The Functional (or Task) Decomposition Design Pattern

A good example of this is the computer game SimPark.

How is this different from Data Decomposition (such as the OpenMP for-loops)

- This is done less for performance and more for programming convenience.
- This is often done in simulations, where each quantity in the simulation needs to make decisions about what it does next based on what it and all the other global quantities are doing right now.
- Each quantity takes all of the “Now” state data and computes its own “Next” state.
- The biggest trick is to synchronize the different quantities so that each of them is seeing only what the others’ data values are right now. Nobody is allowed to switch their data states until they are all done consuming the current data and thus are ready to switch together.
- The synchronization is accomplished with barriers.
Setup the Now global variables

Calculate the current Environmental Parameters

Spawn Threads using OpenMP Sections

Watcher

A

B

DoneComputing barrier

DoneAssigning barrier

Print results and increment time

Calculate new Environmental Parameters

DonePrinting barrier

The Functional Decomposition Design Pattern

int main( int argc, char *argv[] )
{
    omp_set_num_threads( 3 );
    // don't worry about this for now, we will get to this later

    #pragma omp parallel sections
    {
        #pragma omp section
        {
            Watcher( );
        }
        #pragma omp section
        {
            Animals( );
        }
        #pragma omp section
        {
            Plants( );
        }
    } // implied barrier -- all functions must return to get past here

    void Watcher()
    {
        while( << You decide how to know when it's all finished? >> )
        {
            // do nothing
            WaitBarrier( ); // 1.
            // do nothing
            WaitBarrier( ); // 2.
            << write out the "Now" state of data >>
            << advance time and re-compute all environmental variables >>
            WaitBarrier( ); // 3.
        }
    }

    void Animals()
    {
        while( << You decide how to know when it's all finished? >> )
        {
            int nextXXX= << function of what all states are right Now >>
            WaitBarrier( ); // 1.
            NowXXX = nextXXX; // copy the computed next state to the Now state
            WaitBarrier( ); // 2.
            if( do nothing )
                WaitBarrier( ); // 3.
        }
    }

    #pragma omp parallel sections
    {
        #pragma omp section
        {
            Watcher( );
        }
        #pragma omp section
        {
            Animals( );
        }
        #pragma omp section
        {
            Plants( );
        }
    } // implied barrier -- all functions must return to get past here

    // implied barrier -- all functions must return to get past here
}
Sometimes You Have to Make Your Own Barrier Function

```c
omp_lock_t Lock;
volatile int NumInThreadTeam;
volatile int NumAtBarrier;
volatile int NumGone;

void InitBarrier( int n )
{
    NumInThreadTeam = n; // number of threads you want to block at the barrier
    NumAtBarrier = 0;
   omp_init_lock( &Lock );
}

void WaitBarrier( )
{
    omp_set_lock( &Lock );
    {
        NumAtBarrier++;
        if( NumAtBarrier == NumInThreadTeam ) // release the waiting threads
            NumGone = 0;
            NumAtBarrier = 0;
            // let all other threads return before this one unlocks:
            while( NumGone != NumInThreadTeam - 1 );
            omp_unset_lock( &Lock );
            return;
    }
    omp_unset_lock( &Lock );
    while( NumAtBarrier != 0 ); // all threads wait here until the last one arrives …
    #pragma omp atomic
    { NumGone++; }
}
```

The WaitAtBarrier( ) Logic

<table>
<thead>
<tr>
<th>Function</th>
<th>Tool</th>
<th>Visual Studio</th>
<th>The Functional Decomposition wants to have #2, because the barriers need to be in different functions</th>
<th>The OpenMP specification only allows for #1.</th>
</tr>
</thead>
<tbody>
<tr>
<td>g++</td>
<td>apparently allows both #1 and #2</td>
<td>Visual Studio requires #1</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

You Might Have to Make Your Own Barrier Function

Why can’t we just use `#pragma omp barrier`?
The Functional Decomposition is a good example of when you sometimes can’t.

There are two ways to think about how to allow a program to implement a barrier:
1. Make a thread block at a specific location in the code. Keep blocking until all threads have blocked there.
2. Make a thread block when it asks to “Wait”. Keep blocking until all threads have blocked by asking to “Wait”.

```c
omp_lock_t Lock;
volatile int NumInThreadTeam;
volatile int NumAtBarrier;
volatile int NumGone;

void InitBarrier( int n )
{
    NumInThreadTeam = n; // number of threads you want to block at the barrier
    NumAtBarrier = 0;
    omp_init_lock( &Lock );
}

void WaitAtBarrier( )
{
    omp_set_lock( &Lock );
    {
        NumAtBarrier++;
        if( NumAtBarrier == NumInThreadTeam ) // release the waiting threads
            NumGone = 0;
            NumAtBarrier = 0;
            // let all other threads return before this one unlocks:
            while( NumGone != NumInThreadTeam - 1 );
            omp_unset_lock( &Lock );
            return;
    }
    omp_unset_lock( &Lock );
    while( NumAtBarrier != 0 ); // all threads wait here until the last one arrives …
    #pragma omp atomic
    { NumGone++; }
}
```