

Animation

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Animation 001

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Animation

Animation is the process of giving motion to your geometric models. Before animating, there are questions you need to ask first:

- Why am I doing this?
- Do I want the animation to obey the real laws of physics? Partially? Which elements?
- Am I willing to "fake" the physics to get the objects to *want* to move in a way that I tell it?
- Do I have specific key positions I want the objects to pass through no matter what?
- Do I want to simply record the motion of a real person, animal, etc., and then play it back?

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Keyframe Animation

These icons refer to explanatory videos on the class web site

anim2.mp4

3

Keyframe Animation

Blender:

4

Here's Some Code that Lets You Create DIY Keyframe Animations

For my own work, instead of *Key Frames*, I like specifying *Key Times* better. And, so, I created a C++ class to do it for you.

```

class Keytimes:
{
    void AddTimeValue( float time, float value );
    float GetFirstTime( );
    float GetLastTime( );
    int GetNumKeytimes( );
    float GetValue( float time );
    void Init( );
    void PrintTimeValues( );
}
    
```

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Instead of Key Frames, I Like Specifying Key Times Better

Keytimes Xpos: Declare one class per parameter you are animating. Here it wants to interpolate and animate the x-location of something.

```

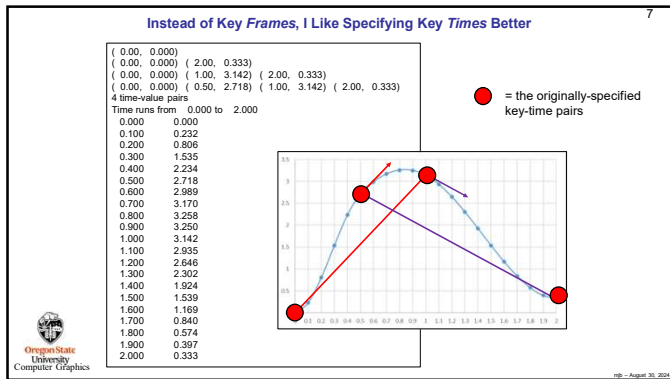
int main( int argc, char *argv[] )
{
    Xpos xpos;
    xpos.AddTimeValue( 0.0, 0.000 );
    xpos.AddTimeValue( 2.0, 0.333 );
    xpos.AddTimeValue( 1.0, 3.142 );
    xpos.AddTimeValue( 0.5, 2.718 );
    printf( "stderr, \"%d time-value pairs:\", xpos.GetNumKeytimes( );\n", xpos.GetNumKeytimes( ) );
    xpos.PrintTimeValues( );

    printf( "stderr, \"Time runs from %8.3f to %8.3f\n", xpos.GetFirstTime( ), xpos.GetLastTime( ) );
    for( float t = 0.0; t <= 2.0; t += 0.1 )
    {
        float v = xpos.GetValue( t );
        printf( "stderr, \"%8.3ft%8.3fv\n", t, v );
    }
}
    
```

Key-Time pairs (Time and Xlocation) can be specified in any order

Just to demonstrate, this for-loop runs through a collection of time values and looks up the interpolate x-location at those values. Normally you would get the time from the system clock.

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Using the System Clock in Display() for Timing

```

#define MSEC 10000 // i.e., 10 seconds
Keytimes Xpos, Ypos, Zpos;
Keytimes ThetaX, ThetaY, ThetaZ;
...
if( AnimationsOn )
{
    // msec into the cycle ( 0 - MSEC-1 ):
    int msec = glutGet( GLUT_ELAPSED_TIME ) % MSEC;

    // turn that into a time in seconds:
    float nowTime = (float)msec / 1000.;
    glTranslatef( Xpos.GetValue( nowTime ), Ypos.GetValue( nowTime ), Zpos.GetValue( nowTime ) );
};

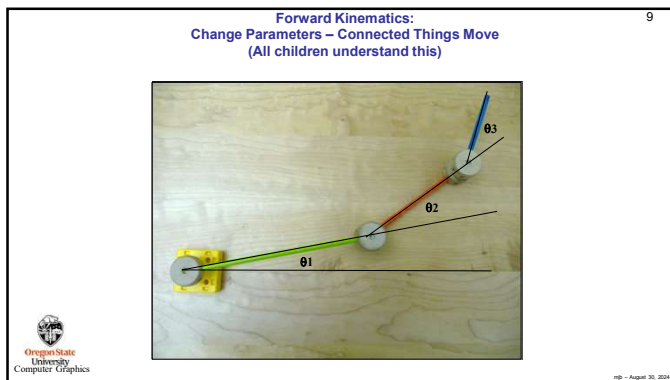
glRotatef( ThetaX.GetValue( nowTime ), 1, 0, 0 );
glRotatef( ThetaY.GetValue( nowTime ), 0, 1, 0 );
glRotatef( ThetaZ.GetValue( nowTime ), 0, 0, 1 );
<< draw the object >>
glPopMatrix();

