
- AP080 Committee on Transit Safety and Security (Dr. Lisa Staes <u>staes@usf.edu</u>)

5 Speakers: Industry (1), National Centers (2), Academicians/Professors (2) 113 registered attendees with contact information







Research CAV Survey Document (based on TRB 2020/2021 Workshops) – To Be Updated After TRB2023 Workshop (join us at ACP50-3 Meeting

Research Needs and Progress:

- 1- Starting with ACC ACC initiative/Webinar Series
- --> 2-day online workshop (AI in CAV Traffic Flow) Yang Zhou and Danjue Chen
- 2- Lane Changing/Platooning 2023
- 3- CAV at junctionsetc
- 4- Network Fleet Management and Deployment:

Transit/Paratransit/Rideshare/Freight → Expansion to ARTS 2023 Proposal







Reminder:

Website Updated:

https://tftcav.seas.gwu.edu

- Expanded List of Members and Friends: 50+
- Possible additional collaboration / joint sponsorships: ACP80, ACP40 discussed









- Subcommittee Expanded Please join us:
 - O Upcoming Meeting: 6:00 pm until 7:30 pm EST. The meeting will be held at the Marriott Marquis, Salon 9 (M2).

Name	Affiliation								
Danjue Chen	University of Wisconsin, Madison								
Ali Zochai	Michigan State University								
Alireza Talebpour	UIUC								
Amir Ghiasi	Leidos								
Anshuman Sharma	Postdoctoral fellow, IISc, India								
Bingyi Fan	Northwestern University								
Chenfeng Xiong	University of Maryland								
Claire Silverstein	Noblis-GWU								
Dan Work	University of Vanderbilt								
Danjue Chen	University of Massachussets, Lowel								
Dazhou Li	Shenyang University of Chemical Technology								
Gabor Orosz	University of Michigan, Ann Arbor								
Haizhong Wang	Oregon State University								
Hao Zhou	Georgia tech								
Jian Wang	School of Transportation, Southeast University								
Jian Zhang	Beijing Key Laboratory of Traffic Engineering, Beijing University of Technology								
Jiang Rui (姜锐)	Beijing Jiangtong University								
Jiaqi Ma	UCLA								
Jing Dong	Iowa State University								
Jinhua TAN	Zhongnan University of Economics and Law								
Kitae Jang	KAIST								
Kuilin Zhang	Michigan Tech University								
Li Song	University of north carolina at charlotte								
Lina Kattan	University of Calgary								
Mark Brackstone	AIMSUM								
Meixin Zhu	University of Washington								
Meng Wang	TU Delft, Netherlands								
Michael Levin	University of Minnesota								
Michail Makridis	ETH Zurich								
Mohaiminul Haque	George Washington University								

Monica Menendez	NYU - Abu Dhabi								
Omer Verbas	Argone National Laboratory								
PENGFEI ZHAO	Beijing University of Civil Engineering and Architecture								
Qian Chen	Southeast University, school of automation								
Rachel James	USDOT - FHWA								
Rafegh Aghamohammadi	Georgia Tech								
Rami Ammourah	uiuc								
Reza Khajeh-Hossein	uiuc								
Samer Hamdar	George Washington University								
Seungmo Kang	Korea University								
Shun SU	BOKU Universität Wien								
Simeon Calvert	TU Delft								
Siyuan Gong	Department of Computer Science, College of Information Engineering, Chang'an University, China								
Stephen Mattingly	University of Texas at Arlington								
Tian junfang (田钧方)	Tianjin University								
Tu Xu	Zhejiang Lab, Hangzhou, China								
Wei Ma	The Hong Kong Polytechnic University								
Xiaopeng (Shaw) Li	University of South Florida								
Xuesong (Simon) Zhou	Arizona State University								
Yang Zhou	University of Wisconsin Madison								
Yangjiao Chen	Georgia Institute of Technology								
Yasir Ali	Queensland University of Technology								
Yuan Zheng	Hong Kong polytechnic university								
Zhengtian Xu	George Washington University								
Zuduo Zheng	University of Queensland								

 Special thanks to all ACP50 committee members/leadership for your support.







