

# CS271

- COMPUTER ARCHITECTURE AND ASSEMBLY LANGUAGE
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    - Text: Tannenbaum, Structured Computer Org. 4 ed.

# Syllabus

- Functional organization of digital computers.
  - Components, Logic-level, MicroArchitecture, ISA
- OS & Assembly language
  - addressing, stacks, argument passing, arithmetic operations, decisions, macros, modularization, linkers and debuggers.
- Prereq: CS 161, MTH 231
- Written Homework: weekly, 10%
- Programming: 10% (2 assignments ?)
- 2 Quizzes: 5% each
- 2 Midterms: 15% each
- Final: 40%

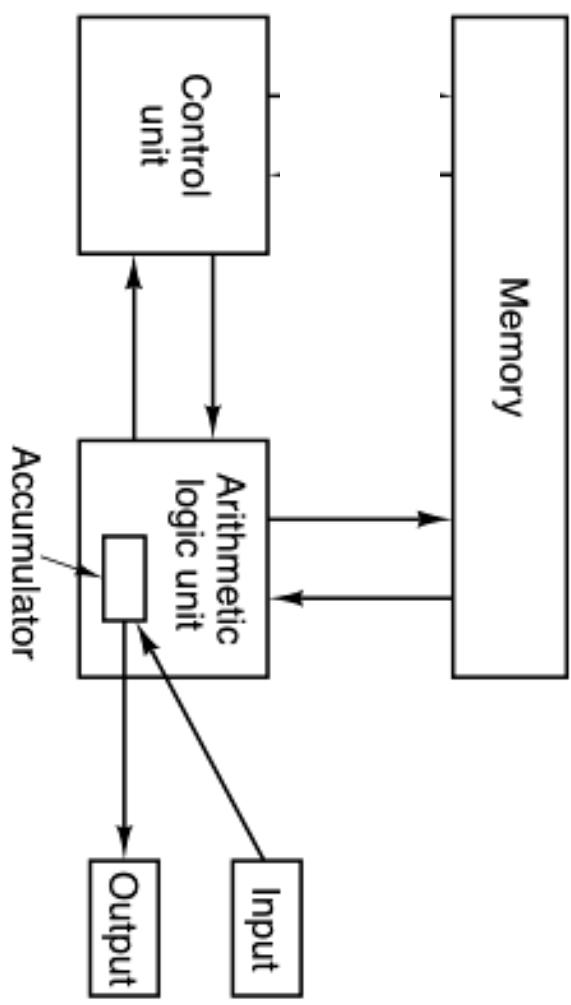
# Schedule

Week	Chapter	Notes
1	1	Quiz
2	2	
3	3.1 - 3.4	
4	3.5, 4.1	Midterm 1
5	4.2 - 4.7	
6	5.1 - 5.5	
7	5.6 - 5.7	Midterm 2
8	6.1 - 6.3	Holiday
9	6.4 - 6.5, 7.1	
10	7	