```

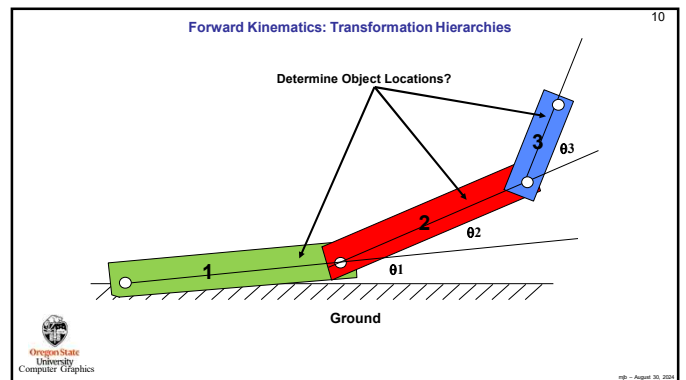
Number of msec in the animation cycle

Oregon State University Computer Graphics

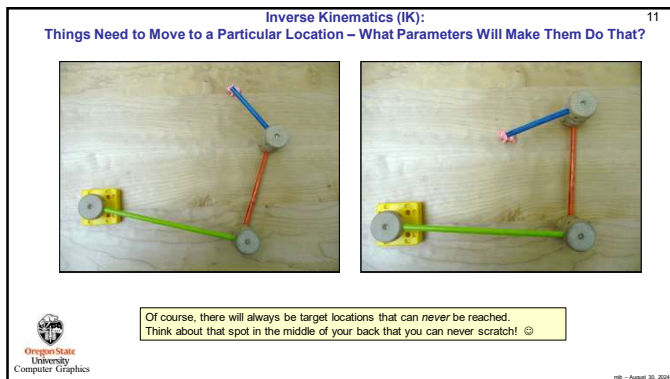
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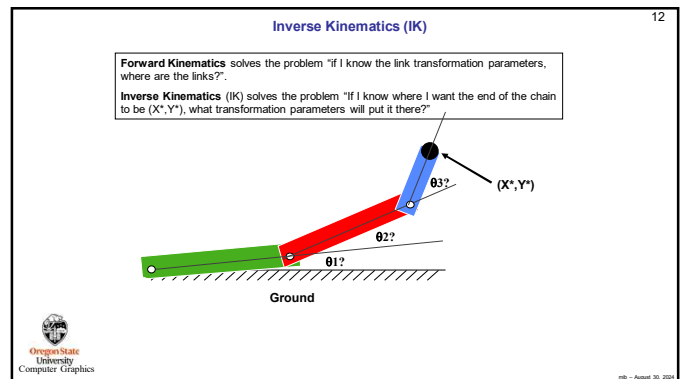
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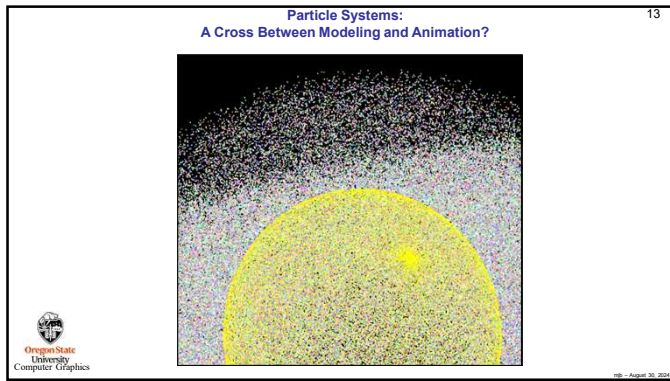