Subcommittees



1. Connected Automated Vehicles (ACP50(3))

S. Hamdar

2. Research Problem Statements

V. Gayah

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R. Bertini & A. Zockaie

7. Subcommittee reshuffling

L. Leclercq



Goals as Committee Research Coordinator

- Identify research needs
- Develop research needs statements
- Seek funding sources
- Submit RNSs to funding programs
- Share information about research needs and research in progress
- Develop/maintain research portfolios



Research Needs Statements

- Identify and explain research need that can eventually be turned into a project (e.g., NCHRP)
- Due Nov 1 annually
- Can be written by anyone
- Must be submitted and supported by:
 - State highway safety office
 - Governors highway safety association executive board member
 - NHSTA
 - The more, the better
- Reviewed for AASHTO committee on Research and Innovation
- If selected, results in NCHRP project!
- Would love to have help from volunteers to develop these!
 - Great opportunity for senior PhD students or early career individuals to get engaged!
 - Email Vikash if interested in helping



Research Needs Statements

- Submitted one recently last year jointly with SimSub
 - Title: Simulating Mixed Heterogeneous Traffic Flows for Better Assessment of Heavy Vehicles
 - TFTC contributing members: Mohammed Hadi, Samer Hamdar, Danjue Chen, Vikash Gayah
 - Supported by: Virginia and Wisconsin DOTs, supported by North Carolina, California, Florida DOTs



Research Needs Statements

- Potential collaborative avenues discussed during TRB AM:
 - SimSub
 - Safety committees
 - Highway Capacity committee
 - Network modeling committee
 - Freeway operations committee
- Volunteers available that work with these committees and can engage in these efforts???



NCHRP Synthesis topics

- Documents current practice for specific highway topic
- If selected:
 - Results in funded project of \$55K to to review of specific area
 - Can lead to future NCHRP project
- Due February 17, 2023
- Can be written and submitted by anyone
- Would love to have help from volunteers to develop these!!!
 - Great opportunity for senior PhD students or early career individuals to get engaged!
 - Email Vikash if interested in helping



Potential Synthesis topic

- Use of ITS for congestion management
- Planning for CAV impacts
- Impacts of urban freight on traffic in city centers



Subcommittees

1. Connected Automated Vehicles (ACP50(3))

S. Hamdar

2. Research Problem Statements

V. Gayah

3. Paper Review

L. Leclercq

4. Awards.

M. Menendez / J. Kim

5. Mid-Year Meetings

L. Leclercq

6. Outreach and Diversity.

S. Hamdar / A. Talebpour

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TFTC Webinar

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R. Bertini & A. Zockaie

7. Subcommittee reshuffling

L. Leclercq



















Many thanks to subcommittee members, authors and reviewers!







Dates	Process	Review Outcome
Aug 1	Papers due	
Aug 18	Review Assignment	Please 'accept/decline' review invitations!
Sept 15	Reviews due	
Oct 1-15	1st round decision	Presentation: Accept, Reject Publication: Reject or Moved to Editorial Review

Review process after moved to editorial review

- Assigned to an Associate Editor and then a Handling Editor
- A handling editor may invite additional reviewers or make a decision (accept, revise, reject)







Annual Meeting	2023	2022	2021	2020	2019	2018	2017	2016	2015	2014
Papers Received	174	140	109	194	196	194	207	173	201	195
Percent increase	24%	28%	-44%	-1%	1%	-6%	20%	-14%	4%	13%
Presentation only	113	94	61	93	80	64	67	54	48	32
Publication only	х	х	0	0	0	4	1	2	4	3
Present and publish	59	48	48	101	116	126	139	117	149	160
Submitted Presentation	174	140	109	194	196	190	206	171	197	192
Lectern Sessions	5	1	1	5	5	5	6	6	6	5
Lectern Papers	25	6	4	25	25	25	30	31	27	23
Poster Sessions	4	4	4	5	5	4	4	3	2	2
Poster Papers	83	75	61	86	84	84	84	71	80	84
Subtotal	108	81	65	111	109	109	114	102	107	107
Percent Accepted	62%	58%	60%	57%	56%	57%	55%	60%	54%	56%
Rejected	66	59	44	83	87	81	92	70	90	85







