

# Remaining Opportunities in Capacitive Power Transfer Based on Duality with Inductive Power Transfer

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**Abstract**—Wireless power transfer (WPT) has proven to be an effective solution for electric vehicle charging. As two mainstream near-field WPT technologies, inductive and capacitive power transfer (IPT and CPT) have many similarities. This paper aims to explore the remaining opportunities in CPT systems, not yet reported in existing literature, based on duality with the mature IPT technology. First, a generic modeling method based on two-port network theory is proposed, which contributes to unified modeling and analysis for both inductive and capacitive couplings. Then, power transfer mechanism of IPT and CPT couplers is compared, and unified transfer efficiency is derived, promoting CPT theory developments. Last, the duality between existing IPT and CPT circuits is demonstrated in two aspects: compensation circuit configuration and resonant relationship. 14 CPT topologies are derived based on duality with the existing 7 mainstream IPT circuits, of which 11 circuits do not exist in literature, offering future opportunities in CPT. Detailed comparison and evaluation of the derived 14 CPT circuits are conducted, and high-performance circuits are recommended. As a demonstration, a case study of a 2.1kW 3MHz CPT system is implemented in hardware based on the newly proposed  $M_1$ -SS topology. This example system achieves a peak efficiency of 93.19% with the predicted circuit properties of load-independent constant-voltage (CV) output and zero-phase-angle (ZPA) property.

**Index Terms**—Capacitive power transfer, inductive power transfer, duality, two-port parameter.

## I. INTRODUCTION

Wireless power transfer (WPT) technology has shown great potential in electric vehicle (EV) charging [1]-[3], which gets rid of troublesome cables and can utilize underground installation, allowing higher space utilization, convenience, and safety over conventional conductive charging [4]-[6].

Inductive power transfer (IPT) and capacitive power transfer (CPT) are two mainstream WPT technologies for EV charging [7]-[9]. In principle, IPT achieves power transfer via an alternating magnetic field generated by a pair of mutually coupled coils while CPT relies on an alternating electric field of two pairs of metal plates, shown in Figs. 1 and 2, respectively. IPT and CPT distinguish each other in couplers and fields. Meantime, similarities are also identifiable [10], typically in the compensation circuit designs. For example, in an

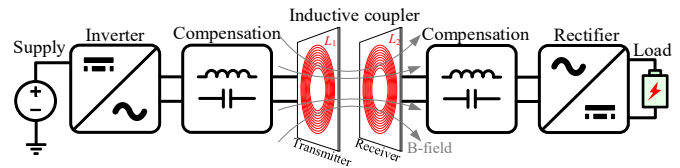


Fig.1 Structure of an inductive power transfer system.

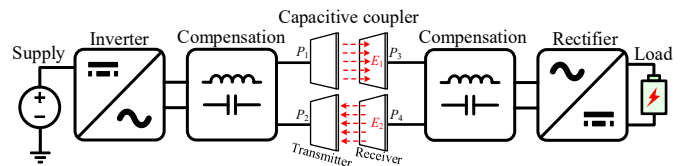


Fig.2 Structure of a capacitive power transfer system.

IPT system, there are four basic two-capacitor compensation circuits, namely, series-series (SS), series-parallel (SP), parallel-series (PS), and parallel-parallel (PP) [11]-[14]. Likewise, four basic two-inductor compensations have also been proposed for a CPT coupler with same configurations [15]-[18]. In another description, CPT technology could be considered as a reflection of IPT in a special “mirror”. Such a property is named duality between IPT and CPT systems in this paper.

IPT has been developed for over 100 years and achieved success in EVs, medical equipment, and consumer electronics [19]-[21]. However, the bulky and expensive IPT coupler and the eddy current loss limit practical applications [22]-[23]. CPT is proposed within 20 years [24] with advantages of light weight, no eddy current loss, and good misalignment tolerance, which can be applied where the IPT is not convenient, such as in underwater applications and metal-intensive motor scenarios [22], [23]. However, due to a short history, the basic theory research and circuit opportunities of CPT technology are still insufficient. Besides, the existing research that explores feasible CPT circuits [17]-[18], [25]-[28] is limited to one particular topology, lacking systematic discovery and analysis of all applicable high-performance CPT circuits. This paper hence presents a methodology to comprehensively explore remaining CPT opportunities that are not yet reported in literature based on the duality between CPT and mature IPT technologies.

The paper’s main contributions are summarized as follows. First, a generic modeling method based on the two-port network theory is proposed, which contributes to a standardized and unified modeling method for both IPT and CPT systems. Second, the power transfer mechanism of IPT and CPT systems is compared in detail, and unified transfer efficiency is derived for both couplers, revealing their similarity and promoting the CPT theory development. Third, the duality between IPT and CPT circuits is demonstrated in terms of the compensation circuit configuration and resonant relationship.

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Table I Description of IPT and CPT couplers.

Property	Inductive coupler	Capacitive coupler
Structure		
Coupling		
Self-L/C	$L_1, L_2$	$C_1, C_2$
Mutual coupling	$L_M$	$C_M$
Coupling coeff.	$k_I = L_M / (L_1 L_2)^{0.5}$	$k_C = C_M / (C_1 C_2)^{0.5}$

14 CPT topologies can be derived in duality with existing 7 mainstream IPT circuits, of which 11 CPT circuits are not yet reported in the existing literature. Furthermore, detailed comparison and evaluation of the derived 14 CPT circuits are conducted, and high-performance circuits are recommended. One case study of a 2.1kW 3MHz  $M_1$ -SS CPT system is constructed in hardware, validating the demonstrated duality investigation.

## II. MODELING OF INDUCTIVE AND CAPACITIVE COUPLINGS

### A. Standardized Definition of IPT and CPT Couplers

The inductive coupler consists of two coils  $L_1$  and  $L_2$ , and the mutually coupled magnetic field transfers power, as shown in Fig.1. An inductive coupler is generally described by self-inductances  $L_1$  and  $L_2$ , and mutual inductance  $L_M$  (or coupling coefficient  $k_I$ ).

A typical capacitive coupler includes four metal plates,  $P_1 \sim P_4$ , as shown in Fig.2. The electric field between the plates contributes to power transfer. The six-capacitor modeling can be used to demonstrate the capacitive couplings in a four-plate CPT coupler, shown in Table I.  $C_{13}$  and  $C_{24}$  are the main couplings between plate pairs  $P_1$  and  $P_3$ ,  $P_2$  and  $P_4$ ;  $C_{14}$  and  $C_{23}$  are cross-couplings between  $P_1$  and  $P_4$ ,  $P_2$  and  $P_3$ ;  $C_{12}$  and  $C_{34}$  are shunt capacitances between  $P_1$  and  $P_2$ ,  $P_3$  and  $P_4$ . According to [28], self-capacitance  $C_1$ ,  $C_2$ , and mutual capacitance  $C_M$  can be defined in (1).

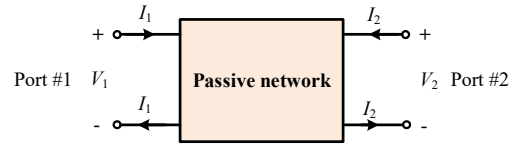


Fig.3 A typical two-port network.

Table II Description of four two-port parameters [29].

Parameters	Description	Calculation
$z$ -parameter	$\begin{cases} V_1 = z_{11}I_1 + z_{12}I_2 \\ V_2 = z_{21}I_1 + z_{22}I_2 \end{cases}$	$\begin{cases} z_{11} = \frac{V_1}{I_1} \Big _{I_2=0}, z_{12} = \frac{V_1}{I_2} \Big _{I_1=0} \\ z_{21} = \frac{V_2}{I_1} \Big _{I_2=0}, z_{22} = \frac{V_2}{I_2} \Big _{I_1=0} \end{cases}$
$y$ -parameter	$\begin{cases} I_1 = y_{11}V_1 + y_{12}V_2 \\ I_2 = y_{21}V_1 + y_{22}V_2 \end{cases}$	$\begin{cases} y_{11} = \frac{I_1}{V_1} \Big _{V_2=0}, y_{12} = \frac{I_1}{V_2} \Big _{V_1=0} \\ y_{21} = \frac{I_2}{V_1} \Big _{V_2=0}, y_{22} = \frac{I_2}{V_2} \Big _{V_1=0} \end{cases}$
$h$ -parameter	$\begin{cases} V_1 = h_{11}I_1 + h_{12}I_2 \\ I_2 = h_{21}I_1 + h_{22}I_2 \end{cases}$	$\begin{cases} h_{11} = \frac{V_1}{I_1} \Big _{I_2=0}, h_{12} = \frac{V_1}{I_2} \Big _{I_1=0} \\ h_{21} = \frac{I_2}{I_1} \Big _{V_2=0}, h_{22} = \frac{I_2}{I_2} \Big _{V_1=0} \end{cases}$
$g$ -parameter	$\begin{cases} I_1 = g_{11}V_1 + g_{12}I_2 \\ V_2 = g_{21}V_1 + g_{22}I_2 \end{cases}$	$\begin{cases} g_{11} = \frac{I_1}{V_1} \Big _{I_2=0}, g_{12} = \frac{I_1}{I_2} \Big _{V_1=0} \\ g_{21} = \frac{V_2}{V_1} \Big _{I_2=0}, g_{22} = \frac{V_2}{I_2} \Big _{V_1=0} \end{cases}$

plings between plate pairs  $P_1$  and  $P_3$ ,  $P_2$  and  $P_4$ ;  $C_{14}$  and  $C_{23}$  are cross-couplings between  $P_1$  and  $P_4$ ,  $P_2$  and  $P_3$ ;  $C_{12}$  and  $C_{34}$  are shunt capacitances between  $P_1$  and  $P_2$ ,  $P_3$  and  $P_4$ . According to [28], self-capacitance  $C_1$ ,  $C_2$ , and mutual capacitance  $C_M$  can be defined in (1).