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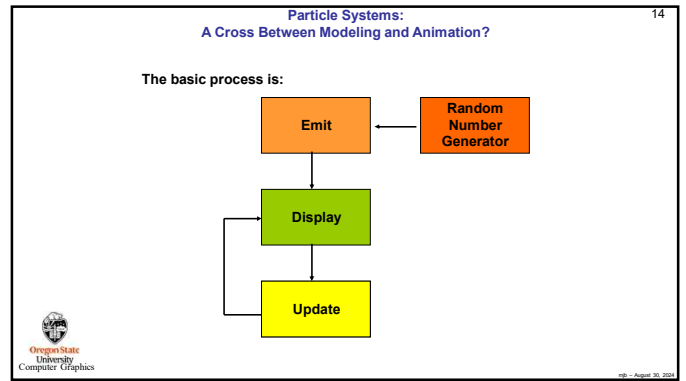
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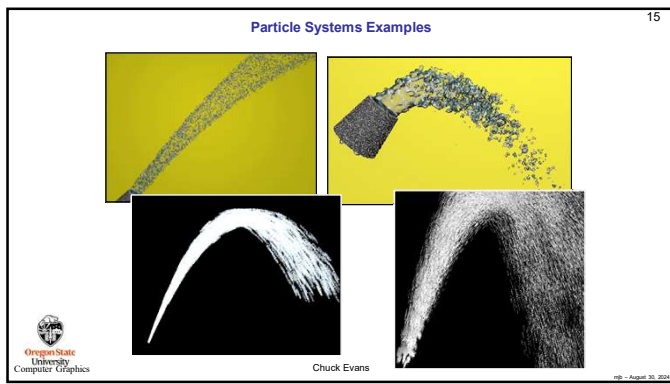
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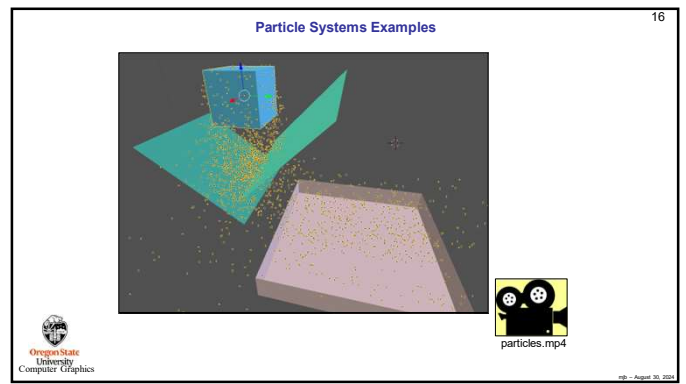
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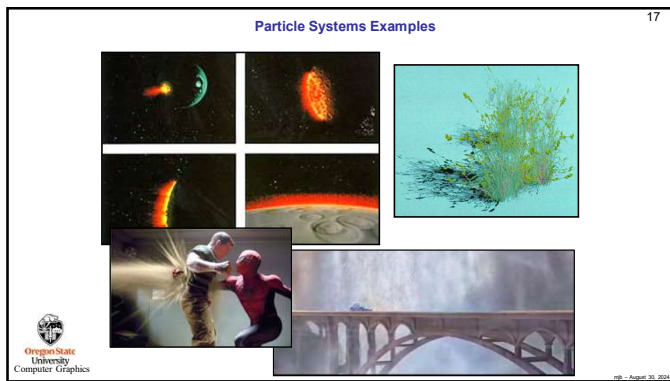
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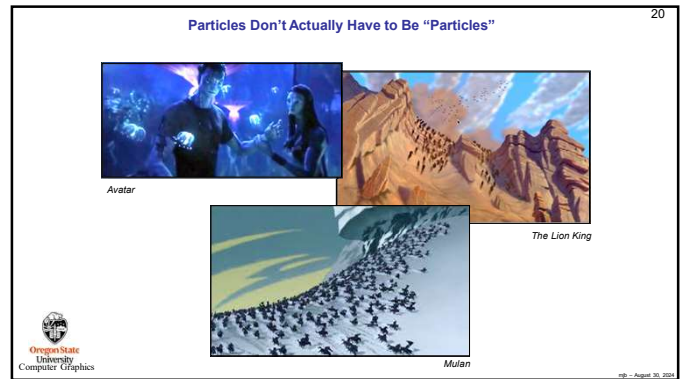