Annual Meeting	2023	2022	2021	2020	2019	2018	2017	2016	2015	2014
Submitted Publication	59	46	48	101	116	129	140	119	152	163
Editorial Review	23	14	15	32						



Best Reviewer award





Congratulation to

Saif Eddin Jabari New-York University Abu Dhabi





CERTIFICATE OF APPRECIATION

BEST PAPER REVIEWER AWARD

PRESENTED TO

S. Jabari

In recognition to your commitment to the Committee on Traffic Flow Theory and Characteristics TRB 102nd Annual Meeting ~ January 8-12, 2023 ~ Washington, DC

Ludovic Leclercg

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

JANUARY 2023



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L. Leclercq



Some insights



- 5 awards are discussed within the committee (2 are specific to the TFTC committee, 3 are from TRB)
- Previously, papers had to be submitted (and accepted) for publication to qualify for any award. This year, as part of a trial, we also accepted papers submitted only for presentation, as long as they are later published in TRR.
- Typically, awards are given one year after the paper is presented at TRB.
 This year, as part of a trial, we made decisions on the Greenshield and Gartner awards on the same year.
- Award subcommittee: Rob Bertini, Jiwon Kim, Sue Ahn, Monica
 Menendez. The subcommittee chair, Monica Menendez is stepping down this year, and Jiwon Kim will be the next chair.







- Recognizes theoretical papers with significant methodological contributions
- Award is given within the Traffic Flow Theory committee

2022

 22-04077: A Real-Time Distributed Cooperative Adaptive Cruise Control Model Considering Time Delays and Actuator Lag (by Yingtong Tan and Kuilin Zhang).

2023

 23-04279: Traffic Flow as A Simple Fluid: Towards A Scaling Theory of Urban Congestion (by Jorge Laval).





2022 Nathan Gartner Award

Presented to

Gingtong Tan

Michigan Technological University

For the Paper

A Real-Time Distributed Cooperative Adaptive Cruise Control Model Considering Time Delays and Actuator Lag

Ludovic Leclercq

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

TRB STAFF REPRESENTATIVE

Awarded January 2023





2022 Nathan Gartner Award

Presented to

Kuilin Zhang

Michigan Technological University

For the Paper

A Real-Time Distributed Cooperative Adaptive Cruise Control Model Considering Time Delays and Actuator Lag

Ludovic Leclercg

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

TRB STAFF REPRESENTATIVE

Awarded January 2023





2023 Nathan Gartner Award

Presented to

Forge H. Laval Georgia Institute of Technology

For the Paper
Traffic Flow as A Simple Fluid: Towards A Scaling
Theory of Urban Congestion

Ludovic Leclercq

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

Awarded January 2023







- Recognizes the use of empirical data for understanding traffic phenomena
- Award is given within the Traffic Flow Theory committee

2022

There was no award.

2023

23-02314: How Will Waymo Self-driving Cars Impact Traffic Flow? Evidence from Empirical Data (by Danjue Chen, Tienan Li, Jorge Laval,
 Soyoung Ahn and Zuduo Zheng).

Paper will be published in TRR under the name "How Will Level 4 Self-driving Cars Impact Traffic Flow? - Evidence from Empirical Data" (by Danjue Chen, Tienan Li, Jorge Laval, Soyoung Ahn and Zuduo Zheng).





2023 Greenshields Award

Presented to

Danjue Chen

University of Massachusetts, Lowell

For the Paper

How Will Waymo Self-driving Cars Impact Traffic Flow?

Evidence from Empirical Data

Ludovic Leclercq

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

Awarded January 2023





2023 Greenshields Award

Presented to

Tienan Li

University of Massachusetts, Lowell

For the Paper

How Will Waymo Self-driving Cars Impact Traffic Flow? Evidence from Empirical Data

Ludovic Leclercq

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
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Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

Awarded January 2023





2023 Greenshields Award

Presented to

Forge H. Laval Georgia Institute of Technology

For the Paper

How Will Waymo Self-driving Cars Impact Traffic Flow?

