

Nvidia's Compute Unified Device Architecture (CUDA)



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cuda.pptx

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The CUDA Paradigm

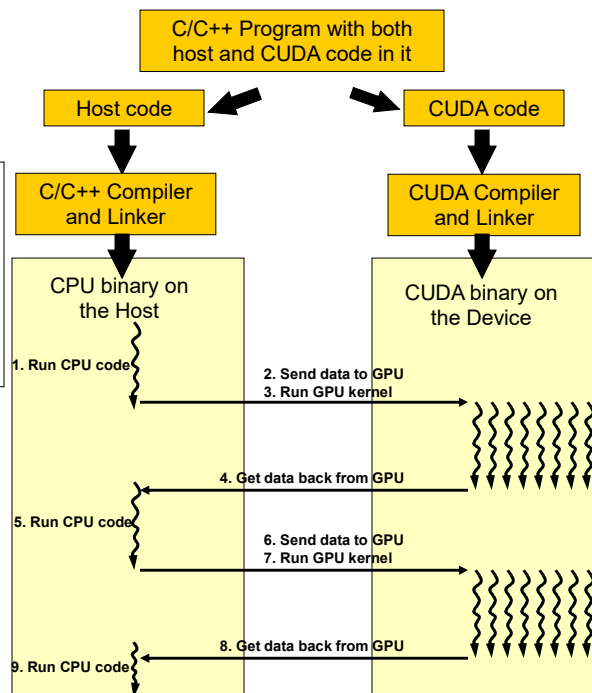
CUDA is an NVIDIA-only product. It is very popular, and got the whole GPU-as-CPU ball rolling, which has resulted in other packages like OpenCL.

CUDA also comes with several libraries that are highly optimized for applications such as linear algebra and deep learning.



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CUDA wants you to break the problem up into Pieces

If you were writing
in **C/C++**, you
would say:

```
void
ArrayMult( int n, float *a, float *b, float *c)
{
    for ( int i = 0; i < n; i++ )
        c[ i ] = a[ i ] * b[ i ];
}
```

If you were writing in
CUDA, you would say:

```
__global__
void
ArrayMult( float *dA, float *dB, float *dC )
{
    int gid = blockIdx.x*blockDim.x + threadIdx.x;
    dC[gid] = dA[gid] * dB[gid];
}
```



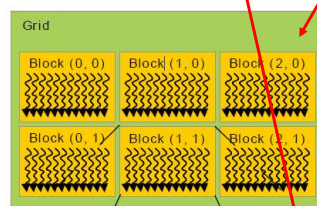
Think of this as having an implied for-loop around it,
looping through all possible values of *gid*

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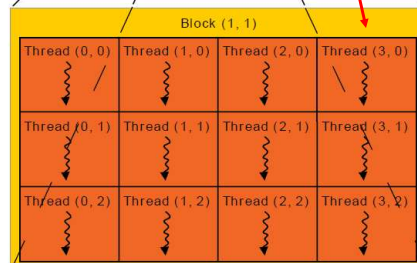
Organization: Blocks are Arranged in Grids

- The GPU's workload is divided into a **Grid of Blocks**
- Each Block's workload is divided into a **Grid of Threads**

Grid of Blocks



Grid of Threads

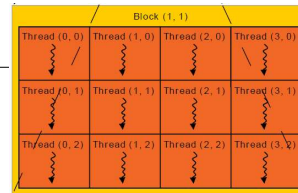


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A Block is made up of a Grid of Threads

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- The threads in a block each have *Thread ID* numbers within the Block
- Your CUDA program will use these Thread IDs to select work to do and pull the right data from memory
- Threads share data and synchronize while doing their share of the work
- Every **32** threads constitute a "*Warp*". Each thread in a Warp simultaneously executes the same instruction on different pieces of data.
- But, it is likely that a Warp's execution will need to stop at some point, waiting for a memory access. This would make the execution go idle – bad! So, it is worthwhile to have multiple Warps worth of threads available so that when one Warp blocks, another Warp can be swapped in.
- The threads in a *Thread Block* can cooperate with each other by:
 - Synchronizing their execution
 - Efficiently sharing data through a low latency shared memory
- Threads from different blocks cannot cooperate