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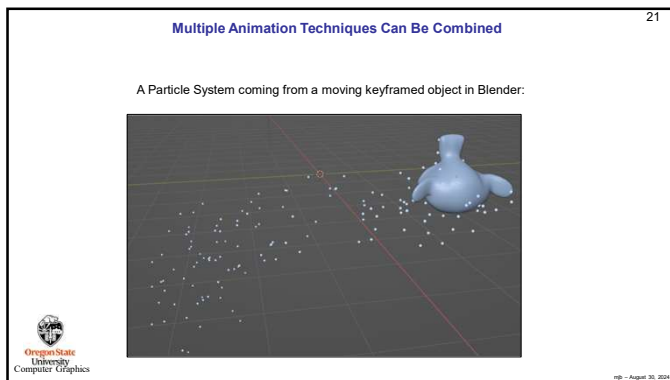
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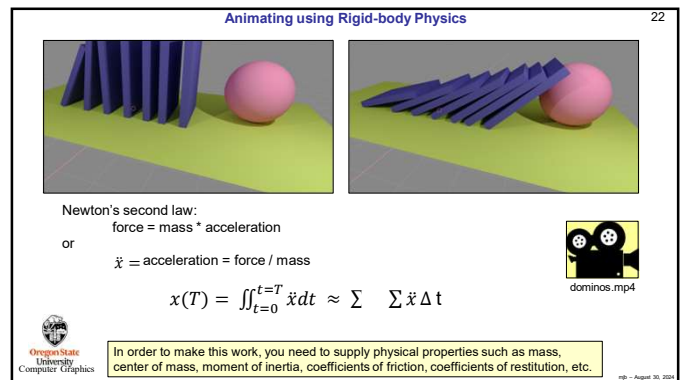
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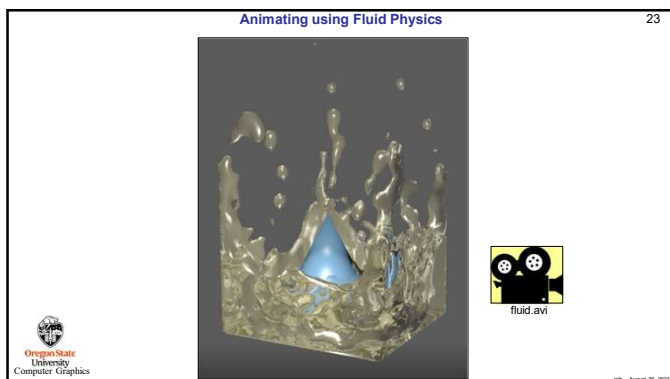
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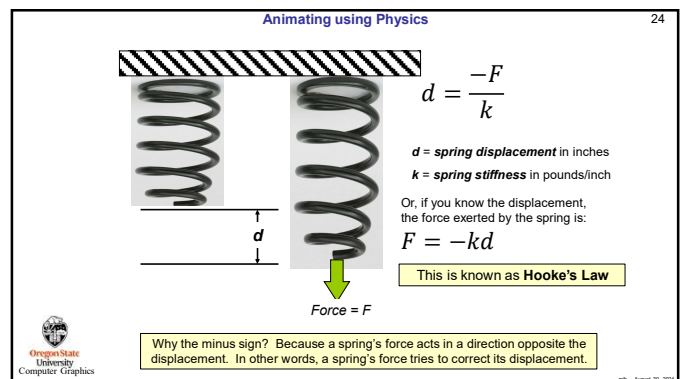