Evidence from Empirical Data

Ludovic Leclercq

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
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Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

Awarded January 2023





2023 Greenshields Award

Presented to

Soyoung Ahn University of Wisconsin, Madison

For the Paper

How Will Waymo Self-driving Cars Impact Traffic Flow?

Evidence from Empirical Data

Ludovic Leclercy

LUDOVIC LECLERCQ, CHAIR COMMITTEE
ON TRAFFIC FLOW THEORY AND
CHARACTERISTICS

Richard A. Cunard

RICHARD A. CUNARD
TRB STAFF REPRESENTATIVE

Awarded January 2023



Cunard Award



- Stimulate and encourage young researchers
- Best 1st Young Author Paper in the area of Operations (first author 35 years of age or younger)
- **2022**
 - There was no nomination.
- **2023**
 - There is one paper nominated.







- Established 1966
- Stimulate and encourage young researchers
- Recognition of excellence in transportation research by researchers 35 years of age or younger whose papers have been published under the sponsorship of any Division A Standing Group
- Accompanied by a cash prize
- Honors TRB director from 1951-1964
- **2022**
 - There was no nomination.
- **2023**
 - There was no nomination.







- Established 1976
- Outstanding paper published in the field of operation, safety, and maintenance of transportation facilities.
- Honors fifth executive director, later 33rd Executive Committee Chair
- **2**022
 - There was no nomination.
- **2**023
 - There is one paper nominated.



Subcommittees



- S. Hamdar Connected Automated Vehicles (ACP50(3))
 - Research Problem Statements V. Gayah
- 3. Paper Review L. Leclercq
- **Awards** M. Menendez / J. Kim
- Mid-Year Meetings
- 6. Outreach and Diversity.
 - **Committee Communications**
 - **TFTC Webinar**
 - **TFTC Journal Club**
 - Committee Website
- 7. Subcommittee reshuffling

- - L. Leclercq
- S. Hamdar / A. Talebpour
 - S. Hamdar
 - J. Laval
 - A. Talebpour
 - R. Bertini & A. Zockaie
 - L. Leclercq







- 2007 ISTTT London, UK (in pub)
- 2008 Greenshields Symposium, Woods Hole, Massachusetts
- 2009 ISTTT Hong Kong, China (lunch table)
- 2010 Does Traffic Data Support Traffic Models? Annecy, France
- 2011 ISTTT Berkeley (one hour w/SimSub)
- 2012 Joint Summer Meeting with HCQS Committee, Fort Lauderdale, Florida
- 2013 ISTTT, Noordwijk, the Netherlands
- 2014 Portland, Oregon, USA, Symposium Celebrating 50 Years of Traffic Flow Theory
- 2015 ISTTT Kobe, Japan
- 2016 Sydney, Australia
- 2017 ISTTT Chicago
- 2018 Woods Hole, Massachusetts
- 2019 ISTTT Lausanne, Switzerland
- 2020 Amsterdam, the Netherlands (postponed) Zoom meeting
- 2021 ISTTT Beijing, China (postponed) Zoom meeting
- 2022 Zoom meeting
- 2023 Amsterdam, the Netherlands
- 2024 ISTTT Michigan
- 2025 Start making plan!







Irene Martinez, Marco Rinaldi (chairs)
Panchamy Krishnakumari, Hans van Lint, and Serge Hoogendoorn (co-chairs),
Winnie Daamen, Victor Knoop, and Simeon Calvert (proceedings)







- Summer meeting: <u>July 26-28, 2023</u>
- Deadline for abstracts: March 15, 2023
- Review results: April 15, 2023
- Camera ready abstract submission: May 30, 2023



Venue location



- Amsterdam Institute of Advanced Metropolitan Solutions (AMS)
- Many hotels in the direct neighbourhood, e.g.:
 - Volkshotel (<u>www.volkshotel.nl</u>)
 - Lloyd hotel Amsterdam
 - Student Hotel (not only for students!)
 - Hotel Okura Amsterdam (high end!)
 - Sir Albert hotel (Albert Kuyp)









Themes considered during the meeting are:

- Urban traffic flow operations theory and models
- Traffic flow theory and AI
- Active mode flow operations
- Traffic flow and automation
- Multi-modal traffic flows in climate resilient cities

Abstracts on other relevant themes are also welcomed!