Table III. Behavior-source models of inductive coupler.

$z$ -parameters	$y$ -parameters	$h$ -parameters	$g$ -parameters
$\begin{cases} V_1 = I_1 j\omega L_1 + I_2 j\omega L_M \\ V_2 = I_1 j\omega L_M + I_2 j\omega L_2 \end{cases}$	$\begin{cases} I_1 = \frac{V_1}{j\omega L_1(1-k_I^2)} - \frac{V_2}{j\omega L_M(1/k_I^2-1)} \\ I_2 = -\frac{V_1}{j\omega L_M(1/k_I^2-1)} + \frac{V_2}{j\omega L_2(1-k_I^2)} \end{cases}$	$\begin{cases} V_1 = I_1 j\omega L_1(1-k_I^2) + V_2 \frac{L_M}{L_2} \\ I_2 = -I_1 \frac{L_M}{L_2} + V_2 \frac{1}{j\omega L_2} \end{cases}$	$\begin{cases} I_1 = V_1 \frac{1}{j\omega L_1} - I_2 \frac{L_M}{L_1} \\ V_2 = V_1 \frac{L_M}{L_1} + I_2 j\omega L_2(1-k_I^2) \end{cases}$

Table IV. Behavior-source models of capacitive coupler [29].

$z$ -parameters	$y$ -parameters	$h$ -parameters	$g$ -parameters
$\begin{cases} V_1 = \frac{I_1}{j\omega C_1(1-k_C^2)} + \frac{I_2}{j\omega C_M(1/k_C^2-1)} \\ V_2 = \frac{I_1}{j\omega C_M(1/k_C^2-1)} + \frac{I_2}{j\omega C_2(1-k_C^2)} \end{cases}$	$\begin{cases} I_1 = j\omega C_1 V_1 - j\omega C_M V_2 \\ I_2 = -j\omega C_M V_1 + j\omega C_2 V_2 \end{cases}$	$\begin{cases} V_1 = \frac{I_1}{j\omega C_1} + V_2 \cdot \frac{C_M}{C_1} \\ I_2 = -I_1 \cdot \frac{C_M}{C_1} + V_2 \cdot j\omega C_2(1-k_C^2) \end{cases}$	$\begin{cases} I_1 = V_1 \cdot j\omega C_1(1-k_C^2) - I_2 \cdot \frac{C_M}{C_2} \\ V_2 = V_1 \cdot \frac{C_M}{C_2} + \frac{I_2}{j\omega C_2} \end{cases}$

$$\begin{cases} C_1 = C_{12} + \frac{(C_{13} + C_{14}) \cdot (C_{23} + C_{24})}{C_{13} + C_{14} + C_{23} + C_{24}} \\ C_2 = C_{34} + \frac{(C_{13} + C_{23}) \cdot (C_{14} + C_{24})}{C_{13} + C_{14} + C_{23} + C_{24}} \\ C_M = \frac{C_{13} \cdot C_{24} - C_{23} \cdot C_{14}}{C_{13} + C_{14} + C_{23} + C_{24}} \end{cases} \quad (1)$$

Table I summarizes these concepts and notations, achieving similar descriptions for IPT and CPT couplers.

### B. Generic Two-Port Parameter Modeling

Both IPT and CPT couplers can be considered a two-port circuit network. Each port consists of two terminals and satisfies the port condition: the current flowing into one terminal must equal the current flowing out of the other, which is demonstrated in Fig. 3. Considering this, a generic modeling method is proposed based on two-port network theory.

In Fig. 3, a two-port network includes 4 variables:  $V_1$ ,  $I_1$ ,  $V_2$ , and  $I_2$ . Each port has an independent excitation, either voltage or current. According to the two-port network theory [29], there exist four categories of parameters, namely:  $z$ -parameters (impedance),  $y$ -parameters (admittance),  $h$ -parameters (hybrid), and  $g$ -parameters (inverse hybrid), as described in Table II.

In each two-port parameter model, the network is linearly described by two independent excitations and four coefficients. It helps derive the equivalent behavior-source models of IPT and CPT coupler, respectively provided in Tables III and IV. For example, the inductive or capacitive coupler is equivalent to a behavior-voltage-source circuit by  $z$ -parameters, or a behavior-current-source circuit by  $y$ -parameters. Particularly, the two-port modeling for capacitive coupling has been reported in [29] while its application in IPT systems has not been clearly discussed.

### C. Power Transfer Mechanism

The description of the power transfer mechanism of inductive and capacitive couplers is provided in Table V. In both IPT and CPT couplers, the power flow from primary to secondary side is represented by  $S_{12}$ , including both the active power  $P_{12}$  and the reactive power  $Q_{12}$  [19], [29].

#### 1) Inductive Power Transfer

As shown in Table V, for an inductive coupler, the inductive coupling is equivalent to two behavior-voltage-sources  $V_{12}$  and  $V_{21}$  based on  $z$ -parameter modeling. Current  $I_2$  is taken as the reference phasor and the phase angle of  $I_1$  is represented by  $\theta_{12}$ . Then,  $I_2$  is expressed below.

$$I_1 = |I_1|(\cos \theta_{12} + j \sin \theta_{12}) \quad (2)$$

In an IPT coupler, the power flow  $S_{12}$  is calculated:

$$S_{12}|_{IPT} = V_{12} \cdot I_1^* = \omega L_M I_1 I_2 \sin \theta_{12} + j \omega L_M I_1 I_2 \cos \theta_{12} \quad (3)$$

$P_{12}$  and  $Q_{12}$  in an inductive coupler are provided below:

$$\begin{cases} P_{12}|_{IPT} = \text{Re}[S_{12}|_{IPT}] = \omega L_M I_1 I_2 \sin \theta_{12} \\ Q_{12}|_{IPT} = \text{Im}[S_{12}|_{IPT}] = \omega L_M I_1 I_2 \cos \theta_{12} \end{cases} \quad (4)$$

In an IPT coupler,  $P_{12}$  and  $Q_{12}$  are jointly determined by  $\omega$ ,  $L_M$ ,  $I_1$ ,  $I_2$  and  $\theta_{12}$ .  $P_{12}$  should be maximized to achieve effective power transfer while  $Q_{12}$  should be suppressed to reduce the Volt-Ampere (VA) rating and power loss. Namely, phase angle  $\theta_{12}$  should be as close to  $90^\circ$  as possible, which can be

Table V. Power transfer mechanism of IPT and CPT coupler.

Inductive coupler	Capacitive coupler
Power flow $S_{12} = V_{12} \cdot I_1^* = P_{12} + jQ_{12}$	Power flow $S_{12} = V_1 \cdot (-I_{12}^*) = P_{12} + jQ_{12}$
Reference phasor $I_2 = I_2 \angle 0^\circ, I_1 = I_1 \angle \theta_{12}$	Reference phasor $V_1 = V_1 \angle 0^\circ, V_2 = V_2 \angle \varphi_{21}$

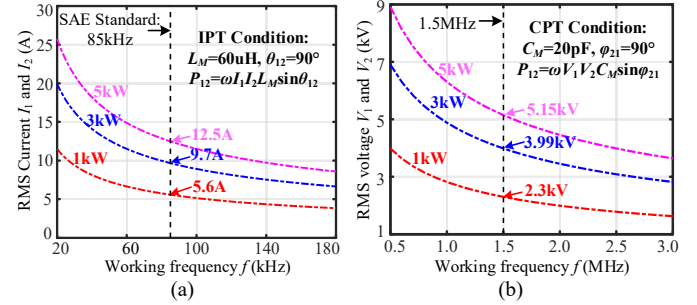


Fig.4 (a) IPT coil currents  $I_1$  and  $I_2$  vs. frequency  $f$  at specific power level; (b) CPT port voltage  $V_1$  and  $V_2$  vs. frequency  $f$  at specific power level. ( $I_1$  and  $I_2$ ,  $V_1$  and  $V_2$  are assumed to be the same, respectively.)

achieved by double-sided compensation capacitors.

In an IPT system, with a specified power level  $P_{12}$  and assuming identical current stress on primary and secondary coils, the coil currents  $I_1$  and  $I_2$  can be calculated by:

$$I_1 = I_2 = \sqrt{\frac{P_{12}}{\omega L_M \sin \theta_{12}}} \quad (5)$$

In practice, it is easy for an IPT coupler to achieve a mutual inductance  $L_M$  of tens of microhenry ( $\mu\text{H}$ ). For example, with  $L_M=60\mu\text{H}$  and  $\theta_{12}=90^\circ$ , the coil currents versus working frequency under a given power are provided in Fig. 4 (a). It shows that the IPT system can easily achieve several kW at 85kHz and tens of amperes.