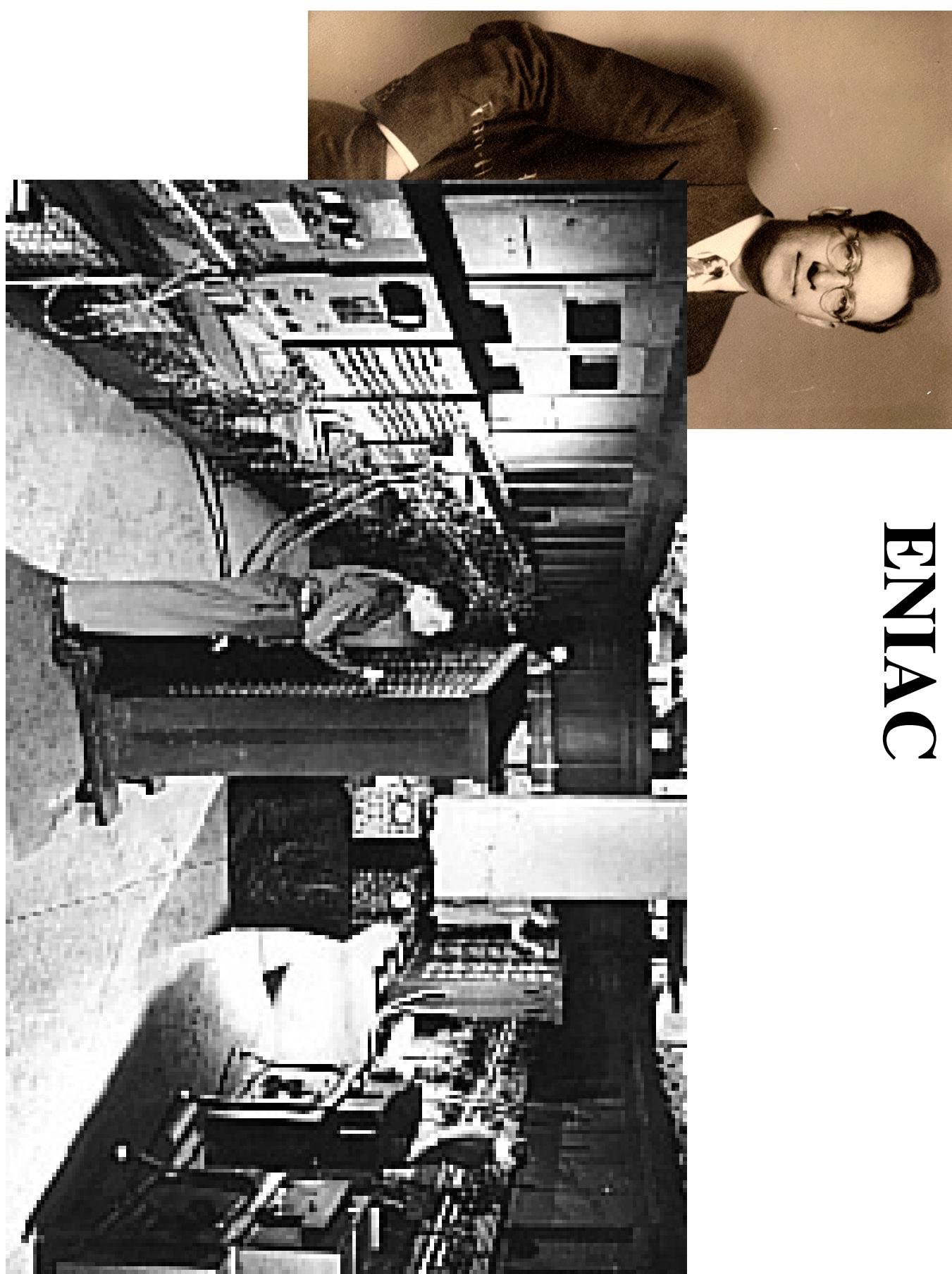
# History

Year	Name	Made by	Comments
1834	Analytical Engine	Babbage	First attempt to build a digital computer
1936	Z1	Zuse	First working relay calculating machine
1943	COLOSSUS	British govt	First electronic computer
1944	Mark I	Aiken	First American general-purpose computer
1946	ENIAC I	Eckert/Mauchley	Modern computer history starts here
1949	EDSAC	Wilkes	First stored-program computer
1951	Whirlwind I	M.I.T.	First real-time computer
1952	IAS	Von Neumann	Most current machines use this design
1960	PDP-1	DEC	First minicomputer (50 sold)
1961	1401	IBM	Enormously popular small business machine
1962	7094	IBM	Dominated scientific computing in the early 1960s
1963	B5000	Burroughs	First machine designed for a high-level language
1964	360	IBM	First product line designed as a family
1964	6600	CDC	First scientific supercomputer
1965	PDP-8	DEC	First mass-market minicomputer (50,000 sold)
1970	PDP-11	DEC	Dominated minicomputers in the 1970s
1974	8080	Intel	First general-purpose 8-bit computer on a chip
1974	CRAY-1	Cray	First vector supercomputer
1978	VAX	DEC	First 32-bit superminicomputer
1981	IBM PC	IBM	Started the modern personal computer era
1985	MIPS	MIPS	First commercial RISC machine
1987	SPARC	Sun	First SPARC-based RISC workstation
1990	RS6000	IBM	First superscalar machine

# The Difference Engine

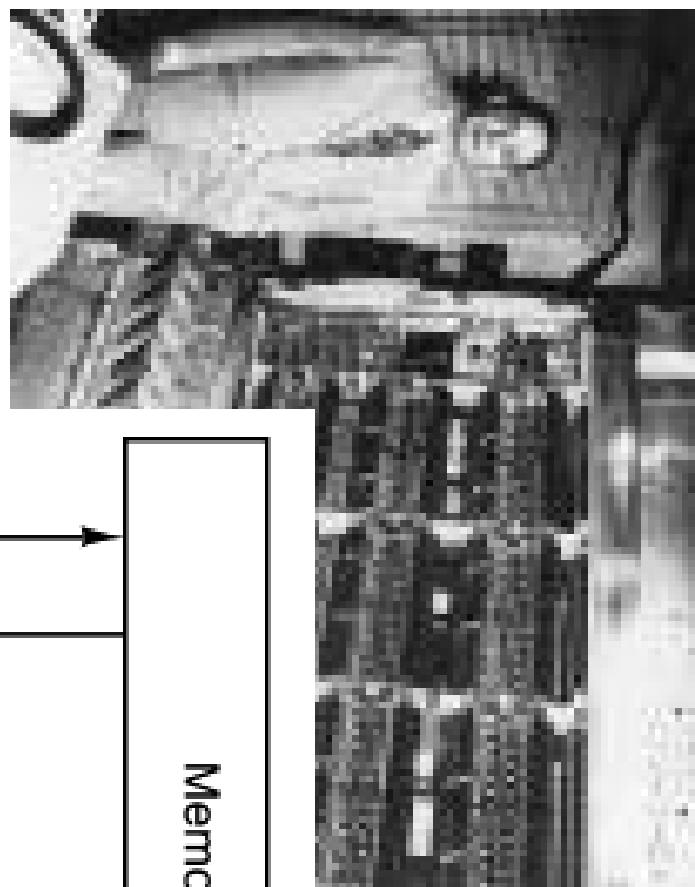
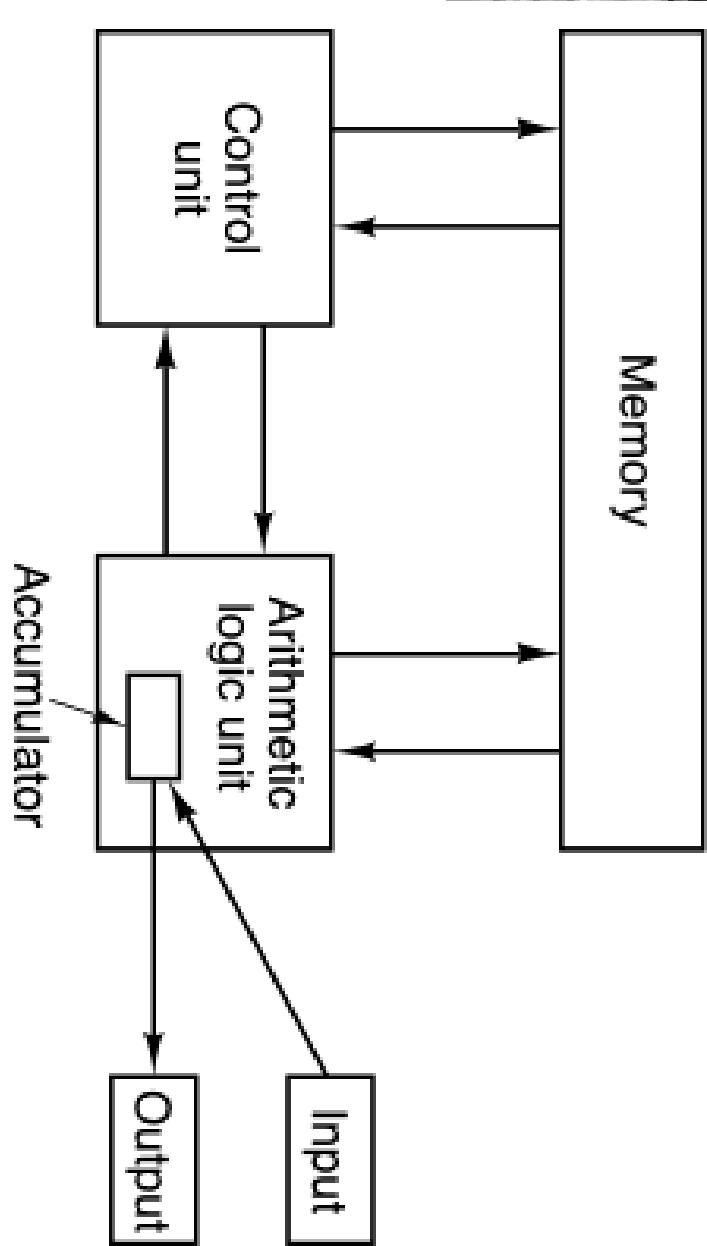


