



## Generalized Bump-mapping with Surface Local Coordinates


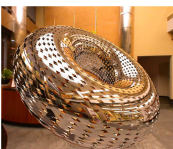
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**Oregon State University**  
Mike Bailey  
mjb@cs.oregonstate.edu

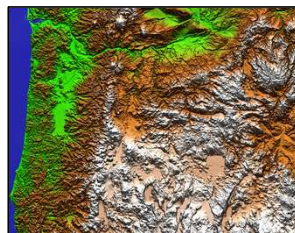
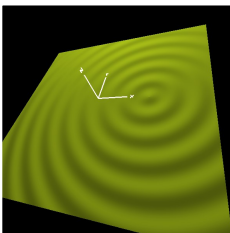



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## The Most Straightforward Types of Bump-Mapping are Height Fields

### Why?

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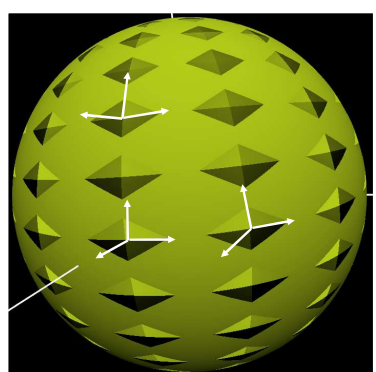



Height Field bump-mapping is straightforward because the underlying coordinate system is constant. Each fragment's Z points up, each fragment's X points right, etc. Thus, the tangent vectors always involve  $\frac{dz}{dx}$  and  $\frac{dz}{dy}$ .

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## What if that is not the case? Here, the coordinate system is constantly changing, depending on where you are on the sphere

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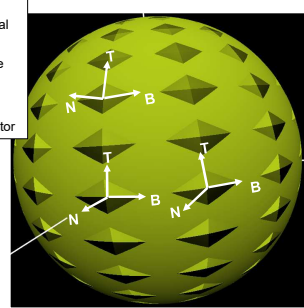
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## This is referred to as Surface Local Coordinates

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To call these moving axes X-Y-Z would be confusing. Rather than X-Y-Z, Surface Local Coordinates are **B-T-N**:

- N is the surface Normal vector, which we usually know already
- T is a Tangent vector
- B is the Bitangent, the other tangent vector



We will assume that we know the Normal everywhere because of how the shape was modeled. Now, how do we find T and B? And, how do we convert these to X-Y-Z?

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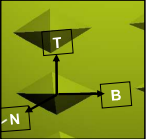
## Generalized Bump Mapping: A Problem

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The problem is that we need to do lighting, but the lighting needs to be done in X-Y-Z, *but* the bump information is in B-T-N!

We need to:

- Figure out how to determine T and B, and,
- Figure out how to convert B-T-N coordinates to X-Y-Z for lighting



We will refer to the coordinates in the B-T-N system as **(b,t,n)**.

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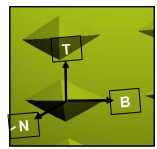
## Bump Mapping: Establishing the Surface Local Coordinate System

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We need a second piece of information: Pick a general rule, e.g., "Tangent = up (0,1,0.)"

We then have two choices:

- Use two cross-products to correctly orthogonalize it wrt the Normal
- Use the Gram-Schmidt rule to correctly orthogonalize it wrt the Normal



```
// the vectors B-T-N form an X-Y-Z looking
// right handed coordinate system:
vec3 N = normalize( gl_NormalMatrix * gl_Normal );
vec3 Tg, T; // Tguess and corrected T
vec3 B;

#define CROSS_PRODUCT_METHOD

#ifdef CROSS_PRODUCT_METHOD
Tg = vec3( 0.,1.,0.); // guess at T
B = normalize( cross(Tg,N) ); // correct B
T = normalize( cross(N,B) ); // corrected T
#endif

#ifdef GRAM_SCHMIDT_METHOD
Tg = vec3( 0.,1.,0.); // guess at T
float d = dot( Tg, N );
T = normalize( Tg - d*N ); // corrected T
B = normalize( cross(T,N) ); // correct B
#endif
```

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### Cross Product Orthogonalization

