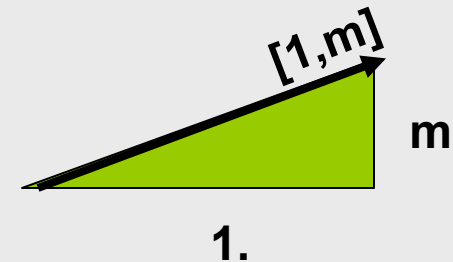
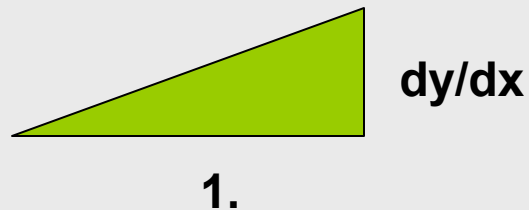
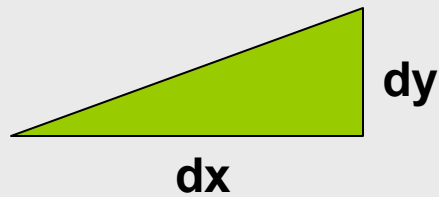
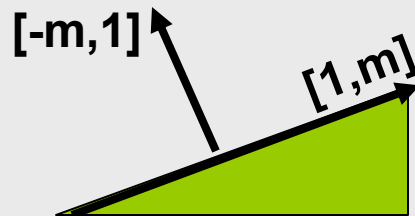


In 2D, a slope $m = dy/dx$. It can be expressed as the vector $[1, m]$.



The normal to the shape is the vector perpendicular to the vector slope:



Note that $[1, m] \cdot [-m, 1] = 0$, as it must be.

So, if $z = -\text{Amp} * \cos(2\pi x / \text{Pd} - 2\pi \text{Time})$, then the slope dz/dx is:

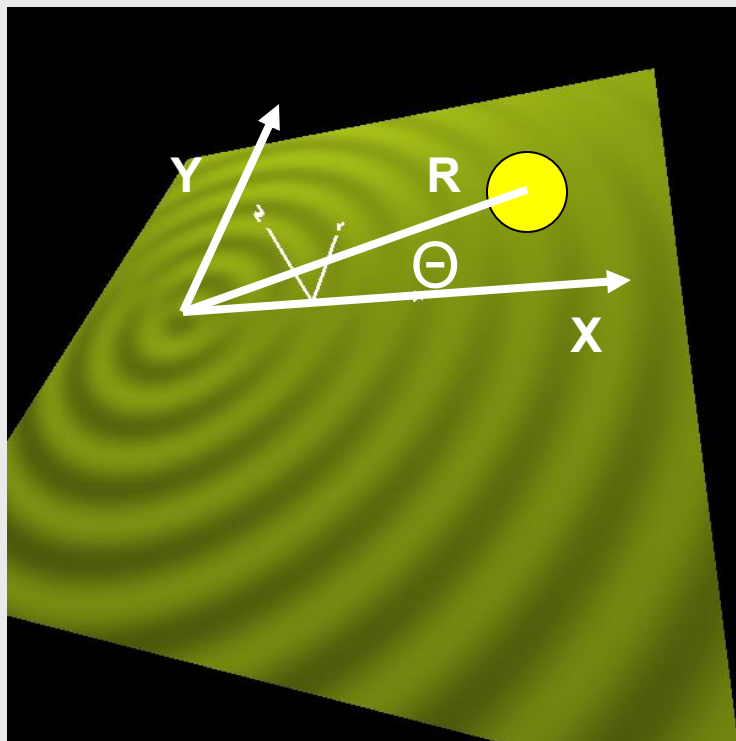
$dz/dx = \text{Amp} * 2\pi / \text{Pd} * \sin(2\pi x / \text{Pd} - 2\pi \text{Time})$, and the vector slope is:

Slope = $[1., 0., \text{Amp} * 2\pi / \text{Pd} * \sin(2\pi x / \text{Pd} - 2\pi \text{Time})]$

Following the pattern from before, the normal vector is:

$$[\text{Normal}] = [-\text{Amp} * 2\pi/\text{Pd} * \sin(2\pi x/\text{Pd} - 2\pi \text{Time}), 0., 1.]$$

This is true along just the X axis. The trick now is to rotate the normal vector into where we really are. Because we are just talking about a rotation, the transformation is the same as if we were rotating a vertex.



$$N_x' = N_x * \cos\Theta - N_y * \sin\Theta = N_x * \cos\Theta$$

$$N_y' = N_x * \sin\Theta + N_y * \cos\Theta = N_x * \sin\Theta$$

$$N_z' = N_z = 1.$$

(Note that in the final version, you will substitute R for x in the slope equation)