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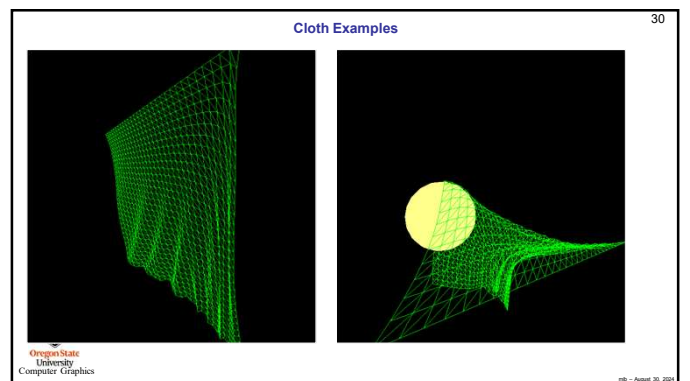
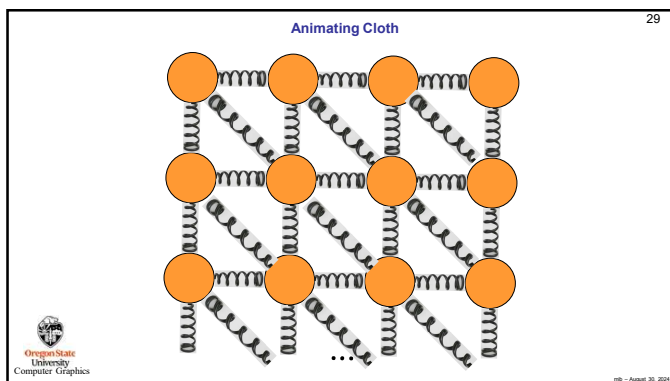
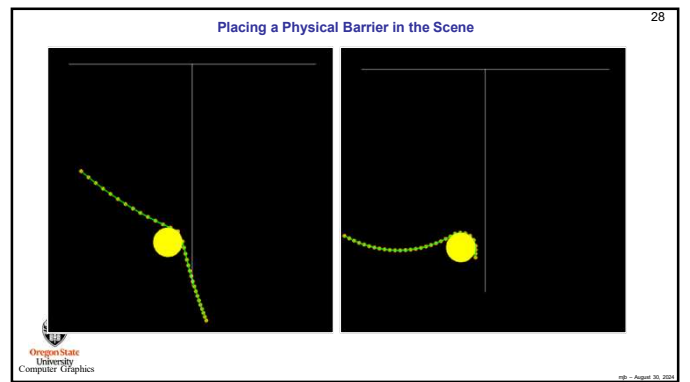
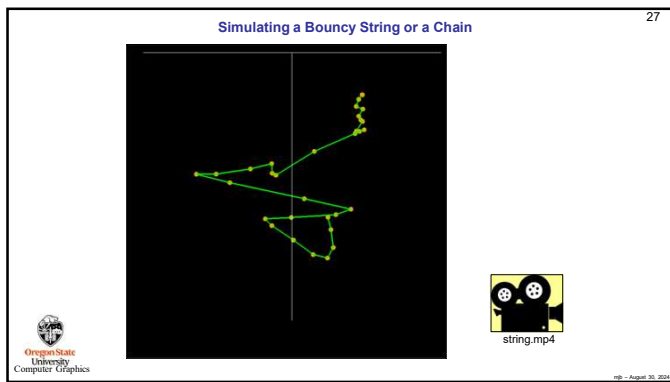
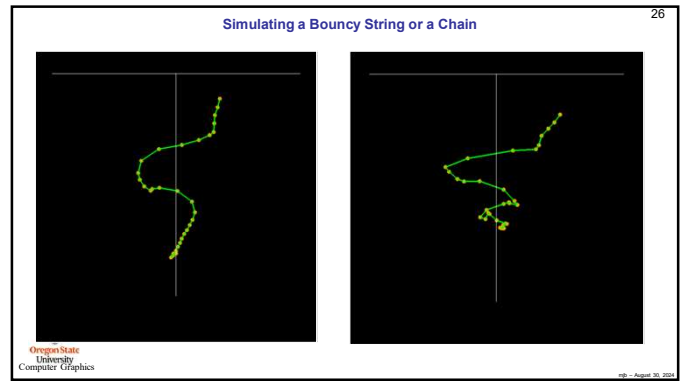
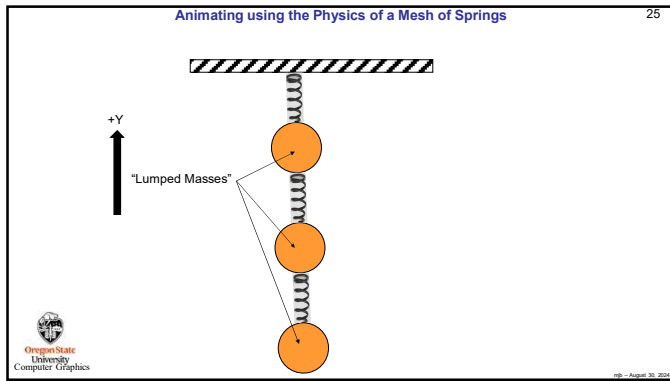
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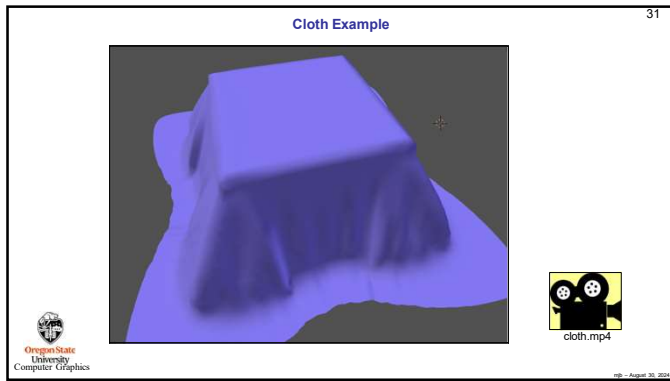