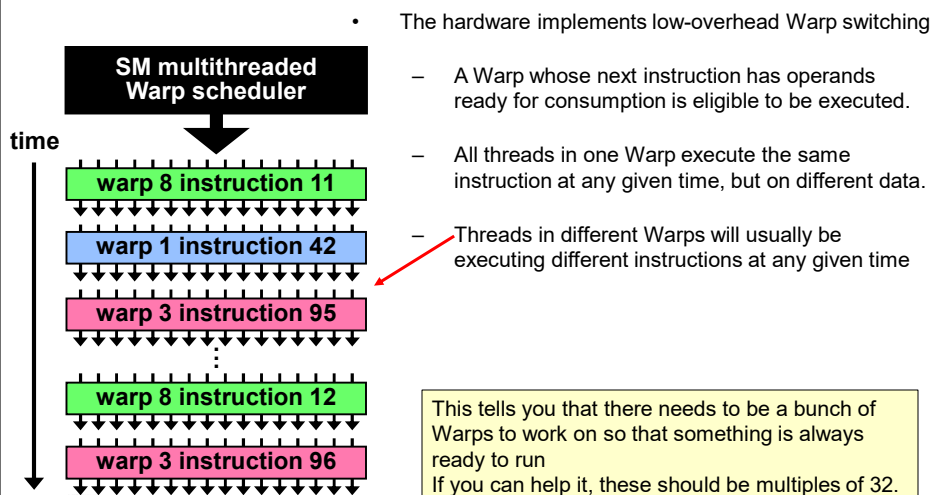


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Scheduling

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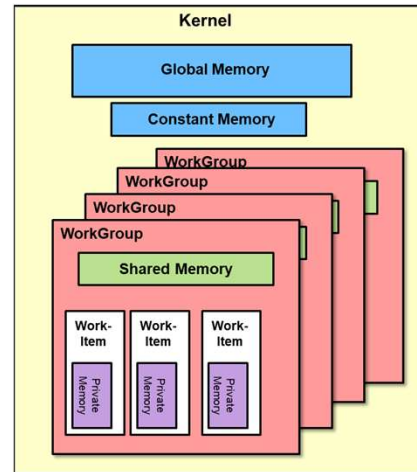


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Threads Can Access Various Types of Storage

- Each thread has access to:
 - Its own R/W per-thread **registers**
 - Its own R/W per-thread **private memory**
- Each thread has access to:
 - Its block's R/W per-block **shared memory**
- Each thread has access to:
 - The entire R/W per-grid **global memory**
 - The entire read-only per-grid **constant memory**
 - The entire read-only per-grid **texture memory**
- The CPU can read and write **global and, constant** memories



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Different Types of CUDA Memory

Memory	Location	Who Uses
Registers	On-chip	One thread
Private	On-chip	One thread
Shared	On-chip	All threads in that block
Global	Off-chip	All threads + Host
Constant	Off-chip	All threads + Host



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Thread Rules

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- Each Thread has its own registers and private memory
- Each Block can use at most some maximum number of registers, divided equally among all Threads
- Threads can share local memory with the other Threads in the same Block
- Threads can synchronize with other Threads in the same Block
- Global and Constant memory is accessible by all Threads in all Blocks
- 192 or 256 are good numbers of Threads per Block (multiples of the Warp size)



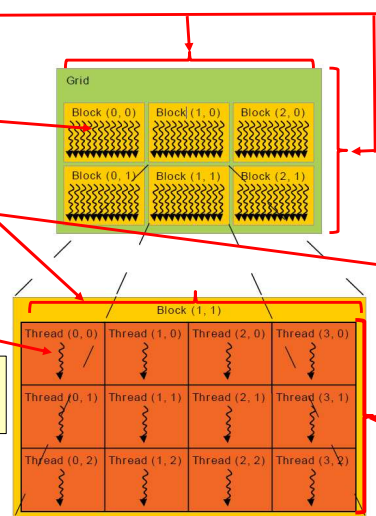
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A CUDA Thread can Query where it Fits in its “Community” of Threads and Blocks