#### 2) Capacitive Power Transfer

As shown in Table V, for a capacitive coupler, behavior-current sources  $I_{12}$  and  $I_{21}$  are introduced based on the  $y$ -parameters. Voltage  $V_1$  is considered as the reference phasor and the phase angle of  $V_2$  is represented by  $\varphi_{21}$ , namely:

$$V_2 = |V_2|(\cos \varphi_{21} + j \sin \varphi_{21}) \quad (6)$$

Then, in a CPT coupler, the power flow  $S_{12}$  is calculated as:

$$S_{12}|_{CPT} = V_1 \cdot (-I_{12}^*) = \omega C_M V_1 V_2 \sin \varphi_{21} + j \omega C_M V_1 V_2 \cos \varphi_{21} \quad (7)$$

$P_{12}$  and  $Q_{12}$  in a capacitive coupler are provided as:

$$\begin{cases} P_{12}|_{CPT} = \text{Re}[S_{12}|_{CPT}] = \omega C_M V_1 V_2 \sin \varphi_{21} \\ Q_{12}|_{CPT} = \text{Im}[S_{12}|_{CPT}] = \omega C_M V_1 V_2 \cos \varphi_{21} \end{cases} \quad (8)$$

In a CPT coupler,  $P_{12}$  and  $Q_{12}$  are determined by  $\omega$ ,  $C_M$ ,  $V_1$ ,  $V_2$ , and  $\varphi_{21}$ . Similar to an IPT coupler, to maximize  $P_{12}$  and minimize  $Q_{12}$ ,  $\varphi_{21}$  should be close to  $90^\circ$ , which can be achieved by using double-sided compensation inductors.

In a CPT system, with specified power level  $P_{12}$  and identical port voltages of  $V_1=V_2$ ,  $V_1$  and  $V_2$  can be calculated by:

$$V_1 = V_2 = \sqrt{\frac{P_{12}}{\omega C_M \sin \varphi_{21}}} \quad (9)$$

The capacitive coupling is usually much weaker than the

magnetic coupling. Typically, the coupling capacitance  $C_M$  in an air-based CPT coupler is only at the picofarad (pF) level. To reach an effective power transfer of kilowatts, the frequency  $f$  and voltages  $V_1$  and  $V_2$  generally need to achieve megahertz (MHz) and kilovolt (kV) levels, as shown in Fig.4 (b). For example, with  $C_M=20\text{pF}$  and  $f=1.5\text{MHz}$ , the voltages  $V_1$  and  $V_2$  must achieve 3.99kV to enable a 3kW power transfer.

Furthermore, in an IPT system, the voltages across the transmitter and receiver plates are respectively defined as  $V_{CM1}$  and  $V_{CM2}$ , which can be calculated by:

$$V_{CM1} = V_{CM2} = \frac{|V_1 - V_2|}{2} = \frac{\sqrt{V_1^2 + V_2^2 - 2V_1V_2 \cos \varphi_{21}}}{2} \quad (10)$$

Particularly, when  $V_1=V_2$  is achieved, with specified  $P_{12}$ ,  $\omega$ , and  $C_M$ , voltages  $V_{CM1}$  and  $V_{CM2}$  are provided below.

$$V_{CM1} = V_{CM2} = \sqrt{\frac{V_1V_2(1 - \cos \varphi_{21})}{2}} = \sqrt{\frac{P_{12}}{2\omega C_M} \cdot \tan \frac{\varphi_{21}}{2}} \quad (11)$$

#### D. Transfer Efficiency of IPT and CPT Couplers

In a real IPT or CPT system, the parasitic resistances of the coupler will cause power loss. Considering parasitic resistances, the IPT and CPT systems are modeled as Figs. 5 and 6. For an IPT coupler,  $R_{L1}$  and  $R_{L2}$  are series-modeled with  $L_1$  and  $L_2$  while in a CPT coupler,  $R_{C1}$  and  $R_{C2}$  are parallel-modeled with  $C_1$  and  $C_2$ . In addition, the equivalent load resistance is defined as  $R_{Le}$ .

##### 1) Transfer Efficiency of IPT Coupler

For an IPT coupler, the quality factors of inductors  $L_1$  and  $L_2$  are represented by  $Q_{L1}$  and  $Q_{L2}$ , defined as:

$$Q_{L1} = \omega L_1 / R_{L1}, \quad Q_{L2} = \omega L_2 / R_{L2} \quad (12)$$

Then, the transfer efficiency of an inductive coupler is calculated as:

$$\eta_{IPT} = \frac{I_2^2 R_{Le}}{I_1^2 R_{L1} + I_2^2 R_{L2} + I_2^2 R_{Le}} = \frac{1}{\frac{(R_{Le} + R_{L2})^2}{k_L^2 Q_{L1} Q_{L2} R_{L2} R_{Le}} + \frac{R_{L2} + 1}{R_{Le}}} \quad (13)$$

With  $a_L = R_{Le} / R_{L2}$ , (13) is simplified:

$$\eta_{IPT} = \frac{1}{1 + \frac{1}{a_L} + \frac{1}{k_L^2 Q_{L1} Q_{L2}} (a_L + \frac{1}{a_L} + 2)} \quad (14)$$

##### 2) Transfer Efficiency of CPT Coupler

For a CPT coupler, the quality factors are defined as:

$$Q_{C1} = \omega C_1 R_{C1}, \quad Q_{C2} = \omega C_2 R_{C2} \quad (15)$$

The transfer efficiency of a capacitive coupler is calculated:

$$\eta_{CPT} = \frac{V_2^2 / R_{Le}}{V_1^2 / R_{C1} + V_2^2 / R_{C2} + V_2^2 / R_{Le}} = \frac{1}{\frac{(R_{Le} + R_{C2})^2}{k_C^2 Q_{C1} Q_{C2} R_{C2} R_{Le}} + \frac{R_{Le} + 1}{R_{C2}}} \quad (16)$$

With  $a_C = R_{C2} / R_{Le}$ , (16) is simplified as:

$$\eta_{CPT} = \frac{1}{1 + \frac{1}{a_C} + \frac{1}{k_C^2 Q_{C1} Q_{C2}} (a_C + \frac{1}{a_C} + 2)} \quad (17)$$

From (14) and (17), the inductive and capacitive couplers have a unified expression of transfer efficiency, which is mainly determined by coupling coefficient, quality factors, and load condition. Furthermore, it is also noted that (14) and (17) are not limited to calculating the transfer efficiency of

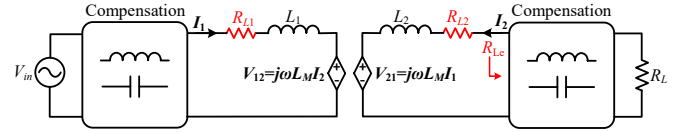


Fig.5. Coupler loss circuit model of an IPT system.

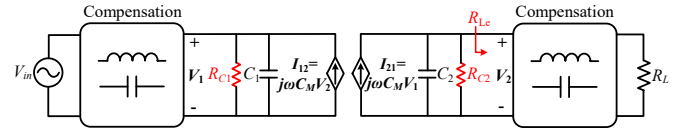


Fig.6. Coupler loss circuit model of a CPT system.

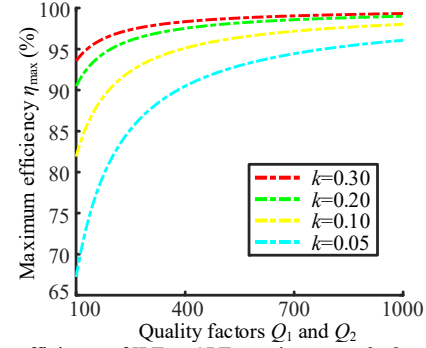


Fig.7. Transfer efficiency of IPT or CPT coupler versus  $k$ ,  $Q_1$  and  $Q_2$

inductive or capacitive coupler but are also suitable for estimating the efficiency of the entire IPT and CPT system [29], in which the quality factors of primary and secondary circuits will be used instead of the quality factors of the pure coupler.

##### 3) Maximum Efficiency Performance

A general form of the maximum efficiency for IPT and CPT couplers is provided in (18) when  $a_L = a_C = a_{max}$ , where  $k$ ,  $Q_1$ , and  $Q_2$  satisfy  $k = k_L = k_C$ ,  $Q_1 = Q_{L1} = Q_{C1}$ ,  $Q_2 = Q_{L2} = Q_{C2}$ .

$$\eta_{max} = \frac{k^2 Q_1 Q_2}{(1 + \sqrt{1 + k^2 Q_1 Q_2})^2}, \quad a_{max} = \sqrt{1 + k^2 Q_1 Q_2} \quad (18)$$

The theoretical maximum transfer efficiency of capacitive or inductive coupler versus coupling coefficient and quality factor is shown in Fig.7, which shows a positive relationship between  $k$  and  $Q_1/Q_2$  and can guide the system parameter design. For example, with estimated quality factors  $Q_1$  and  $Q_2$  of 400, to achieve an ac-ac efficiency of 95%, the coupling coefficient  $k$  can not be smaller than 0.1. Meantime, with  $k=0.2$  and  $Q_1=Q_2=300$ , the maximum efficiency can only achieve 96.7%.

## III. DUALITY BETWEEN BASIC IPT AND CPT COMPENSATIONS

### A. Comparison of Basic IPT and CPT Compensations

To achieve effective power transfer, double-sided compensation circuits are required to suppress the reactive power  $Q_{12}$ , making phase angle  $\theta_{12}$  or  $\varphi_{21}$  close to  $90^\circ$ . For both IPT and CPT couplers, there are four basic compensations, namely, SS, PP, SP, and PS, compared in Tables VI and VII.

Particularly,  $z$ ,  $y$ ,  $h$ , and  $g$ -parameters are respectively suitable for SS, PP, SP, and PS circuits. Then, in the equivalent circuit, inductors and capacitors construct either series or parallel LC tanks. With such a configuration, it is straightforward to conclude the resonance relationship of the circuit by making the series/parallel LC tanks fully resonate, facilitating the circuit resonance analysis.