Ada Lovelace



ENIAC

# Von Neumann and IAS



# IBM - 1960s

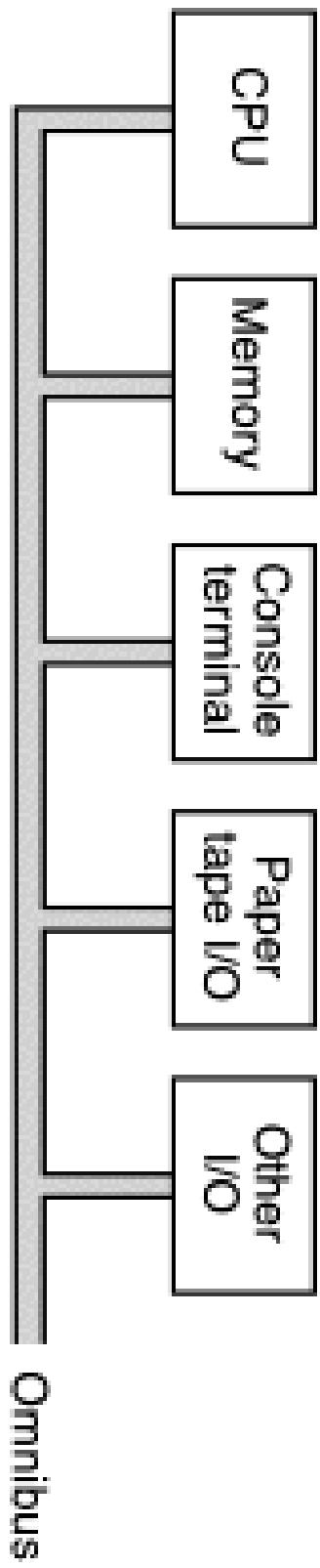


1401



7094

# PDP-8



# IBM 360

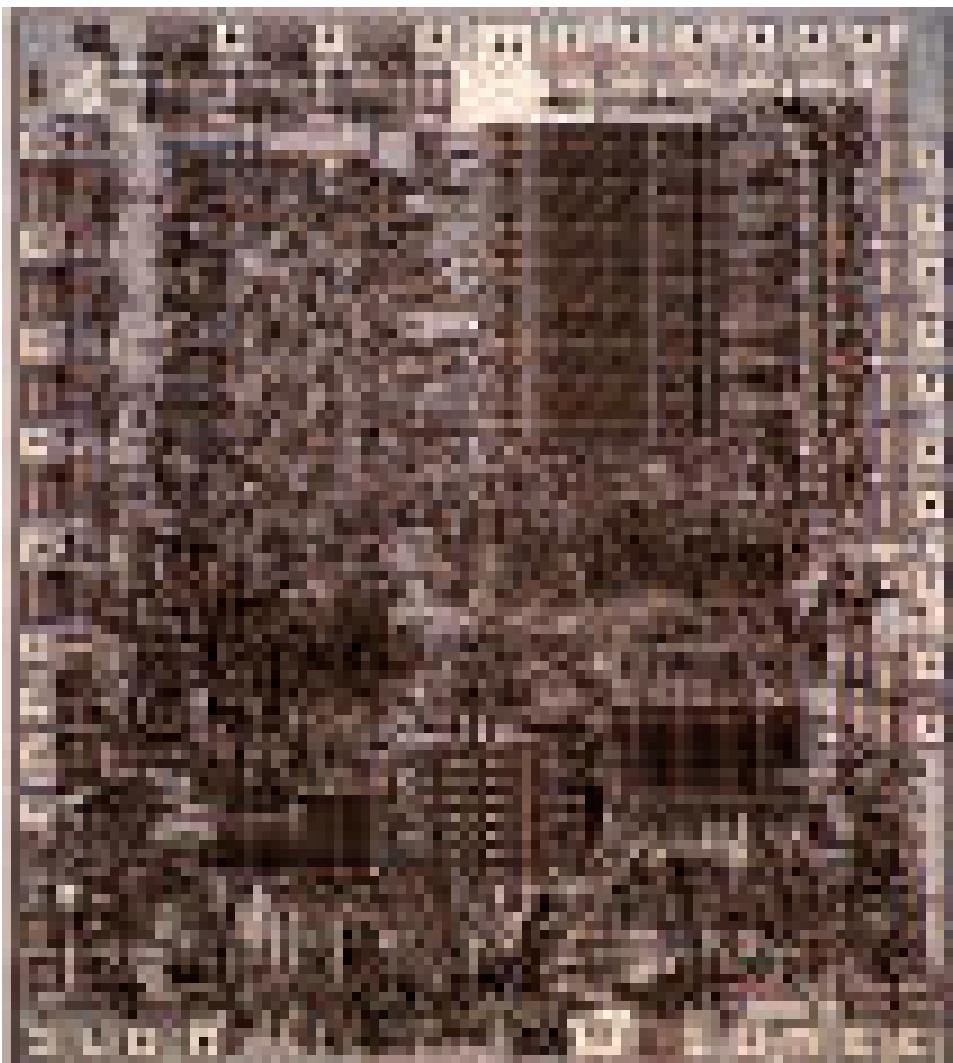
- Microprogrammed
- Family
- Multiprogram