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- `dim3 gridDim;`
 - Dimensions of the blocks in this grid
- `dim3 blockIdx;`
 - This block's indexes within this grid
- `dim3 blockDim;`
 - Dimensions of the threads in this block
- `dim3 threadIdx;`
 - This thread's indexes within the block

Note: It is as if `dim3` is defined as:
`typedef int[3] dim3;`
 (it's not really – it is actually defined within the CUDA compiler)

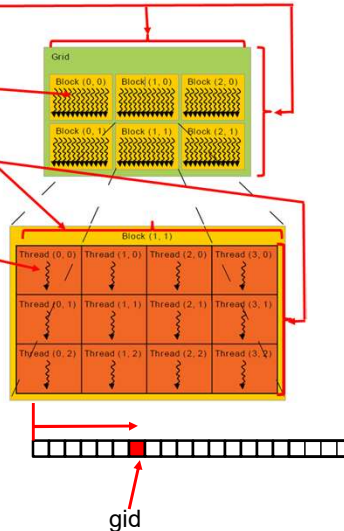


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A CUDA Thread needs to know where it Lives in its “Community” of Threads and Blocks

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- `dim3 gridDim;`
– Dimensions of the blocks in this grid
- `dim3 blockIdx;`
– This block's indexes within this grid
- `dim3 blockDim;`
– Dimensions of the threads in this block
- `dim3 threadIdx;`
– This thread's indexes within the block



For a 1D problem:

```
int blockThreads = blockIdx.x*blockDim.x;
int gid = blockThreads + threadIdx.x;
C[gid] = A[gid]*B[gid];
```

For a 2D problem:

```
int blockNum = blockIdx.y*gridDim.x + blockIdx.x;
int blockThreads = blockNum*blockDim.x*blockDim.y;
int gid = blockThreads + threadIdx.y*blockDim.x + threadIdx.x;
C[gid] = A[gid]*B[gid];
```

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Types of CUDA Functions

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	Executed on the:	Only callable from the:
<code>__device__ float DeviceFunc()</code>	GPU	GPU
<code>__global__ void KernelFunc()</code>	GPU	Host
<code>__host__ float HostFunc()</code>	Host	Host

`__global__` defines a kernel function – it must return `void`

Note: “`__`” is 2 underscore characters

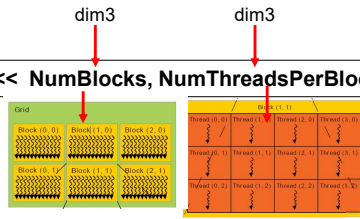
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The C/C++ Program Calls a CUDA Kernel using a Special <<...>> Syntax

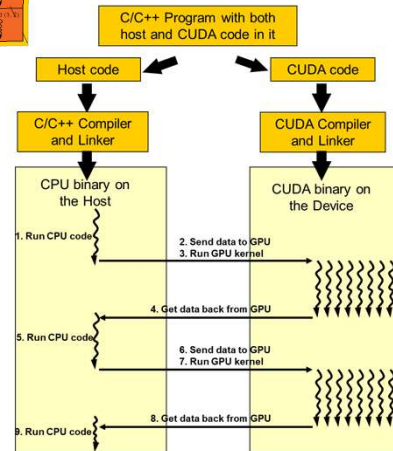
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These are called "chevrons"

```
KernelFunction<< NumBlocks, NumThreadsPerBlock >>>( arg1, arg2, ... );
```



Note that this is just like calling the C/C++ function:
KernelFunction(arg1, arg2, ...);
 except that we have designated it to run on the GPU
 with a particular block/thread configuration.