Announcement TRM 2023, TFTC



Keynote addresses



Dan Work (Vanderbilt Univeristy) "AI and Traffic Flows"





Hani Mahmassani (Northwestern University)
"Multi-modal traffic flows in resilient cities"







- TRAIL Summercourse "AI and Traffic Flow Theory" by Panchamy Krishnakumari, Hans van Lint and Serge Hoogendoorn (24 26 July, 2023)
- Course is aimed at PhDs with basic background in traffic flow theory and will involve tutorials, coding practicals, hackatons, and lots of fun!

М	Т	W	Т	F	S	S
26	27	28	29	30	1	2
3	4	5	6	7	8	9
10	11	12	13	14	15	16
17	18	19	20	21	22	23
24	25	26	27	28	29	30
31	1	2	3	4	5	6

24-26th TRAIL Summercourse

26-28th TFTC Summer meeting



Subcommittees



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 - R. Bertini & A. Zockaie
 - L. Leclercq







ACP50 Outreach and Diversity Subcommittee

Transportation Research Board 2023 Annual Meeting







ACP50 Outreach and Diversity Subcommittee

Annual Meeting of the Transportation Research Board January 2023





Outreach and Diversity Subcommittee

- Newsletter (http://tftcnews.blogspot.com/) is celebrating its 10 year anniversary.
 - 12 issues with each issue corresponding to one months (student volunteer: Mohaiminul Haque)
- ACP50 Journal Club Started in December 2021 and has had 5 presentations in 2022 with a very small group.
 - The rules of discussion have been refined will be open to TFTC members and friends starting February 2023.
 - Target Group: All are welcome, especially graduate students and young professionals
 - Please consider encouraging your students to participate
- Webinar series



Outreach and Diversity Subcommittee

- Special Thanks to:
 - Samer Hamdar
 - Jorge Laval
 - Danjue Chen
 - Mohaiminul Haque
 - Hao Zhou
 - Alireza Talebpour
 - (All TFTC contributors and readers)

Transportation Research Board

Traffic Flow Theory and Characteristics Committee—ACP 50

Newsletter

EVENTS/ANNOUNCEMENTS

Covid-19 Pandemic Resources

The entire world is now focusing on Covid-19 Pandemic. We are living in a very difficult time. The virus has surprised almost all sectors of our societies. Our thoughts are for those who are affected by the virus. We are grateful to the public health professionals and other professionals who are helping us to fight against his invisible enemy. To learn about the symptoms of the virus and play your part in this fight, please visit CDC Covid-19 Webpage.

Letter from the Chair of the ACP50 Committee

Dr. Ludovic Leclercq, the Chair of the ACP50 Committee has sent a open letter to the ACP50 Family and friends. He wishes everyone a happy new year and shares important information regarding the TRB Annual Meeting 2022. Please visit this link to access the full letter.

Traffic Flow Theory and Characteristics Committee's (ACP50) Events Schedule at TRB 101th Annual Meeting

Event Name	Date, Time and Location
Poster Session 1093: Traffic Flow Theory, Part 1: Network Modeling and Control	Monday, January 10 10:30 AM-12:00 PM ET Convention Center, Hall A
Poster Session 1178: Traffic Flow Theory, Part 2: Connected and Autonomous Vehicles	Monday, January 10 4:00 PM-5:30 PM ET Convention Center,



Volume 9, Issue 10 December 2021

Newsletter Spotlight

Covid-19 Pandemic Recourses.

Letter from the Chair of the ACP50 Committee

Traffic Flow Theory and Characteristics Committee's (ACP50) Events Schedule at TRB 101th Annual Meeting

Positions:

Department Head Position Open at NC State University.

Faculty Position open at University of Connecticut

Faculty Positions Open at Laboratoire Ingénierie Circulation Transport (LICIT)

Faculty Position open at TUM

Traffic in the Media:

Argo AI Focuses On Cyclist Identification For Automated Vehicles.