Property	Model 30	Model 40	Model 50	Model 65
Relative performance	1	3.5	10	21
Cycle time (nsec)	1000	625	500	250
Maximum memory (KB)	64	256	256	512
Bytes fetched per cycle	1	2	4	16
Maximum number of data channels	3	3	4	6

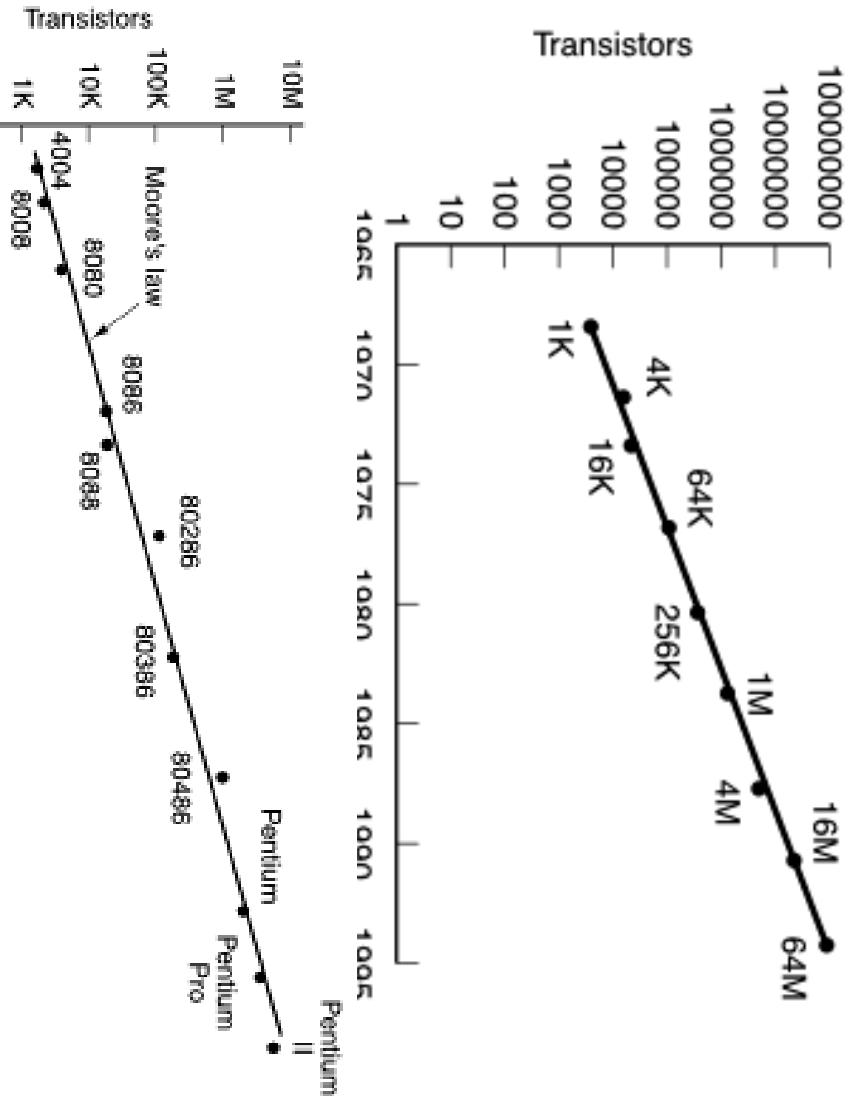
# The VLSI revolution

- 4004
- 8008
- 8080
- 8088
- 8086
- 80286
- 80386
- 80486
- Pentium
- PII
- PIII
- PIV
- ...