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```
vec3 Tg = vec3( 0.,1.,0.); // initial guess
vec3 B = normalize(cross(Tg,N));
vec3 T = normalize(cross(N,B));
```

1 Given that  $\hat{N}$  is correct, how do we change  $T_g$  to be exactly perpendicular to  $\hat{N}$ ?

2 Take the cross product of  $T_g$  and  $\hat{N}$  to get a  $B$  vector that is perpendicular to both.

3 Take the cross product of  $\hat{N}$  and  $B$  to get a  $T$  vector that is perpendicular to both.

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### Gram-Schmidt Orthogonalization

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```
vec3 Tg = vec3( 0.,1.,0.); // initial guess
float d = dot( Tg, N );
vec3 T = normalize( Tg - d*N );
vec3 B = normalize(cross(T,N));
```

1 Given that  $\hat{N}$  is correct, how do we change  $T_g$  to be exactly perpendicular to  $\hat{N}$ ?

2 How much of  $T_g$  is in the same direction as  $\hat{N}$ ?

3 How much of  $T_g$  do we need to get rid of so that none of it is in the same direction as  $\hat{N}$ ?

4 The resulting  $T$  is perpendicular to  $\hat{N}$ .

$$T = T_g - d\hat{N} = T_g - (T_g \cdot \hat{N})\hat{N}$$

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### Bump Mapping: Converting Between Coordinate Systems

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Converting from X-Y-Z to b-t-n:

$$\begin{pmatrix} b \\ t \\ n \end{pmatrix} = \begin{bmatrix} B_x & B_y & B_z \\ T_x & T_y & T_z \\ N_x & N_y & N_z \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

Converting from b-t-n to X-Y-Z:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} B_x & T_x & N_x \\ B_y & T_y & N_y \\ B_z & T_z & N_z \end{bmatrix} \begin{pmatrix} b \\ t \\ n \end{pmatrix}$$

I prefer to use the second one so we can do lighting in X-Y-Z like we are used to doing.

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### Generalized Bump Mapping: Establishing the Surface Local Coordinate System

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Vertex shader:

```
#version 330 compatibility
uniform vec3 uLightPosition;

out vec2 vST;
out vec3 vN;
out vec3 vL;
out vec3 vBTNx, vBTNy, vBTNz;

void main()
{
    vN = normalize( gl_NormalMatrix * gl_Normal ); // normal vector
    vec3 Tg = vec3( 0.,1.,0.); // guess
    vec3 B = normalize( cross(Tg,vN) );
    vec3 T = normalize( cross(vN,B) );

    // produce the transformation from Surface coords to Eye coords
    vBTNx = vec3( B.x, T.x, vN.x );
    vBTNy = vec3( B.y, T.y, vN.y );
    vBTNz = vec3( B.z, T.z, vN.z );
    vST = gl_MultiTexCoord0.st;

    vec4 ECPosition = gl_ModelViewMatrix * gl_Vertex;
    vL = uLightPosition - ECPosition.xyz;
    vE = vec3( 0., 0., 0. ) - ECPosition.xyz;
    gl_Position = gl_ModelViewProjectionMatrix * gl_Vertex;
}
```

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### Generalized Bump Mapping: Using the s-t-h to X-Y-Z Transform

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Fragment shader:

```
#version 330 compatibility
uniform vec3 uColor;
uniform vec3 uSpecularColor;
uniform float uKa, uKd, uKs;
uniform float uShininess;
uniform float uBumpDensity;

in vec2 vST;
in vec3 vN;
in vec3 vL;
in vec3 vE;
in vec3 vBTNx, vBTNy, vBTNz;

vec3 ToXyz( vec3 btn )
{
    btn = normalize( btn );
    vec3 xyz;
    xyz.x = dot( vBTNx, btn );
    xyz.y = dot( vBTNy, btn );
    xyz.z = dot( vBTNz, btn );
    return normalize( xyz );
}
```

Look at this closely. It is actually a matrix-multiply!