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Functional Animation:
Setup Imaginary Physics to Make the Object *Want* to Move Towards a Goal Position

Newton's second law:
force = mass * acceleration
or
 $\ddot{x} = \text{acceleration} = \text{force} / \text{mass}$

$$\ddot{x} = \frac{-c\dot{x} - kx}{m}$$

- The k is an imaginary spring.
- The c is an imaginary "damper", which you can think of as a shock absorber which absorbs energy. (Your car has these to soften bouncing.)

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Functional Animation:
Setup Imaginary Physics to Make the Object *Want* to Move Away from all other Objects

Newton's second law:
force = mass * acceleration
or
 $\ddot{x} = \text{acceleration} = \text{force} / \text{mass}$

$$\ddot{x} = \frac{F_{\text{repulsive}}}{m}$$

$$F_{\text{repulsive}} = \frac{C_{\text{repulsive}}}{d^{\text{Power}}}$$

Repulsion Coefficient
 $C_{\text{repulsive}}$
 Distance between the boundaries of the 2 bodies
 d
 Repulsion Exponent
 Power

This isn't from a book. I just made this up. It seemed like a good idea.

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Total Goal – Make the Free Body Move Towards its Final Position
While Being Repelled by the Other Bodies

Newton's second law:
force = mass * acceleration
or
 $\ddot{x} = \text{acceleration} = \text{force} / \text{mass}$