# Exponential Growth

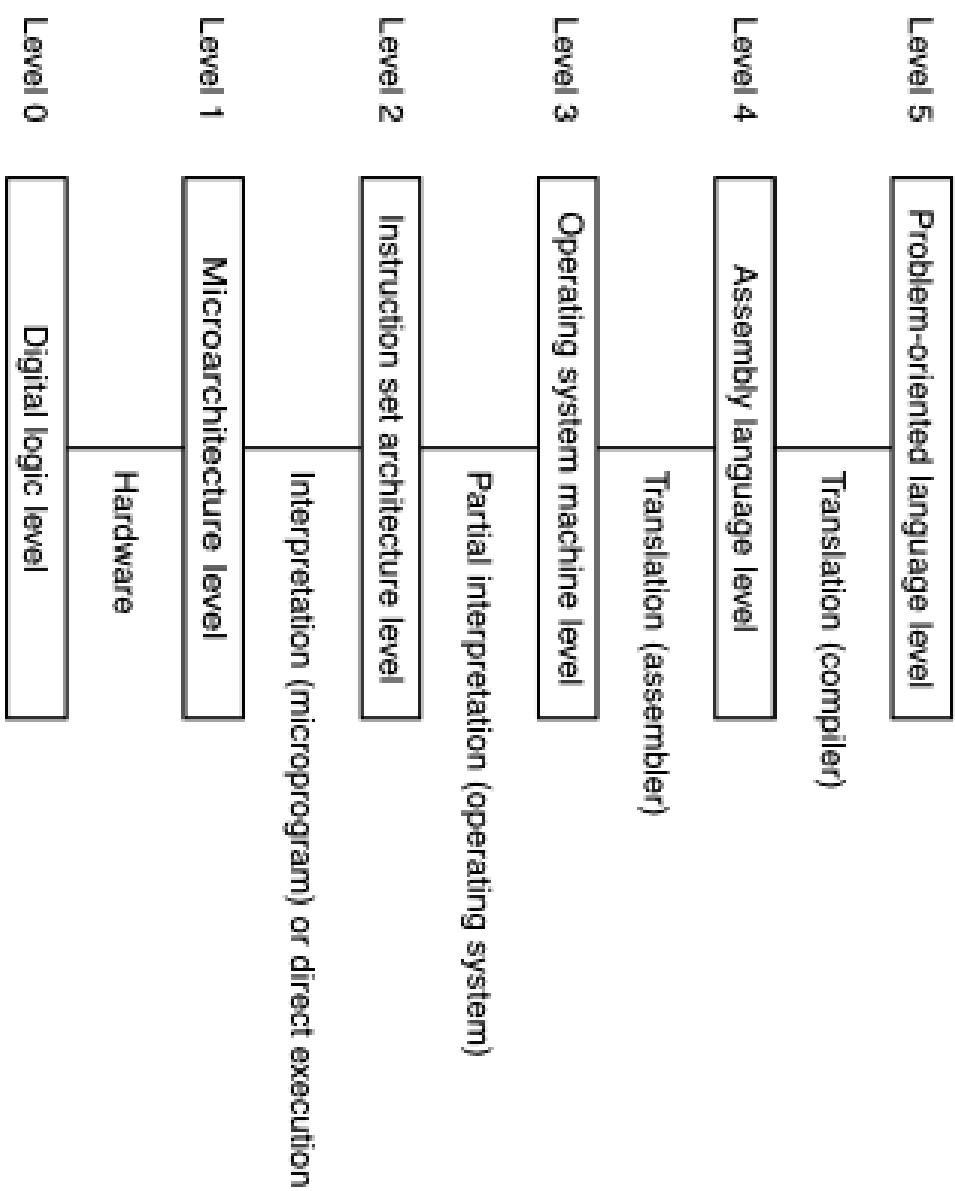
- Machine code
- Single-thread OS
- Multi-thread
- On-line
- Graphical UI
- Multi-media
- Virtual Reality (?)