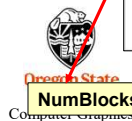
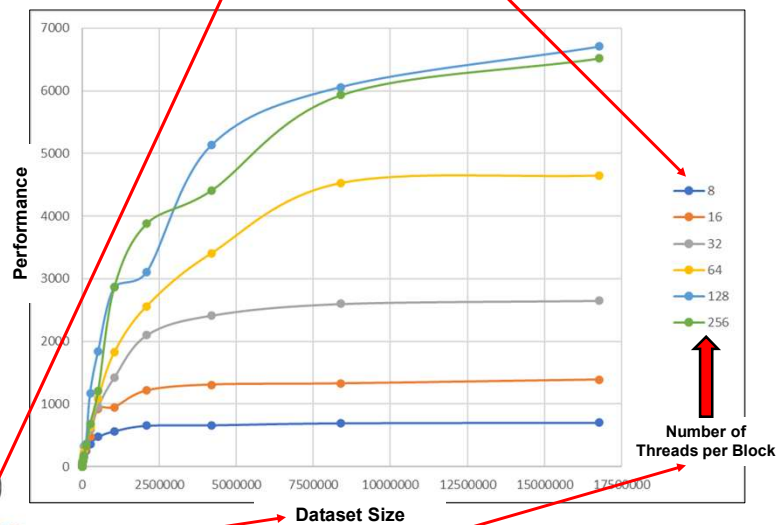


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One of my own Experiments with Number of Threads Per Block

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```
KernelFunction<< NumBlocks, NumThreadsPerBlock >>>( arg1, arg2, ... );
```



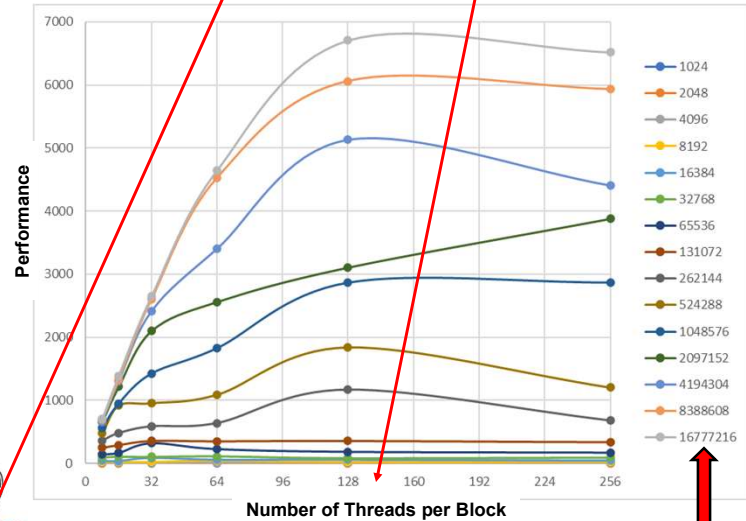
NumBlocks = DataSetSize / NumThreadsPerBlock

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One of my own Experiments with Number of Threads Per Block

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KernelFunction<< NumBlocks, NumThreadsPerBlock >>>(arg1, arg2, ...) ;



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$\text{NumBlocks} = \text{DataSetSize} / \text{NumThreadsPerBlock}$

Dataset Size

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Getting CUDA Programs to Run under Linux

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This is the Makefile we use:

```
CUDA_PATH    = /usr/local/apps/cuda/cuda-10.1
CUDA_BIN_PATH = $(CUDA_PATH)/bin
CUDA_NVCC     = $(CUDA_BIN_PATH)/nvcc
arrayMul:    arrayMul.cu
             $(CUDA_NVCC) -o arrayMul arrayMul.cu
```

This is the path where the CUDA tools are loaded on our Oregon State University systems.

Or, without the Makefile syntax:

```
/usr/local/apps/cuda/cuda-10.1/bin/nvcc -o arrayMul arrayMul.cu
```

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We also have the CUDA-11 and CUDA-12 tools loaded for your use. You can use them if you want. But, given the wide breadth of different Nvidia cards around campus, **CUDA-10** seems to be the one that will run **everywhere**! I recommend you use it.

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Getting CUDA Programs to Run under Visual Studio

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1. Install Visual Studio if you haven't already. If you are an OSU student, go to:

<https://azureforeducation.microsoft.com/devtools>

Click the blue **Sign In** button on the right.
Login using your ONID@oregonstate.edu username and password.
Install **Visual Studio 2022 Enterprise**

2. Install the CUDA toolkit for Windows. It is available here:

https://developer.nvidia.com/cuda-downloads?target_os=Windows&target_arch=x86_64&target_version=11&target_type=exe_local

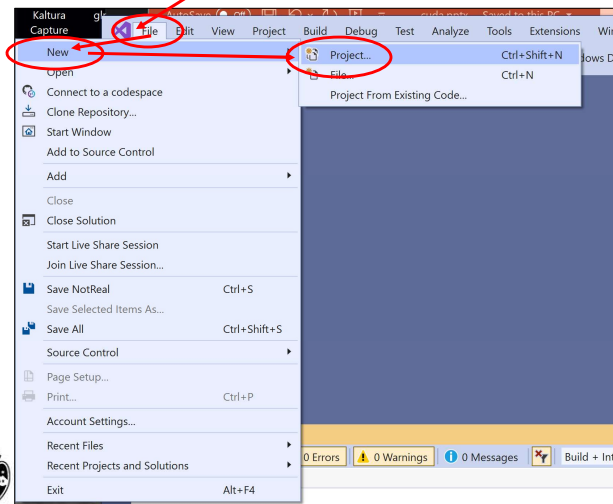


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Getting CUDA Programs to Run under Visual Studio

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From the main screen, click **File** → **New** → **Project...**

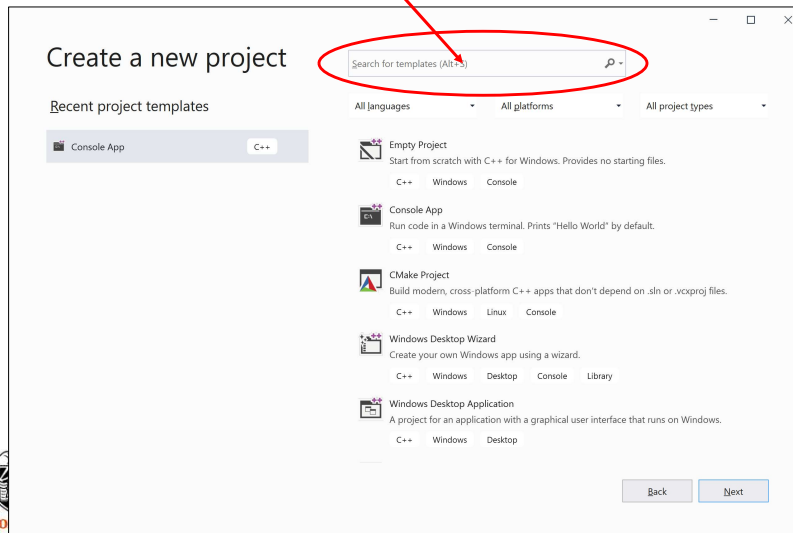


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Getting CUDA Programs to Run under Visual Studio

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Then, in this *templates* box, type: **CUDA**

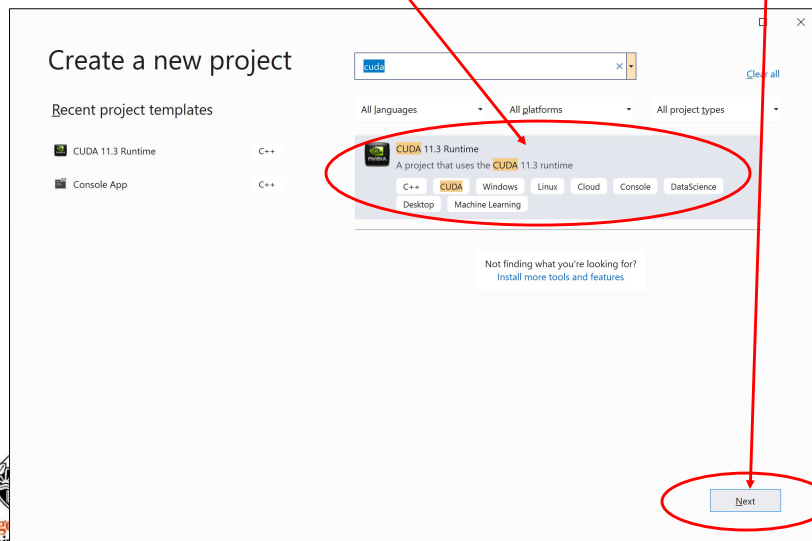