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### Matrix Multiplication is Really Row-by-Row Dot Products

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The basic operation of matrix multiplication is to pair-wise multiply a single row by a single column

$$\begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \begin{Bmatrix} 4 \\ 5 \\ 6 \end{Bmatrix} \rightarrow 4*1 + 5*2 + 6*3 \rightarrow 32$$

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## Generalized Bump Mapping: Using the Surface Local Transform, I

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```

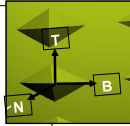
...
void
main()
{
    vec3 Normal = normalize(vN);
    vec3 Light = normalize(vL);
    vec3 Eye = normalize(vE);
    vec3 myColor = uColor; // default color

    // locate the bumps based on (s,t);
    float Swidth = (1.0) / uBumpDensity; // s distance between bumps
    float Theight = (1.0) / uBumpDensity; // t distance between bumps
    float numInS = int( vST.s / Swidth ); // which "checker" square we are in
    float numInT = int( vST.t / Theight ); // which "checker" square we are in

    vec2 center;
    center.s = numInS * Swidth + Swidth/2.; // center of that bump checker
    center.t = numInT * Theight + Theight/2.; // center of that bump checker
    vec2 st = vST - center; // st is now wrt the center of the bump

    float theta = atan( st.t, st.s );
    ...

```



## Generalized Bump Mapping: Using the Surface Local Transform, II

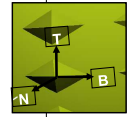
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```

...
vec3 normal = ToXyz( Normal ); // un-bumped normal

if( abs(stp.s) > Swidth/4. || abs(stp.t) > Theight/4. )
{
    normal = ToXyz( vec3( 0., 0., 1. ) );
}
else
{
    if( Pi/4. <= theta && theta <= 3.*Pi/4. )
    {
        normal = ToXyz( vec3( 0., Height, Theight/4. ) );
    }
    else if( -Pi/4. <= theta && theta <= Pi/4. )
    {
        normal = ToXyz( vec3( Height, 0., Swidth/4. ) );
    }
    else if( -3.*Pi/4. <= theta && theta <= -Pi/4. )
    {
        normal = ToXyz( vec3( 0., -Height, Theight/4. ) );
    }
    else if( theta >= 3.*Pi/4. || theta <= -3.*Pi/4. )
    {
        normal = ToXyz( vec3( -Height, 0., Swidth/4. ) );
    }
}
...

```



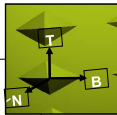
## Generalized Bump Mapping: Using the Surface Local Transform, III

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```

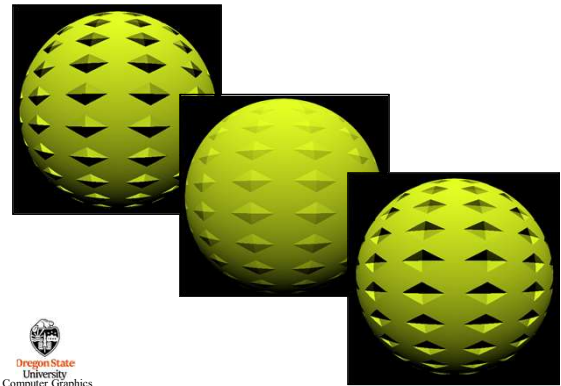
...
vec3 ambient = uKa * myColor;
float d = 0.;
float s = 0.
if( dot(normal,Light) > 0. // only do specular if the light can see the point
{
    d = dot(normal,Light);
    vec3 R = normalize( reflect( -Light, normal ) ); // reflection vector
    s = pow( max( dot(Eye,R), 0. ), uShininess );
}
vec3 diffuse = uKd * d * myColor;
vec3 specular = uKs * s * uSpecularColor;
gl_FragColor = vec4( ambient + diffuse + specular, 1. );
}

```



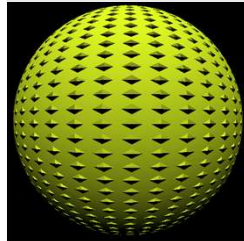
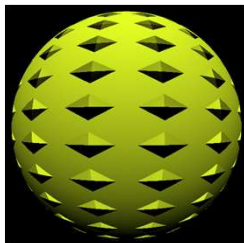
## Changing the Bump Height

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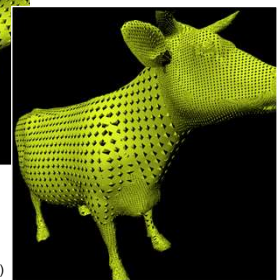
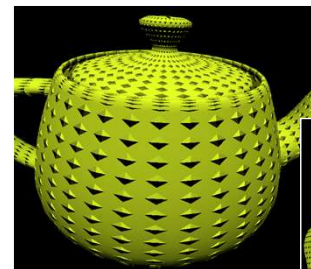
## Changing the Bump Density

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## Different Objects

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Cow Pox? :-)