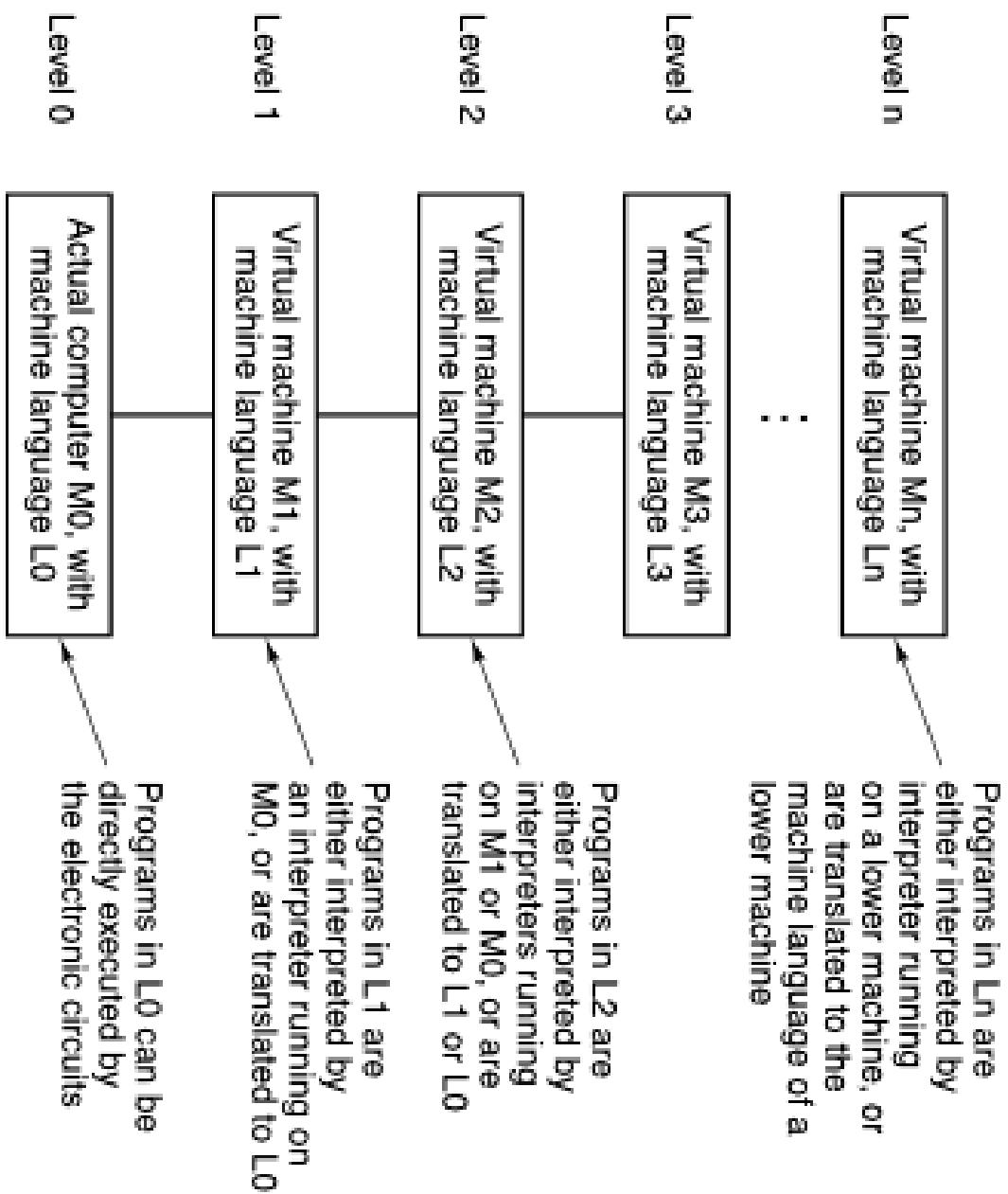
Year of introduction

# Computer Organization

## The layered model

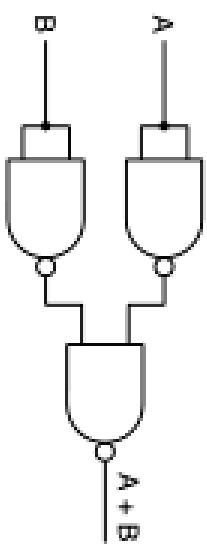
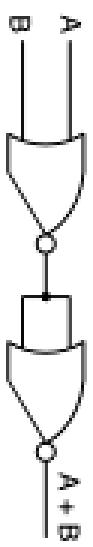
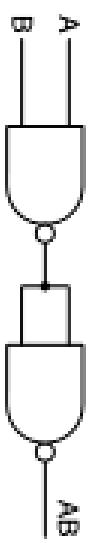
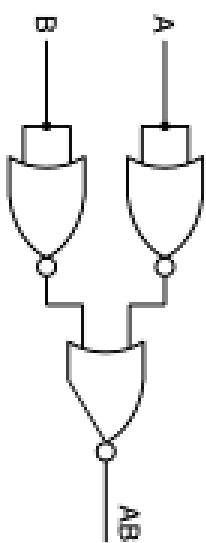