Getting CUDA Programs to Run under Visual Studio

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After a few seconds, you will then see this.

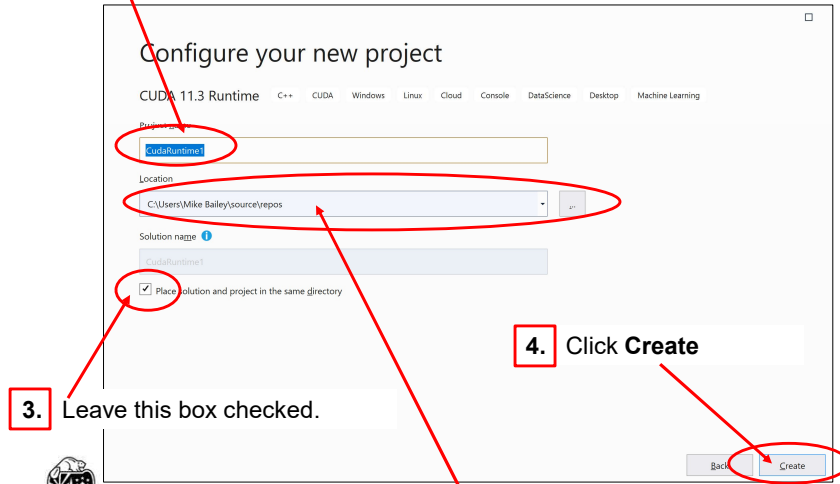
Click **Next**.



Getting CUDA Programs to Run under Visual Studio

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2. Give the name you want for the folder and project

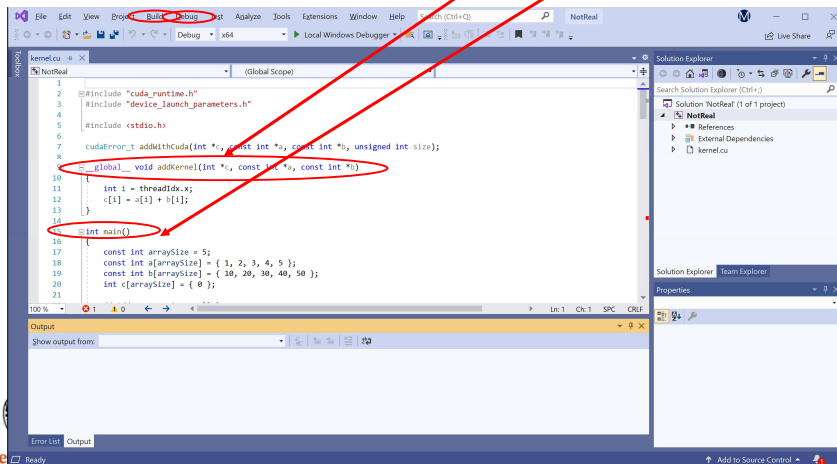


1. Navigate to the folder you want to contain this project folder.

Getting CUDA Programs to Run under Visual Studio

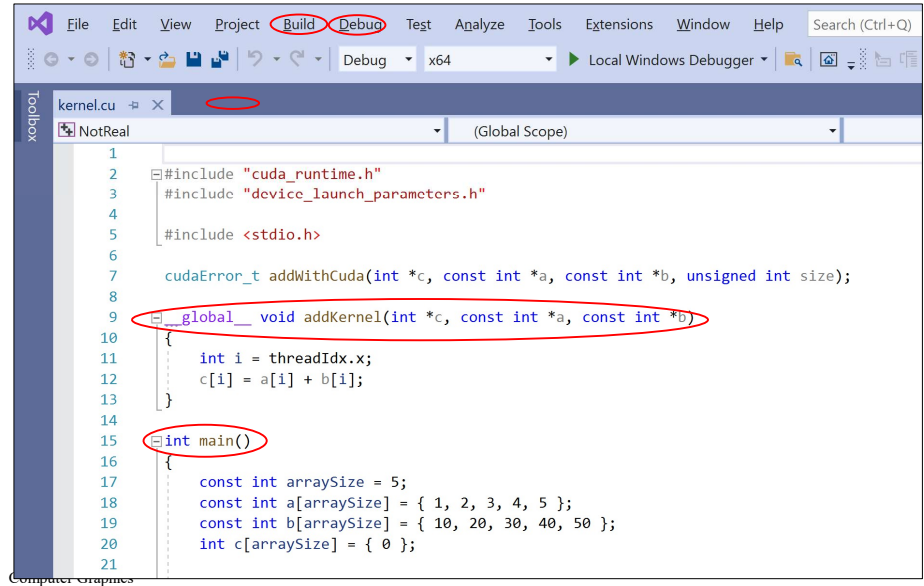
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1. Visual Studio then "writes" a program for you. It has both CUDA and C++ code in it.
2. You can click **Build** → **Build** to compile it, both the C++ and the CUDA code.
3. You can click **Debug** → **Start Without Debugging** to run it.
4. You can then either modify this file, or clear it and paste your own code in.



Getting CUDA Programs to Run under Visual Studio

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```
1
2 #include "cuda_runtime.h"
3 #include "device_launch_parameters.h"
4
5 #include <stdio.h>
6
7 cudaError_t addWithCuda(int *c, const int *a, const int *b, unsigned int size);
8
9 __global__ void addKernel(int *c, const int *a, const int *b)
10 {
11     int i = threadIdx.x;
12     c[i] = a[i] + b[i];
13 }
14
15 int main()
16 {
17     const int arraySize = 5;
18     const int a[arraySize] = { 1, 2, 3, 4, 5 };
19     const int b[arraySize] = { 10, 20, 30, 40, 50 };
20     int c[arraySize] = { 0 };
21 }
```