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7. Subcommittee reshuffling

L. Leclercq





Revisiting Subcommittees

Joint Subcommittee on Traffic Simulation Models (ACP50(1) SimSub)
 Christopher Melson / J. Shaw

This subcommittee is now declared as ACP80(1) with ACP50 as a supporting committee. I propose to remove the mention within ACP50.

- Crowd Flow Dynamics, Modeling and Management (ACP50(2))
 - S. Hoogendoorn / S. Talley

This committee has been less active for the last three years. The idea would be to revitalize it and make it broader (active modes) and better connected with the pedestrian committee (ACH10). We need volunteers!

- Connected Automated Vehicles (ACP50(3))
 - S. Hamdar

This committee is very active, nothing to say.





- BLUE RIBBON COMMITTEE
 Presented by the Technole Activities Council
- Last year we discussed the opportunity to create three new subcommittees:
 - Network modelling and management
 - Mobility services, modelling and design

Shall we proceed? Who volunteers to lead?

 We also plan to create a task force for the Triennal strategic plan (Lead by S. Ahn) – please volunteer



Agenda



Welcome and Call to Order

L. Leclercq

TRB Report

R. Cunard/R. Bertini

Chair Report

L. Leclercq

FHWA Programs & Activities

J. Sturrock/R. James

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Liaison with other Committees

All Attendees

International Liaison

International members and attendees

Announcements and Future Meetings

All Attendees





- Joint Subcommittee on Traffic Simulations ACP80(1) Melson / Shaw / Kaan Ozbay
- Traffic Simulations Committee (ACP80)
 Kaan Ozbay
- Highway Capacity Quality of Service Committee (ACP40)
 J. Sturrock/Others?
- Young Members CouncilE. Gonzales



Agenda



Welcome a	and Call to Order	
- * * GIGGIIIG G	ilia Gail la Giagi	

R. Cunard/R. Bertini TRB Report

Chair Report L. Leclercq

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Announcements and Future Meetings All Attendees

S. Hamdar

L. Leclercq

V. Gayah

L. Leclercq

L. Leclercq

S. Hamdar/A. Talebpour

L. Leclercq

All Attendees





The Munich Test Bed for Connected and Automated Mobility

Elements:

- Intersection area
- Park & Charge Lane
- Drive & Charge Lane
- 5G Connectivity
- Simulation Center

Highlights:

- Highly dynamic and flexible test bed
- Interaction of CAV with VRU
- Certification of automated driving functions
- X2X-Comunication
- Augmented Reality testing in real vehicles

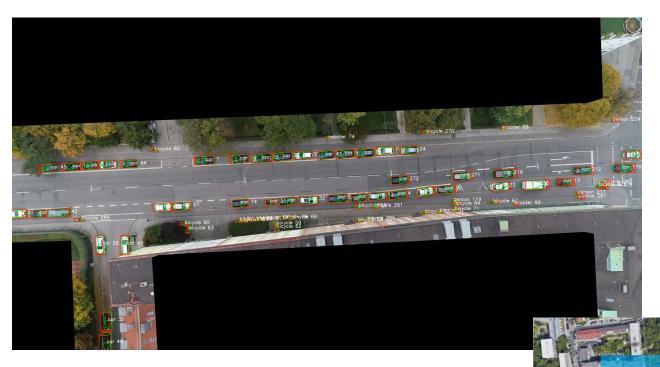
2023 | TUM | Martin Margreiter







Munich – Schwabing – Traffic Data Collection using Drones



Experiment setup:

- Munich, central area
- 2 days (Oct. 6th and 12th) with ~ 3 continuous hours per day
- 6 locations, filmed by 2 drones per location
- ~700 m in length
- Including:
 - 2 signalized and
 - 3 non-signalized intersections
 - Signalized pedestrian crossing
 - Tram stop

Klaus Bogenberger | ACP 50 Commutee Meeting | 2023-01-09





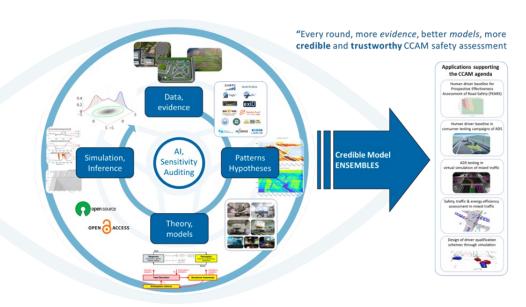


i4Driving

integrated 4D driver modelling under uncertainty

https://i4driving.eu

Vincenzo Punzo, University of Naples FEDERICO II, Hans van lint, Delft University of Technology







14Driving ambition

So, models used as (attentive well-behaved)

BENCHMARK for AV's ...