# Layered Machine model



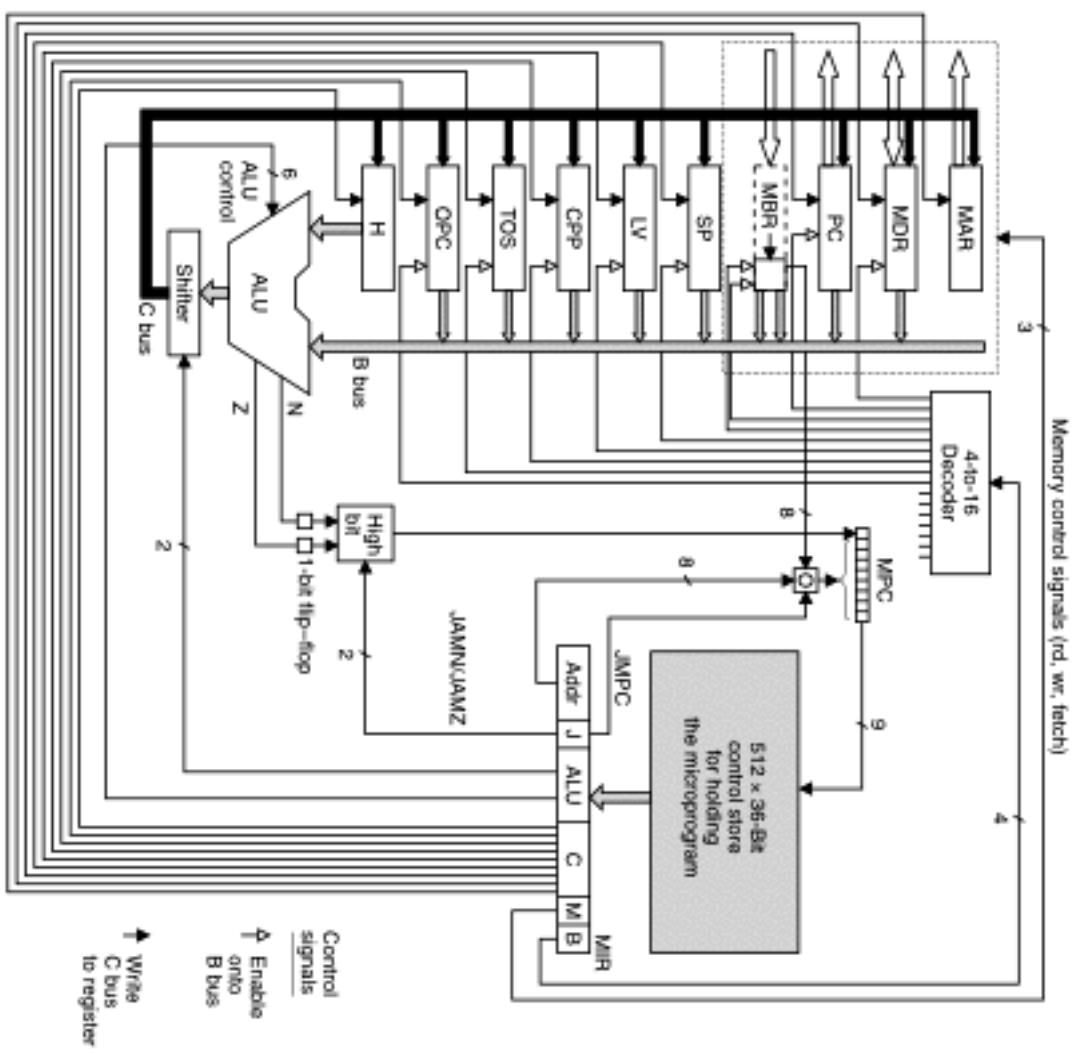
# Digital Logic Level

- Logical Abstraction of physical hardware
- Basic elements are gates.
- How are gates composed?



# MicroArchitecture

- Registers
- Datapaths
- Functional Units
  - ALU
- First view of entire machine - sort of



# Instruction Set Architecture

- Instruction-visible registers
- Instruction-view of storage
- Instruction-available operations
- Instruction word format

Moves		Transfer of control	
MUL DST,SRC	Multiply SRC to DST	JMP ADDR	Jump to ADDR
PUSH SRC	Push SRC onto the stack	JSR ADDR	Conditional jump based on Flags
POP DST	Pop a word from the stack to DST	CALL ADDR	Call procedure at ADDR
XCHG DST,D82	Exchange DST and D82	RET	Return from procedure
LEA DST,FPC	Load effective address of SRC into DST	JEET	Return from interrupt
CMOV DST,SRC	Conditional move	LOOP#	Loop until condition met
INTO	Indicates if overflow bit is set	INT ADDR	Initialize a software interrupt
ADD DST,SRC	Add SRC to DST	Arithmetic	
SUB DST,SRC	Subtract DST from SRC	Logical	
MUL SRC	Multiply EAX by SRC (unaligned)	LCDS	Load string
MUL SRC	Multiply EAX by SRC (aligned)	STOS	Store string
DIV SRC	Divide EDX:EAX by SRC (unaligned)	MOVNS	Move string
DIV SRC	Divide EDX:EAX by SRC (aligned)	CMPS	Compare two strings
ADC DST,SRC	Add SRC to DST, then set carry bit	SCAS	Scan Strings
SBB DST,SRC	Subtract DST & carry from SRC	Comparison codes	
INC DST	Add 1 to DST	STC	Set carry bit in EFL/FLAGS register
DEC DST	Subtract 1 from DST	CLC	Clear carry bit in EFL/FLAGS register
NEG DST	Negate DST (subtracts it from 0)	STD	Complement carry bit in EFL/FLAGS
Binary coded decimal			
DAA	Decimal adjust	CLD	Set direction bit in EFL/FLAGS register
DAS	Decimal adjust for subtraction	STI	Set interrupt bit in EFL/FLAGS register
AAS	ASCII adjust for addition	CLD	Clear interrupt bit in EFL/FLAGS register
AAS	ASCII adjust for subtraction	pushFD	Push EFL/FLAGS register onto stack
AAM	ASCII adjust for multiplication	popFD	Pop EFL/FLAGS register from stack
AMD	ASCII adjust for division	LAHF	Load AH from EFL/FLAGS register
Boolean			
AND DST,SRC	Boolean AND SRC into DST	SHLD DST	Change bitlength of DST
OR DST,SRC	Boolean OR SRC into DST	CDQ	Extend EAX to EDX:EAX for division
XOR DST,SRC	Boolean Exclusive OR SRC to DST	CDE	Extend 16-bit number in AX to EAX
NOT DST	Replace DST with 1's complement	ENTER SIZE LV	Change stack frame with SIZE bytes
Shift/move			
SALSHR DST,#	Shift DST left/right # bits	LEAVE	Unwind stack frame built by ENTER
SHLSHR DST,#	Logical shift DST left/right # bits	MOP	No operation
ROLROR DST,#	Rotate DST left/right # bits	HLT	Halt
RELRGN DST,#	Rotate DST through carry # bits	IN AL,PORT	Input a byte from PORT to AL
Test/compare			
TST SRC1,SRC2	Boolean AND operations, set flags	OUT PORT,AL	Output a byte from AL to PORT
CMPSN1,SRC2	Set flags based on SRC1 - SRC2	WAIT	Wait for an interrupt
SRC = source		# = shiftable count	
DST = destination		LV = # loops	

# ISA View of CPU (Cont'd)

<b>Register</b>	<b>Alt. name</b>	<b>Function</b>
R0	G0	Hardwired to 0. Stores into it are just ignored.
R1 – R7	G1 – G7	Holds global variables
R8 – R13	O0 – O5	Holds parameters to the procedure being called
R14	SP	Stack pointer
R15	O7	Scratch register
R16 – R23	L0 – L7	Holds local variables for the current procedure
R24 – R29	I0 – I5	Holds incoming parameters
R30	FP	Pointer to the base of the current stack frame
R31	I7	Holds return address for the current procedure

Figure 5-4. The UltraSPARC II's general registers.