Using CUDA and OpenMP Together

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This is the Makefile we use on Linux:

```
CUDA_PATH      = /usr/local/apps/cuda/cuda-10.1
CUDA_BIN_PATH  = $(CUDA_PATH)/bin
CUDA_NVCC      = $(CUDA_BIN_PATH)/nvcc
arrayMul:      arrayMul.cu
               $(CUDA_NVCC) -o arrayMul arrayMul.cu -Xcompiler -fopenmp
```

Or, on Linux, but without the Makefile syntax:

```
/usr/local/apps/cuda/cuda-10.1/bin/nvcc -o arrayMul arrayMul.cu -Xcompiler -fopenmp
```

Or, in Visual Studio:

1. Go to the Project menu → Project Properties
2. Change the setting Configuration Properties → C/C++ → Language → OpenMP Support to "Yes (/openmp)"



We also have the CUDA-11 and CUDA-12 tools loaded for your use. You can use them if you want. But, given the wide breadth of different Nvidia cards around campus, **CUDA-10** seems to be the one that will run **everywhere**! I recommend you use it.

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Using Multiple GPU Cards with CUDA

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```
int deviceCount;  
cudaGetDeviceCount( &deviceCount );  
  
...  
  
int device;      // 0 ≤ device ≤ deviceCount - 1  
cudaSetDevice( device );
```