Table VI Four basic IPT compensation circuits.

SS IPT Compensation [11]	PP IPT Compensation [12]	SP IPT Compensation [13]	PS IPT Compensation [14]
<b>Behavior-source circuit</b>			
<b>ZPA frequency</b>			
$\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1 - k_L^2)}} = \frac{1}{\sqrt{L_2 C_2 (1 - k_L^2)}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1 - k_L^2)}} = \frac{1}{\sqrt{L_2 C_2}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2 (1 - k_L^2)}}$
<b>Phase angle <math>\theta_{12}</math> at ZPA frequency</b>			
$\theta_{12} = 90^\circ$ ( $Q_{12} = 0$ )	$90^\circ < \theta_{12} < 180^\circ$	$90^\circ < \theta_{12} < 180^\circ$	$90^\circ < \theta_{12} < 180^\circ$
<b>Output Property at voltage source</b>			
$I_{out} = -V_{in} / (j\omega_0 L_M)$ (CC)	$I_{out} = V_{in} / [j\omega_0 L_M (1/k_L^2 - 1)]$ (CC)	$V_{out} = V_{in} \cdot L_2 / L_M$ (CV)	$V_{out} = V_{in} \cdot L_M / L_1$ (CV)
<b>Output Property at current source</b>			
$V_{out} = I_{in} j\omega_0 L_M$ (CV)	$V_{out} = -I_{in} \cdot j\omega_0 L_M (1/k_L^2 - 1)$ (CV)	$I_{out} = I_{in} \cdot L_M / L_2$ (CC)	$I_{out} = I_{in} \cdot L_1 / L_M$ (CC)

Table VII Four basic CPT compensation circuits.

SS CPT Compensation [15]	PP CPT Compensation [16]	SP CPT Compensation [17]	PS CPT Compensation [18]
<b>Behavior-source circuit</b>			
<b>ZPA frequency</b>			
$\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1 - k_C^2)}} = \frac{1}{\sqrt{L_2 C_2 (1 - k_C^2)}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2 (1 - k_C^2)}}$	$\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1 - k_C^2)}} = \frac{1}{\sqrt{L_2 C_2}}$
<b>Phase angle <math>\varphi_{21}</math> at ZPA</b>			
$0 < \varphi_{21} < 90^\circ$	$\varphi_{21} = 90^\circ$ ( $Q_{12} = 0$ )	$0 < \varphi_{21} < 90^\circ$	$0 < \varphi_{21} < 90^\circ$
<b>Output Property at voltage source</b>			
$I_{out} = -V_{in} j\omega_0 C_M (1/k_C^2 - 1)$ (CC)	$I_{out} = V_{in} \cdot j\omega_0 C_M$ (CC)	$V_{out} = V_{in} \cdot C_1 / C_M$ (CV)	$V_{out} = V_{in} \cdot C_M / C_2$ (CV)
<b>Output Property at current source</b>			
$V_{out} = I_{in} / [j\omega_0 C_M (1/k_C^2 - 1)]$ (CV)	$V_{out} = -I_{in} / (j\omega_0 C_M)$ (CV)	$I_{out} = I_{in} \cdot C_M / C_1$ (CC)	$I_{out} = I_{in} \cdot C_2 / C_M$ (CC)

### 1) SS Compensation

SS IPT/CPT compensation is compatible with the z-parameter modeling. At ZPA frequency, both SS IPT and CPT circuits realize the conversion between CC and CV properties. In an SS IPT circuit, the ZPA frequency is independent of  $k_L$  while in the SS CPT circuit, the ZPA frequency depends on  $k_C$ .

### 2) PP Compensation

PP IPT/CPT compensation is compatible with y-parameter modeling, and they can also achieve conversion between CC and CV properties. In a PP IPT circuit, ZPA frequency is related to  $k_L$ , while in a PP CPT circuit, ZPA frequency is independent of  $k_C$ .

### 3) SP Compensation

SP IPT/CPT compensation is compatible with the h-parameters. Both SP IPT and CPT circuits work as a step-up “transformer”, which can boost the output voltage. For an SP

IPT circuit, the conversion ratio is determined by  $L_2/L_M$ , while in an SP CPT circuit, the ratio is determined by  $C_2/C_M$ .

### 4) PS Compensation

PS IPT/CPT compensation is compatible with the g-parameters. Both SP IPT and CPT circuits work as a step-down “transformer”, which decreases the output. In a PS IPT circuit, the voltage conversion ratio is determined by  $L_M/L_1$  while in the PS CPT circuit, the ratio is determined by  $C_M/C_1$ .

According to (4) and (8), when  $\theta_{12}$  or  $\varphi_{21}$  achieves  $90^\circ$ , there is no reactive power circulation  $Q_{12}$  within coupler, which helps reduce power loss on the coupler and maximize the active power transfer  $P_{12}$ . In an IPT system,  $\theta_{21} = 90^\circ$  is only achievable in an SS compensation, which makes the SS IPT circuit the optimal one. In a CPT system,  $\varphi_{21} = 90^\circ$  is only achievable in a PP CPT compensation. However, in a PP CPT topology, the port voltages  $V_1$  and  $V_2$  are directly limited by the practical input and output voltages, which are generally in

hundreds of volts, resulting in a low power transfer capability. Therefore, in practice, a pure PP CPT circuit is rarely adopted.

### B. Duality Between Basic IPT and CPT Topologies

According to Tables VI and VII, the duality between basic IPT and CPT compensations exists in two aspects.

First, compensation circuit configuration. The SS, PP, SP, and PS CPT topologies respectively have identical compensation configuration, two-port modeling, load-independent output property, and inversion and rectification requirements as their IPT counterparts, namely SS, PP, SP, and PS ones. For example, both SS IPT and SS CPT configure the compensation component in series connection with the inductive/capacitive coupler, show compatibility with two-port z-parameter modeling, achieve load-independent CC output, and require voltage-source inverter (VSI) and voltage-source rectifier (VSR). Such duality can also be found in PP, SP, and PS-type IPT and CPT topologies. In summary, with the duality in compensation circuit configuration, the series (S) and parallel (P) compensation capacitors in an IPT circuit respectively correspond to the series (S) and parallel (P) compensation inductor in a CPT circuit.

Second, resonant relationship. In four basic IPT compensations, SS is considered the optimal one because its resonant frequency is independent of the coupling coefficient and there is no reactive power circulating in the inductive coupler in resonant conditions. In the CPT system, similar merits only exist in PP CPT compensation, not the SS one. From this perspective, PP CPT compensation is the counterpart of SS CPT. Similarly, PP, SP, and PS-type IPT compensations show similarity with SS, PS, and SP-type CPT circuits in the resonant relationship, respectively. Therefore, considering duality of resonance, the series (S) and parallel (P) compensation capacitors in an IPT circuit respectively correspond to the parallel (P) and series (S) compensation inductor in a CPT circuit.

In summary, CPT technology could be considered a reflection of IPT in a special “mirror”, hence the name “duality” between IPT and CPT systems in this paper. The duality between IPT and CPT compensations, qualitatively and quantitatively, is summarized in Tables VIII and IX. Each IPT topology can find two counterparts of the CPT field in terms of compensation circuit configuration and resonant relationship, helping explore potential CPT circuits.

Table VIII Duality between SS- and PP-type IPT and CPT compensations.

CPT Topology	Series-Series CPT	Parallel-Parallel CPT
IPT Topology		
<b>Series-Series IPT</b>	<p><b>Similarity in compensation circuit configuration</b></p> <ul style="list-style-type: none"> <li>• Double-sided series compensation circuit</li> <li>• Two-port z-parameter modeling</li> <li>• Load-independent CC output</li> <li>• VSI and VSR required (1)</li> </ul>	<p><b>Similarity in resonant relationship</b></p> <ul style="list-style-type: none"> <li>• <math>k</math>-independent resonance: <math>\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2}}</math></li> <li>• Zero reactive power flow <math>Q_{12}=0</math> (<math>\theta_{12}=\varphi_{12}=90^\circ</math>)</li> <li>• <math>L_M</math> and <math>C_M</math>-dependent output: <math>\begin{cases} I_{out} _{SS-IPT} = j \cdot V_{in} / \omega L_M \\ I_{out} _{PP-CPT} = j \cdot V_{in} \omega C_M \end{cases}</math></li> </ul>
<b>Parallel-Parallel IPT</b>	<p><b>Similarity in resonant relationship</b></p> <ul style="list-style-type: none"> <li>• <math>k</math>-dependent resonance: <math>\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1-k^2)}} = \frac{1}{\sqrt{L_2 C_2 (1-k^2)}}</math></li> <li>• Non-zero reactive power flow <math>Q_{12} \neq 0</math></li> <li>• CC output expression: <math>\begin{cases} I_{out} _{PP-IPT} = I_{out} _{PP-CPT} \div (1-1/k^2) \\ I_{out} _{SS-CPT} = I_{out} _{PP-CPT} \times (1-1/k^2) \end{cases}</math></li> </ul>	<p><b>Similarity in compensation circuit configuration</b></p> <ul style="list-style-type: none"> <li>• Double-sided parallel compensation circuit</li> <li>• Two-port y-parameter modeling</li> <li>• Load-independent CC output</li> <li>• CSI and CSR required (2)</li> </ul>

(1) VSI: voltage-source inverter; VSR: voltage-source rectifier; (2) CSI: Current-source inverter; CSR: Current-source rectifier

Table IX Duality between SP- and PS-type IPT and CPT compensations.