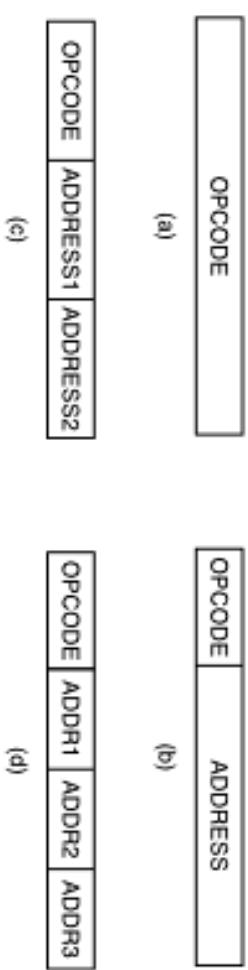


Figure 5-9. Four common instruction formats: (a) Zero-

Type	8 Bits	16 Bits	32 Bits	64 Bits	128 Bits
Signed integer	x	x	x	x	
Unsigned integer					
Binary coded decimal integer				x	x
Floating point					

Figure 5-8. The JVM numeric data types.

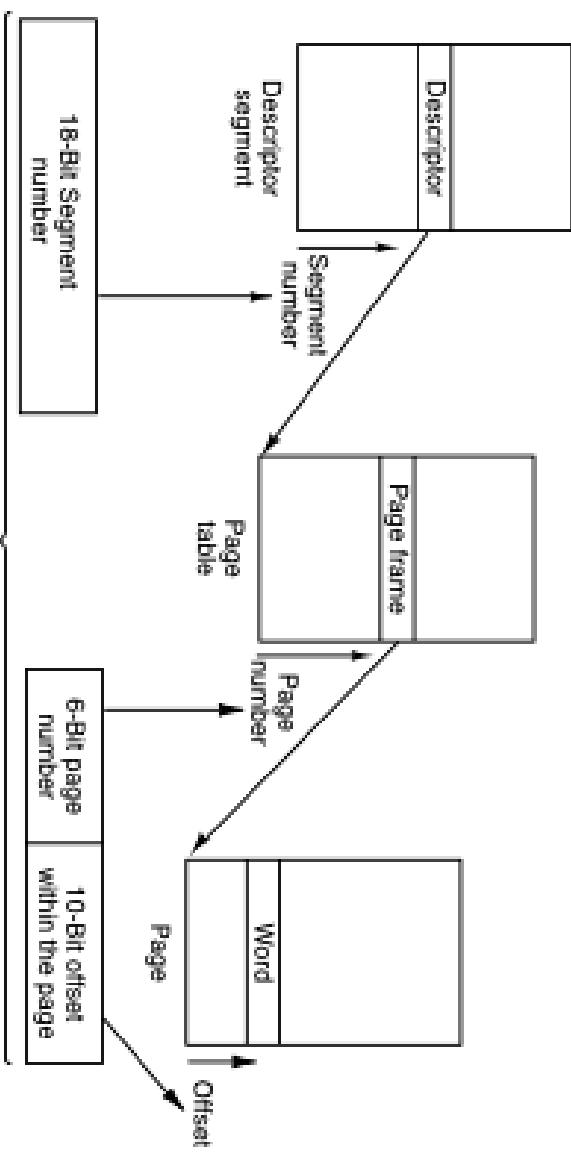
# Operating System Level

- Storage management
- Memory
- Files

- Programs
- Processes
- Communication

Category	Some examples
File management	Open, read, write, close, and lock files
Directory management	Create and delete directories; move files around
Process management	Spawn, terminate, trace, and signal processes
Memory management	Share memory among processes; protect pages
Getting/setting parameters	Get user, group, process ID; set priority
Dates and times	Set file access times; use interval timer; profile execution
Networking	Establish/accept connection; send/receive message
Miscellaneous	Enable accounting; manipulate disk quotas; reboot the system

Figure 6-29. A rough breakdown of the UNIX system calls.



# Assembly Language Level

- Symbolic language
  - Keywords
  - Name management
  - Pseudo-Operations
  - Meta-language
    - macros

000010		
100001		
111001		
001100		
Limit: WORD 2		
A: ADD R1, R0		
CMP R0, Limit		
BLT A		
Item	Macro call	Procedure call
When is the call made?	During assembly	During execution
Is the body inserted into the object program every place the call is made?	Yes	No
Is a procedure call instruction inserted into the object program and later executed?	No	Yes
Must a return instruction be used after the call is done?	No	Yes
How many copies of the body appear in the object program?	One per macro call	1

# Basics of software development

- Program development environment

- Assembler
- Linker
- Loader

- Debugger

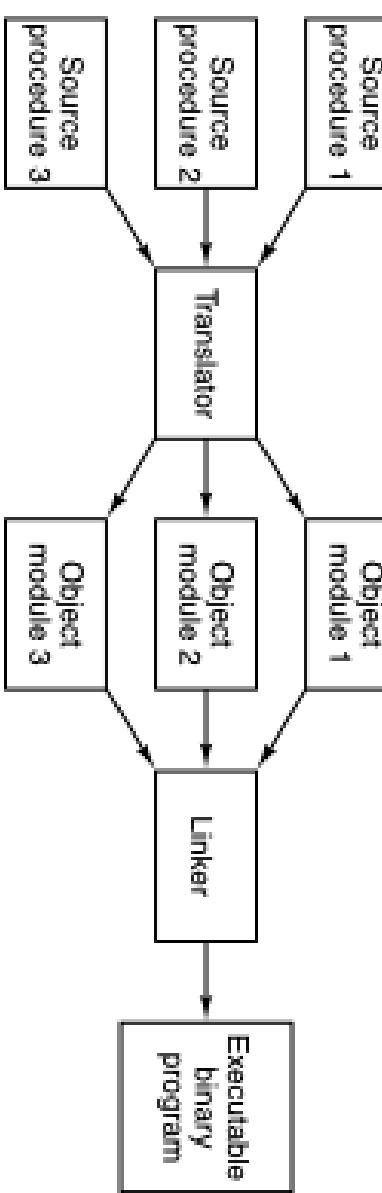


Figure 7-13. Generation of an executable binary program from a collection of independently translated source procedures requires using a linker.