$$\ddot{x} = \frac{-c\dot{x} - kx + \sum F_{\text{repulsive}}}{m}$$

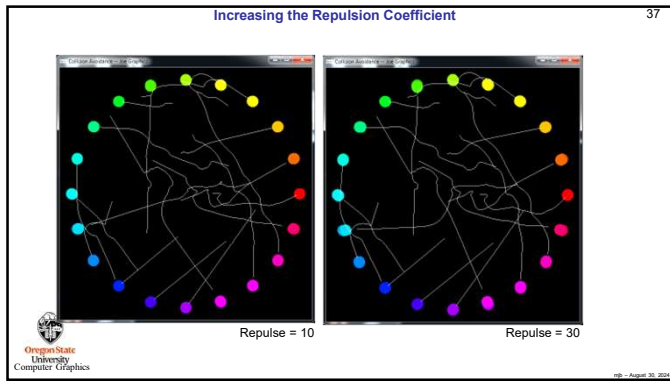
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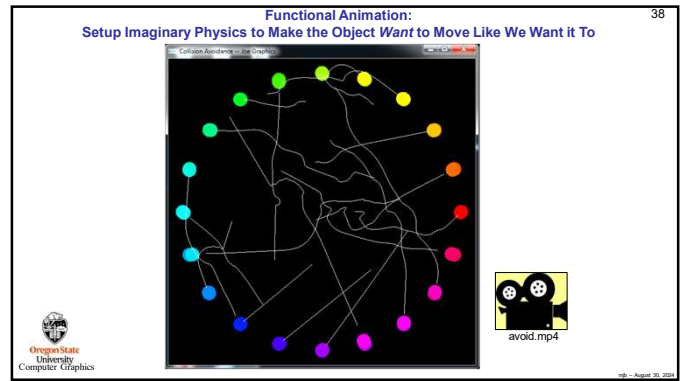
Increasing the Stiffness

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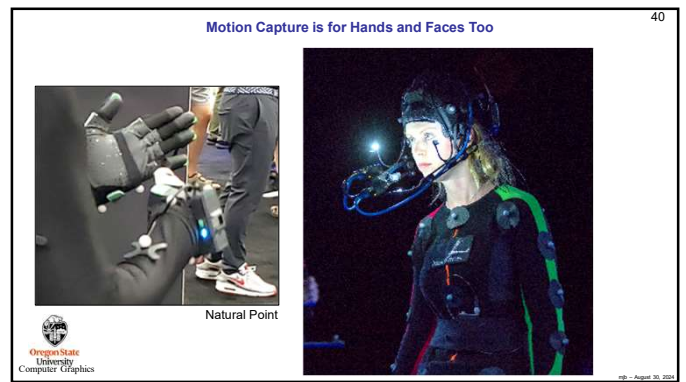
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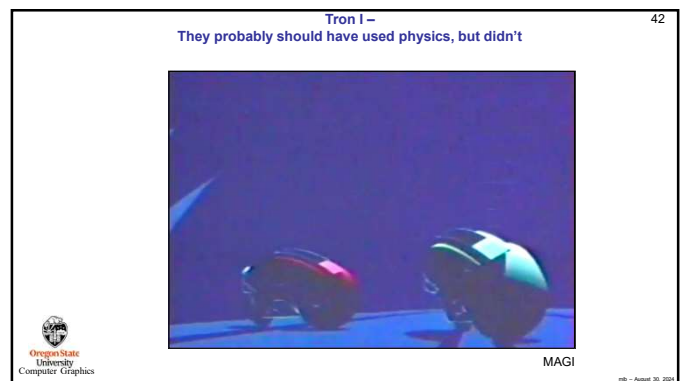
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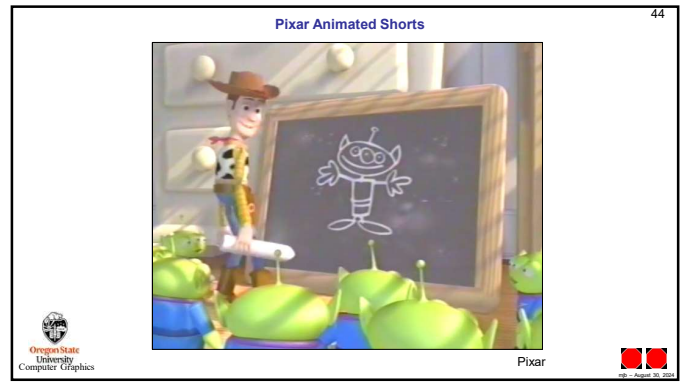
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