CPT Topology	Series-Parallel CPT	Parallel-Series CPT
IPT Topology		
<b>Series-Parallel IPT</b>	<p><b>Similarity in compensation circuit configuration</b></p> <ul style="list-style-type: none"> <li>• Primary series and secondary parallel compensation circuit</li> <li>• Two-port g-parameter modeling</li> <li>• Load-independent step-up CV output</li> <li>• VSI and CSR required</li> </ul>	<p><b>Similarity in resonant relationship</b></p> <ul style="list-style-type: none"> <li>• <math>k</math>-independent resonance: <math>\omega_0 = \frac{1}{\sqrt{L_1 C_1 (1-k^2)}} = \frac{1}{\sqrt{L_2 C_2}}</math></li> <li>• Non-zero reactive power flow <math>Q_{12} \neq 0</math></li> <li>• <math>L_1</math> and <math>C_1</math>-independent output: <math>\begin{cases} V_{out} _{SP-IPT} = V_{in} \cdot L_2 / L_M \\ V_{out} _{PS-CPT} = V_{in} \cdot C_M / C_2 \end{cases}</math></li> </ul>
<b>Parallel-Series IPT</b>	<p><b>Similarity in resonant relationship</b></p> <ul style="list-style-type: none"> <li>• <math>k</math>-dependent resonance: <math>\omega_0 = \frac{1}{\sqrt{L_1 C_1}} = \frac{1}{\sqrt{L_2 C_2 (1-k^2)}}</math></li> <li>• Non-zero reactive power flow <math>Q_{12} \neq 0</math></li> <li>• <math>L_2</math> and <math>C_2</math>-independent output: <math>\begin{cases} V_{out} _{PS-IPT} = V_{in} \cdot L_M / L_1 \\ V_{out} _{SP-CPT} = V_{in} \cdot C_1 / C_M \end{cases}</math></li> </ul>	<p><b>Similarity in compensation circuit configuration</b></p> <ul style="list-style-type: none"> <li>• Primary parallel and secondary series compensation circuit</li> <li>• Two-port h-parameter modeling</li> <li>• Load-independent step-down CV output</li> <li>• CSI and VSR required</li> </ul>

#### IV. EXPLORATION OF CPT OPPORTUNITIES BASED ON DUALITY WITH MAINSTREAM IPT CIRCUITS

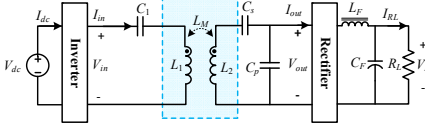
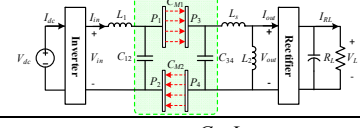
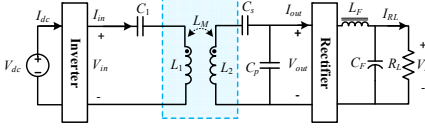
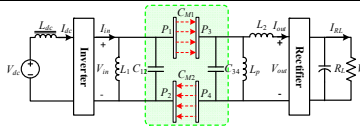
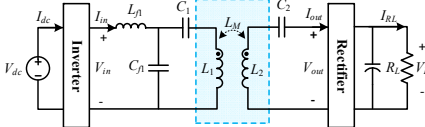
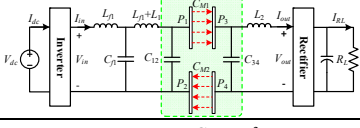
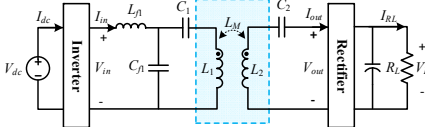
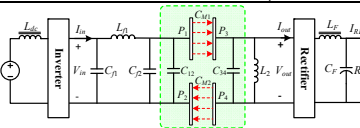
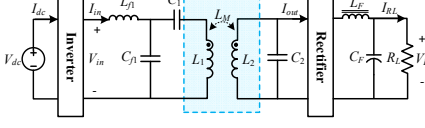
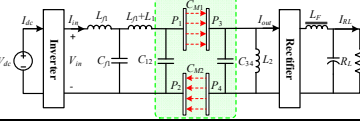
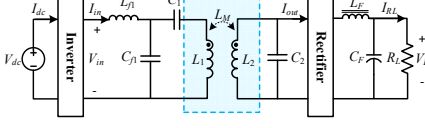
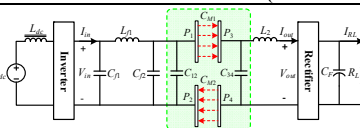
##### A. Exploration of CPT Opportunities

According to the aforementioned duality investigation, for any IPT topology, it is accessible to find two CPT counterparts based on the duality of compensation configuration and resonant relationship. IPT technology has become very mature after development of over 100 years. According to the literature, apart from the 4 basic IPT topologies (SS, PP, SP, and PS), 7 higher-order IPT compensations, S-SP, LCC-S, LCC-P, LCC-SP, LCC-LCC, three-coil, and four-coil [30]-[36], are most commonly researched and used, which can be considered as the optimal IPT circuit candidates. Based on the

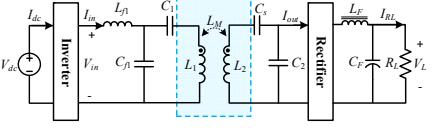
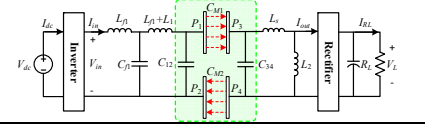
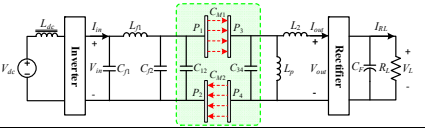
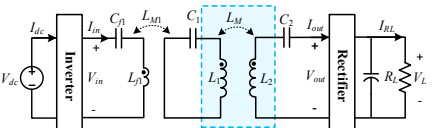
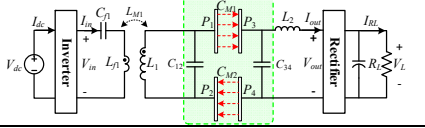
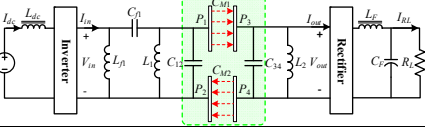
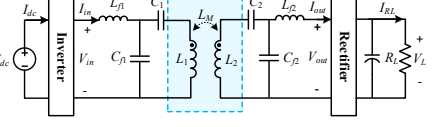
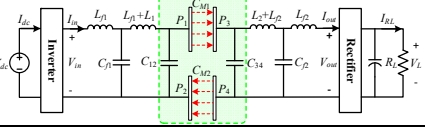
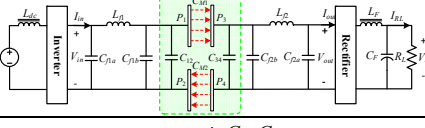
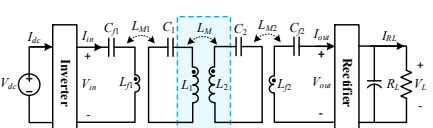
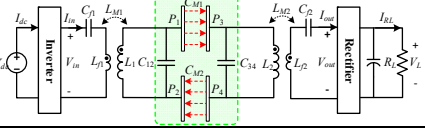
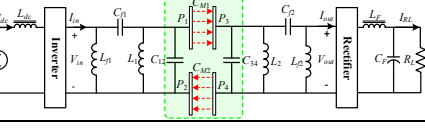
duality with the existing 7 optimal IPT circuits, 14 CPT topologies are derived, which possibly have good performance as well. Among these 14 CPT circuits, 3 have been reported in [25]-[27], namely, *LCL-S*, *LCL-LCL*, and *M<sub>1</sub>-SS-M<sub>2</sub>* CPT circuits, which are the counterparts of LCC-LCC, LCC-S, and four-coils IPT circuits; however, the rest are not and are explored in detail as the following, and the comparison between IPT circuits and their counterparts are provided in Table X.

1) *Duality with S-SP IPT Circuit*: The S-SP compensated IPT [30] circuit is developed from the basic SP compensation. With an additional series capacitor at the secondary side, an S-SP IPT circuit can be designed in either voltage step-up or -down mode, achieving more flexible control of output voltage.

Table X. CPT Circuit Prediction based on the duality with IPT circuit.