... AND to
simulate messy
and flawed
humans with
whom AV's interact

- Overarching objective of i4Driving is to deliver a new (open-source) library or credible (simulation) models of heterogeneous human driver behaviours ...
- ... which helps set a safety baseline in virtual assessment of CCAM (connected, cooperative automated mobility), i.e., AV's should at least be as safe as our benchmark human model (interacting with potentially not so great drivers)
- The i4Driving library is central component for a new standard methodology for CCAM assessment that includes simulation, VR, field lab, sensitivity auditing, ...
- This all entails much more than just the TFT we all know and love:
 - Ensemble modelling, uncertainty quantification
 - Transferable libraries of 2/3D models & scenario's & reproducible experiments
 - Communication/visualisation ideas which are transparent, rigorous, trustworthy









integrated 4D driver modelling under uncertainty











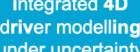


Tonight (9/1) 18:00 Hall A



















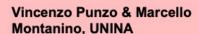






TRBAM-23-03557 — VISION FOR A NEW INDUSTRY-STANDARD METHODOLOGY FOR VIRTUAL ASSESSMENT OF AUTOMATED DRIVING SYSTEMS

Hans van Lint, TU Delft i.w.c.vanlint@tudelft.nl



Maria Rodriguez, Panteia

How can we benchmark the adequacy of automated driving systems (ADS) in real traffic, interacting with real (human) drivers? When is safe safe enough? With how much certainty can we predict this in the first place? Interactions between multiple vehicles are inherently uncertain due to driver and technology heterogeneity and the huge space of possible circumstances. Trustworthy answers require accepting this uncertainty.



Agenda



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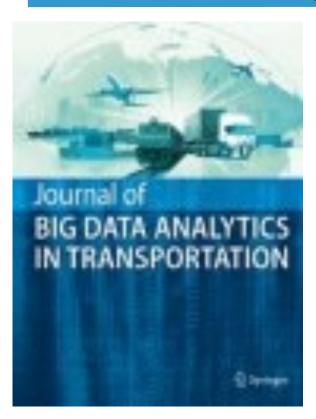
International members and attendees

Announcements and Future Meetings

All Attendees



Journal of Big Data Analytics in Transportation



Will change the name in 2023

Change in the editorial board: L. Leclercq has joined S. Ukkusuri as EIC

Welcome all papers related to data & transportation science (not restricted to big data)

EDITOR-IN-CHIEF

Satish V. Ukkusuri, Purdue University, West Lafayette, IN, USA

Distinguished Advisory Editors

Fred Mannering, University of South Florida, USA Hani Mahmassani, Northwestern University, USA Kay Axhausen, ETH, Switzerland Junyi Zhang, Hiroshima University, Japan

Associate Editors

Chao Chen, Chongqing University, China
Eleni Vlahogianni, National Technical University of Athens, Greece
Francesco Viti, University of Luxembourgh, Luxembourgh
Gitakrishnan Ramadurai, IIT Madras, India
Lavanya Marla, University of Illinois at Urbana Champaign, USA
Mecit Cetin, Old Dominion University, Norfolk, VA, USA
Meead Saberi, UNSW, Australia
Ruimin Li, Tsinghua University, China
Samiul Hasan, University of Central Florida, USA
Zhiyuan Liu, Southeast University, China









26th IEEE International Conference on Intelligent Transportation Systems

September 24th - 28th, 2023 Palacio Euskalduna, Bilbao, Bizkaia, Spain

2023.ieee-itsc.org









Towards a New Era of Human-aware, Human-interactive, and Human-friendly ITS

















Please don't forget to sign in!