Existing IPT Topology	Resonance	CPT Counterpart	Resonance
<b>1.0 S-SP IPT Circuit [30]</b>			
	$\begin{cases} L_2^* = L_2 - 1/(\omega^2 C_s) \\ \omega^2 (L_1 - \frac{L_M^2}{L_2}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} L_2^* = L_2 + L_s \\ \frac{\omega^2 L_1 C_1 \cdot (1-k_c^2)}{1 - (L_2/L_2) \cdot k_c^2} = 1 \\ \omega^2 L_2 C_2 (1-k_c^2) = 1 \end{cases}$
		<p>CV output: <math>V_{out} = V_{in} \cdot \frac{C_1}{C_M} \cdot \frac{L_2}{L_2} \quad (\varphi_{21} &lt; 90^\circ)</math></p>	
<b>1.2 P-PS CPT Circuit (New)</b>			
	$\begin{cases} L_2^* = L_2 - 1/(\omega^2 C_s) \\ \omega^2 (L_1 - \frac{L_M^2}{L_2}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} C_2^* = C_2 - 1/(\omega^2 L_p) \\ \omega^2 (C_1 - \frac{C_M^2}{C_2}) L_1 = 1 \\ \omega^2 L_2 C_2^* = 1 \end{cases}$
		<p>CV output: <math>V_{out} = V_{in} \cdot \frac{L_2}{L_M}</math></p>	
<b>2.0 LCC-S IPT Circuit (LCL-S/S Compensation) [31]</b>			
	$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 (L_1 - L_{f1}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_1 C_1 (1-k_c^2) = 1 \\ \omega^2 L_2 C_2 (1-k_c^2) = 1 \end{cases}$
		<p>CV output: <math>V_{out} = V_{in} \cdot \frac{L_M}{L_{f1}}</math></p>	
<b>2.2 CLC-P CPT Circuit (CLC-P/P Compensation) (New)</b>			
	$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 (L_1 - L_{f1}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_2 C_2 = 1 \\ C_{f2} = C_{f1} - C_1 \end{cases}$
		<p>CV output: <math>V_{out} = V_{in} \cdot \frac{L_M}{L_{f1}}</math></p>	
<b>3.0 LCC-P IPT Circuit (LCL-S/P Compensation) [32]</b>			
	$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 (L_1 - L_{f1} - \frac{L_M^2}{L_2}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_1 C_1 = 1 \\ \omega^2 L_2 C_2 (1-k_c^2) = 1 \end{cases}$
		<p>CC output: <math>I_{out} = -V_{in} j \omega C_{f1} \cdot \frac{C_M}{C_1} \quad (\varphi_{21} &lt; 90^\circ)</math></p>	
<b>3.2 CLC-S CPT Circuit (CLC-P/S Compensation) (New)</b>			
	$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 (L_1 - L_{f1} - \frac{L_M^2}{L_2}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}$		$\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_2 C_2 = 1 \\ C_{f2} = C_{f1} - C_1 (1-k_c^2) \end{cases}$
		<p>CC output: <math>I_{out} = -V_{in} j \omega C_{f1} \cdot \frac{C_2}{C_M} \quad (\varphi_{21} &lt; 90^\circ)</math></p>	

Continuous next page

<p><b>4.0 LCC-SP IPT Circuit (LCL-S/SP Compensation) [33]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ L_2 = L_2 - 1/(\omega^2 C_s) \\ \omega^2 (L_1 - L_{f1} - \frac{L_M^2}{L_2}) C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = \frac{V_{in}}{j\omega L_{f1}} \cdot \frac{L_M}{L_2^*}</math></p>	<p><b>4.1 LCL-SP CPT Circuit (LCL-S/SP Compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ L_2 = L_2 + L_s \\ \frac{\omega^2 L_1 C_1 \cdot (1 - k_c^2)}{1 - (L_s/L_2) \cdot k_c^2} = 1 \\ \omega^2 L_2 C_2 (1 - k_c^2) = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = -V_{in} j\omega C_{f1} \cdot \frac{C_M}{C_1} \cdot \frac{L_2^*}{L_2} \quad (\varphi_{21} &lt; 90^\circ)</math></p> <p><b>4.2 CLC-PS CPT Circuit (CLC-P/PS Compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ C_2^* = C_2 - 1/(\omega^2 L_p) \\ \omega^2 L_2 C_2^* = 1 \\ C_{f2} = C_{f1} - (C_1 - \frac{C_M^2}{C_2}) \end{cases}</math> </p> <p>CC output: <math>I_{out} = -V_{in} j\omega C_{f1} \cdot \frac{C_2}{C_M} \quad (\varphi_{21} &lt; 90^\circ)</math></p>
<p><b>5.0 Three-Coil IPT Circuit (M1-S/S Compensation) [34]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_1 C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}</math> </p> <p>CV output: <math>V_{out} = V_{in} \frac{L_M}{L_{M1}} \quad (Q_{12}=0)</math></p>	<p><b>5.1 M1-SS CPT Circuit (M1-S/S Compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_1 C_1 (1 - k_c^2) = 1 \\ \omega^2 L_2 C_2 (1 - k_c^2) = 1 \end{cases}</math> </p> <p>CV output: <math>V_{out} = \frac{V_{in}}{\omega^2 L_{M1} C_M (1/k_c^2 - 1)} = V_{in} \frac{L_1}{L_{M1}} \frac{C_M}{C_2} \quad (\varphi_{21} &lt; 90^\circ)</math></p> <p><b>5.2 LCL-P CPT Circuit (M1-P/P Compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_1 (C_1 + C_{f1}) = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}</math> </p> <p>CV output: <math>V_{out} = -V_{in} \frac{C_{f1}}{C_M} \quad (\varphi_{21} = 90^\circ)</math></p>
<p><b>6.0 LCC-LCC IPT Circuit (LCL-S/S-LCL compensation) [35]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_{f2} C_{f2} = 1 \\ \omega^2 (L_1 - L_{f1}) C_1 = 1 \\ \omega^2 (L_2 - L_{f2}) C_2 = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = \frac{V_{in} L_M}{j\omega L_{f1} L_{f2}} \quad (Q_{12}=0)</math></p>	<p><b>6.1 LCL-LCL CPT Circuit (LCL-S/S-LCL compensation) [26]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_{f2} C_{f2} = 1 \\ \omega^2 L_1 C_1 (1 - k_c^2) = 1 \\ \omega^2 L_2 C_2 (1 - k_c^2) = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = V_{in} \cdot \frac{j\omega C_{f1} C_{f2}}{C_M} \cdot \frac{k_c^2}{1 - k_c^2} \quad (\varphi_{21} &lt; 90^\circ)</math></p> <p><b>6.2 CLC-CLC CPT Circuit (CLC-P/P-CLC compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1a} = 1 \\ \omega^2 L_{f2} C_{f2a} = 1 \\ C_{f1b} = C_{f1a} - C_1 \\ C_{f2b} = C_{f2a} - C_2 \end{cases}</math> </p> <p>CC output: <math>I_{out} = -V_{in} \frac{j\omega C_{f1a} C_{f2a}}{C_M} \quad (\varphi_{21} = 90^\circ)</math></p>
<p><b>7.0 Four-Coil IPT Circuit (M1-S/S-M2 Compensation) [36]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_{f2} C_{f2} = 1 \\ \omega^2 L_1 C_1 = 1 \\ \omega^2 L_2 C_2 = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = \frac{V_{in} L_M}{j\omega L_{M1} L_{M2}} \quad (Q_{12}=0)</math></p>	<p><b>7.1 M1-SS-M2 CPT circuit (M1-S/S-M2 Compensation) [27]</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_{f2} C_{f2} = 1 \\ \omega^2 L_1 C_1 (1 - k_c^2) = 1 \\ \omega^2 L_2 C_2 (1 - k_c^2) = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = \frac{-V_{in}}{j\omega^3 L_{M1} L_{M2} C_M} \cdot \frac{k_c^2}{1 - k_c^2} \quad (\varphi_{21} &lt; 90^\circ)</math></p> <p><b>7.2 LCL-PP-LCL CPT Circuit (LCL-P/P-LCL Compensation) (New)</b></p>  <p> <math display="block">\begin{cases} \omega^2 L_{f1} C_{f1} = 1 \\ \omega^2 L_{f2} C_{f2} = 1 \\ \omega^2 L_1 (C_1 + C_{f1}) = 1 \\ \omega^2 L_2 (C_2 + C_{f2}) = 1 \end{cases}</math> </p> <p>CC output: <math>I_{out} = -V_{in} \frac{j\omega C_{f1} C_{f2}}{C_M} \quad (\varphi_{21} = 90^\circ)</math></p>



Considering the duality in circuit structure, an S-SP compensated CPT circuit is proposed, shown as case 1.1 in Table X. Compared to the basic SP CPT circuit, one more compensation inductor is used, however, the total net inductance on the secondary side does not increase. Meantime, it can also be designed in voltage step-up or -down mode.

Considering the duality in the resonant relationship, a *P-PS* compensated CPT circuit is proposed with flexible voltage step-down/up output, shown as case 1.2 in Table X. However, according to the resonant relationship, in the *P-PS* CPT circuit, the secondary-side net inductance increases compared to a *PS* CPT circuit, which is a drawback.

2) *Duality with LCC-S IPT Circuit*: The *LCC-S* IPT circuit [31] is equivalent to a combination of a primary-side T-type *LCL* network and an SS IPT compensation. The second inductor of the *LCL* network is canceled by the series capacitor of the SS circuit, resulting in an *LCC-S* IPT system. *LCC-S* is a classic IPT topology, which achieves constant transmitting current, load-independent CV output, and zero reactive power circulation in the magnetic coupler with a compact receiver.

Considering the duality of circuit configuration with *LCC-S* IPT, the *LCL-S* CPT circuit is developed, shown as case 2.1 in Table X. It can achieve load-independent CV output with a compact receiver circuit, which has been reported in [25].

Considering the resonant relationship, the SS IPT is in duality with *PP* CPT. Similarly, the T-type *LCL* network should be in duality with a  $\Pi$ -type *CLC* network [37]. Therefore, a *CLC-P* CPT circuit is developed as case 2.2 in Table X, in which the second capacitor of the  $\Pi$ -type *CLC* network cancels the primary compensation inductor of the *PP* CPT circuit. For the *CLC-P* CPT circuit, zero reactive power circulation ( $Q_{12}=0$ ) is achieved, and only two resonant inductors are required. However, the secondary port voltage  $V_2$  of the coupler is limited by the load voltage, which is adverse for high power transfer. Besides, the *CLC-P* CPT circuit requires a current-source inverter.

3) *Duality with LCC-P IPT Circuit*: The *LCC-P* IPT circuit [32] can be considered as a combination of a T-type *LCL* network and a basic SP IPT circuit. The secondary inductor of the *LCL* network is canceled by the series capacitor of an SP IPT circuit. It achieves CC output with a compact receiver.

Considering the duality, *LCL-P* and *CLC-S* CPT circuits are respectively developed with CC output, shown in cases 3.1 and 3.2 in Table X. For the *LCL-P* CPT circuit, port voltage  $V_2$  of the capacitive coupler is limited by the load voltage, which is adverse for high power transfer. In comparison, the *CLC-S* CPT circuit uses fewer resonant inductors and overcomes the drawback of the *LCL-P* CPT circuit.

4) *Duality with LCC-SP IPT Circuit*: The *LCC-SP* IPT circuit [33] is an improved version of the *LCC-P* IPT circuit, using an additional series capacitor at the secondary side to achieve more design flexibility.

Considering the duality, *LCL-SP* and *CLC-PS* CPT circuits are respectively developed, shown in cases 4.1 and 4.2. The *LCL-SP* CPT circuit is an improved version of the *LCL-P* CPT circuit (case 3.1), which can boost the secondary port voltage  $V_2$  without increasing the secondary net inductance. In contrast, the *CLC-PS* circuit does not improve when compared to the *CLC-S* CPT circuit (case 3.2).

5) *Duality with Three-Coil IPT Circuit*: In the three-coil IPT circuit [34], a mutually coupled magnetic-link is used at the primary side, which works as a CC excitation for the followed SS CPT circuit. In this case, a CV output property is achieved when neglecting the cross-coupling.

Considering the duality in circuit configuration, an  $M_1$ -SS CPT circuit is developed, shown as case 6.1. Considering the resonant relationship, the SS mutually coupled magnetic-link is in duality with the  $\Pi$ -type *LCL* network [37]. Hence the *LCL-PP* CPT circuit is developed as case 6.2. Similarly, in the *LCL-PP* CPT circuit, the coupler port voltage  $V_2$  is limited by load voltage, which is adverse for high power transfer.

6) *Duality with LCC-LCC IPT Circuit*: *LCC-LCC* IPT circuit [35] is one of the most classic topologies, which is equivalent to the combination of a double-side T-type *LCL* network and an SS IPT compensation. It achieves CC output, constant transmitting current, and zero reactive power circulation.

Considering the duality, *LCL-LCL* and *CLC-CLC* CPT circuits are respectively developed. The *LCL-LCL* CPT circuit has been validated to achieve a high power of 2.4kW with over 90% efficiency [26]. In comparison, the newly proposed *CLC-CLC* CPT topology requires fewer resonant inductors. Meantime, the property of zero reactive power circulation potentially helps to further improve system efficiency. The *CLC-CLC* CPT circuit requires the current-source inverter and rectifier.

7) *Duality with Four-Coil IPT Circuit*: The four-coil IPT circuit [36] uses two additional mutually coupled magnetic links on double sides, which have a similar function to a T-type *LCL/CLC* network. The main coupling is designed as an SS circuit. Neglecting cross-couplings, CC output is achieved.

Considering the duality in circuit configuration, the  $M_1$ -SS- $M_2$  and *LCL-PP-LCL* CPT circuits are respectively developed as cases 7.1 and 7.2.  $M_1$ -SS- $M_2$  CPT circuit has been validated in [27], which achieves a high power of 3kW and an efficiency of up to 95.7%. In comparison, the newly proposed *LCL-PP-LCL* CPT circuit can achieve zero reactive power circulation in the capacitive coupler, which is a potential merit.

## B. Evaluation of Developed CPT Circuits

Based on the duality investigation with 7 mainstream higher-order IPT circuits, 14 CPT circuits are developed. Particularly, 11 of these 14 CPT circuits are newly proposed in this paper. Table X marks all 14 circuits and indicates the ones already in literature and the ones explored in this paper.

In comparison, the four basic CPT topologies, SS, PP, SP and PS, have the simplest circuit structure and are more suitable for low-power applications. However, the newly developed 14 high-order CPT circuits tend to achieve more design flexibility and freedom for high power transfer capability and load-independent CC or CV output property, which can be selectively used for different scenarios. For example, the newly proposed *S-SP* CPT circuit permits a more flexible CV output design (either step-up or step-down) than the basic SP CPT that can only achieve voltage step-up. Besides, in the *LCL-LCL* CPT circuit, with the double-side *LCL* networks, additional two variables  $C_{f1}$  and  $C_{f2}$  are introduced, which can be leveraged to increase the system power level, meaning higher design flexibility. Table XI provides a summary and evaluation of the developed 14 CPT circuits in terms of inver-

Table XI Summary and evaluation of the derived 14 high-order CPT circuits.

CPT Circuit	Inverter and Rectifier	Compensation Inductor Num.	Compensation Capacitor Num.	Output Property	Circuit Simplicity	Power Transfer Capability	Recommendation
1.1 <i>S-SP</i> CPT	VSI, VSR	3	0	CV	★★★★	Low	✓
1.2 <i>P-PS</i> CPT	CSI, VSR	3	0	CV	★★★★☆	Low	✗
2.1 <i>LCL-S</i> CPT [25]	VSI, VSR	3	1	CV	★★★	Medium	✓
2.2 <i>CLC-P</i> CPT	CSI, CSR	2	1	CV	★★★	Low	✗
3.1 <i>LCL-P</i> CPT	VSI, CSR	3	1	CC	★★★	Low	✗
3.2 <i>CLC-S</i> CPT	CSI, VSR	2	2	CC	★★★	Medium	✓
4.1 <i>LCL-SP</i> CPT	VSI, VSR	4	1	CC	★★☆	Medium	✓
4.2 <i>CLC-PS</i> CPT	CSI, VSR	3	2	CC	★★☆	Medium	✓
5.1 <i>M<sub>1</sub>-SS</i> CPT	VSI, VSR	3	2	CV	★★★	Medium	✓
5.2 <i>LCL-P</i> CPT	CSI, CSR	3	2	CV	★★☆	Low	✗
6.1 <i>LCL-LCL</i> CPT [26]	VSI, VSR	4	2	CC	★★	High	✓
6.2 <i>CLC-CLC</i> CPT	CSI, CSR	2	4	CC	★★	High	✓
7.1 <i>M<sub>1</sub>-SS-M<sub>2</sub></i> CPT [27]	VSI, VSR	4	2	CC	★★	High	✓
7.2 <i>LCL-PP-LCL</i> CPT	CSI, CSR	4	2	CC	★★	High	✓

sion and rectification design, the number of compensation components, output property, circuit simplicity, and power transfer capability.

Compared to basic CPT compensations, the *S-SP* and *P-PS* CPT circuits use only one more inductor on the secondary side to achieve a more flexible output voltage, which has a relatively compact system size and low power transfer capability. However, the *P-PS* CPT circuit requires larger secondary-side inductance than the *S-SP* circuit, and therefore, is not recommended.

For the CPT circuits of cases 2.1~5.2 in Table XI, a T-type *LCL* or  $\Pi$ -type *CLC* network is used in the primary side when compared to the basic CPT circuits, which introduces additional design degrees of freedom for improving power transfer capability without significantly increasing the complexity of the secondary circuit. There are exceptions, however. For example, in the *CLC-P*, *LCL-P*, and *LCL-P* CPT circuits, the port voltage  $V_2$  of the capacitive coupler will be limited by the load voltage to hundreds of volts, which is adverse for high power transfer. Therefore, these circuits are not recommended.

For the CPT circuits of cases 6.1~7.2, double-sided T-type *LCL* or  $\Pi$ -type *CLC* networks are used, which introduces two more design degrees for a high power transfer capability at the cost of increased circuit complexity, which are mainly expected to be applied to high-power scenarios.

In summary, compared to the 4 basic CPT circuits, some of the new circuits clearly show 1) potentials of flexible output, such as *S-SP*; 2) trade-off between circuit simplicity and power transfer capability, such as *LCL-S*, and *M<sub>1</sub>-SS*; and 3) high power transfer capability, such as *M<sub>1</sub>-SS-M<sub>2</sub>*, and *LCL-LCL* which can be selectively used in various scenarios, such as electric vehicle charging, underwater capacitive power transfer, etc.

## V. CASE STUDY WITH EXPERIMENT VALIDATION

### A. Validation from the Existing Work

Based on the presented duality analysis, 14 CPT topologies are derived from 7 mainstream IPT circuits. Their performance in terms of resonant relationship, output property, and output power expressions are predicted. To validate the demonstrated duality analysis, the convincing approach is to

experimentally verify the performance of the newly proposed CPT circuits with the prediction.

Among these 14 CPT circuits, the *LCL-S*, *LCL-LCL*, and *M<sub>1</sub>-SS-M<sub>2</sub>* topologies have been respectively reported and investigated in [25], [26], and [27]. The existing research shows that the *LCL-S*, *LCL-LCL*, and *M<sub>1</sub>-SS-M<sub>2</sub>* CPT circuits respectively achieve load-independent CV, CC, and CC output property. The resonant relationship and output power expressions are the same as predicted in this paper, which can validate the effectiveness of the proposed duality investigation in exploring high-performance CPT circuits.

### B. Case Study of *M<sub>1</sub>-SS* CPT Circuit

Beyond the existing related research, in this paper the *M<sub>1</sub>-SS* CPT circuit (case 5.1), which uses a mutually coupling magnetic link on the primary side to improve the power transfer capability and only uses one inductor on the secondary side to achieve a compact receiver, is implemented to further validate the revealed duality between IPT and CPT systems.

The simplified *M<sub>1</sub>-SS* CPT circuit is shown in Fig. 8.  $C_{M1}$  and  $C_{M2}$  are the main coupled capacitances while  $C_{12}$  and  $C_{34}$  are the parasitic shunt capacitance of the capacitive coupler.  $C_{ex1}$  and  $C_{ex2}$  are external capacitances. The coupler is described as:

$$\begin{cases} C_M = C_{M1} \cdot C_{M2} / (C_{M1} + C_{M2}) \\ C_1 = C_{ex1} + C_{12} + C_M, \quad C_2 = C_{ex2} + C_{34} + C_M \end{cases} \quad (19)$$

$z$ -parameter is used to simplify the system. The equivalent circuit is provided in Fig. 9, and resonant relationship satisfies

$$\omega = \frac{1}{\sqrt{L_{f1} C_{f1}}} = \frac{1}{\sqrt{L_1 C_1 (1 - k_c^2)}} = \frac{1}{\sqrt{L_2 C_2 (1 - k_c^2)}} \quad (20)$$

Based on the circuit, the voltage relationship is described as

$$\begin{cases} V_{in} = I_{in} \cdot (j\omega L_{f1} + \frac{1}{j\omega C_{f1}}) - I_{L1} j\omega L_{M1} \\ V_{out} = I_{L1} \frac{1}{j\omega C_M (1/k_c^2 - 1)} - I_{out} [j\omega L_2 + \frac{1}{j\omega C_2 (1 - k_c^2)}] \end{cases} \quad (21)$$

The current  $I_{L1}$  is given below, which is independent of load, namely a CC excitation for the followed SS CPT circuit.

$$I_{L1} = -V_{in} / j\omega L_{M1} \quad (22)$$

The output voltage of the *M<sub>1</sub>-SS* CPT is provided as

$$V_{out} = \frac{V_{in}}{\omega^2 L_{M1} C_M (1/k_c^2 - 1)} = V_{in} \frac{L_1}{L_{M1}} \frac{C_M}{C_2} \quad (23)$$

### C. 2.1kW 3MHz CPT Experiment

A 2.1kW CPT hardware prototype is implemented as shown in Fig. 10. A sleeve-type capacitive coupler is used, which can be usable in rotary applications [38]. With an air gap of 8mm,  $C_{M1}$  and  $C_{M2}$  achieve 50pF. A high frequency of 3MHz is selected. Silicon carbide MOSFET C3M0120100K is used to design the inverter, and 3000-strand AWG46 Litz wire is used to fabricate inductors. It is noted that in the implemented CPT system, the rectifier is not used. Multiple 2Ω/140W non-inductive resistors of OHMITE THE140 Series are connected as a high-power load. The system parameters are provided in Table XII.

With  $V_{dc}=300V$ ,  $f=3MHz$ , and  $R=40\Omega$ , the output power achieves 2.1kW and the experimental waveforms are provided in Fig. 11. The output voltage  $V_{out}$  is almost in phase with the input voltage  $V_{in}$ . Besides, the input current  $I_{in}$  only slightly lags  $V_{in}$  in phase, showing a ZPA property as well as zero-voltage-switching (ZVS), which reduces the switching loss.

The output voltage  $V_{out}$  and efficiency are provided in Fig. 12. When the power increases by 250% from 606W to 2122W, the output voltage only experiences a small decrease of 9.7% from 327.4V to 295.6V, validating the constant-voltage (CV) output. The small voltage fluctuation is attributed to the parasitic circuit resistance and the slight detuning for ZVS. The maximum efficiency reaches 93.19% at 755W and an efficiency of 89.8% is achieved at 2122W.

In this work, the purpose is to validate the feasibility of using the IPT-CPT duality for higher-order CPT exploration. In future work, high-quality components can be used to improve efficiency, and a high-frequency rectification stage will be implemented to achieve a dc output.

## VI. CONCLUSION

This paper comparatively investigates the duality between CPT and IPT technologies, aiming at exploring the full suite of potential CPT opportunities not yet reported in the literature. The CPT and IPT systems are systematically compared in terms of modeling, power transfer mechanism, compensation circuit, resonant relationship, and power and efficiency. A generic two-port modeling method is developed, and unified power transfer and efficiency expressions are derived. The duality is demonstrated in aspects of compensation circuit configuration and resonant relationship. 14 CPT topologies are discovered in duality with 7 mainstream IPT circuits, of which 11 CPT circuits are not reported in the literature. Detailed comparison and evaluation of the developed 14 CPT circuits are conducted, and high-performance circuits are recommended. As a case study, a 2.1kW 3MHz CPT system is implemented in hardware based on the newly proposed  $M_1$ -SS CPT circuit which shows consistency with the predicted circuit properties of load-independent CV output, and ZPA property with a peak efficiency of 93.19%. The demonstrated experimental result and the existing research work in [25]-[27] jointly validate the proposed duality analysis. Design and hardware demonstration for the other theoretically-feasible CPT circuits is beyond the scope of the paper. However, this work paves a pathway for future researchers in this direction.

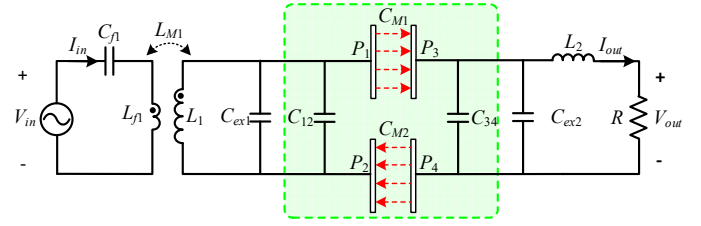


Fig. 8 Circuit topology of  $M_1$ -SS CPT system.

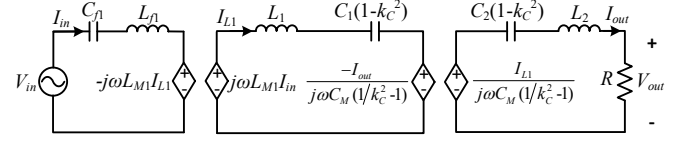


Fig. 9 Equivalent circuit of  $M_1$ -SS CPT system based on z-parameter modeling.

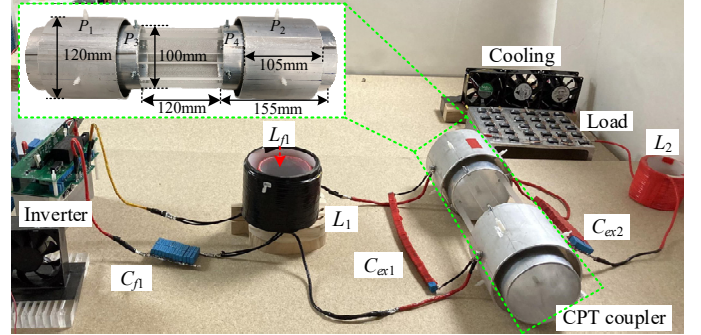


Fig. 10 Implemented 2.1kW CPT prototype.

Table XII. Parameters of the implemented CPT prototype.

Parameter	Value	Parameter	Value
$V_{dc}$	300 V	$f$	3 MHz
$L_{l1}$	4.8 $\mu$ H	$C_{l1}$	663.9 pF
$L_1$	70.0 $\mu$ H	$C_{ex1}+C_{12}$	20.5 pF
$L_2$	27.0 $\mu$ H	$C_{ex2}+C_{34}$	93.0 pF
$L_{M1}$	13.6 $\mu$ H	$C_{M1}, C_{M2}$	50.0 pF
$C_1$	45.5 pF	$C_2$	118.0 pF
$C_M$	25.0 pF	$k_c$	0.34
Air gap	8 mm	Voltage gain $G_V$	1.09

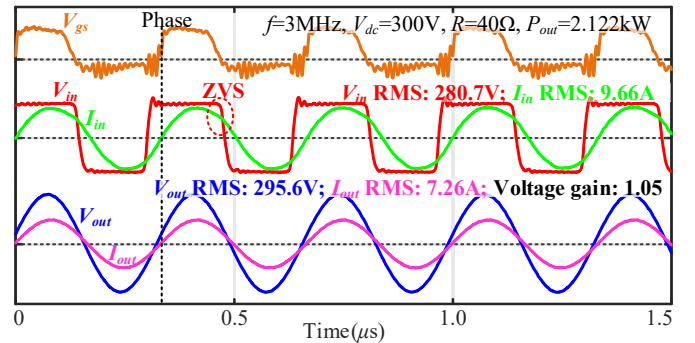


Fig. 11 Experimental waveforms at 2.122kW and 3MHz.

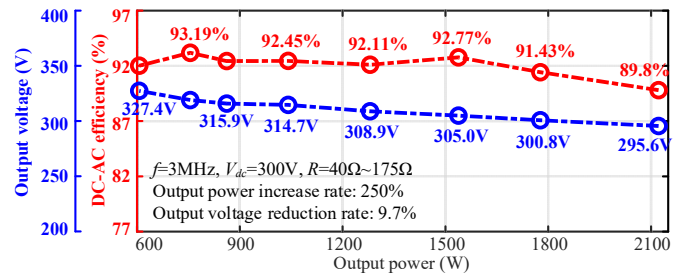


Fig. 12 Output voltage and efficiency versus power.

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