Vertex Buffers

Mike Bailey
mjb@cs.oregonstate.edu

This work is licensed under a Creative Commons Attribution-NonCommercial-NoDerivatives 4.0 International License
What is a Vertex Buffer?

Vertex Buffers are how you draw things in Vulkan. They are very much like Vertex Buffer Objects in OpenGL, but more detail is exposed to you (a lot more…).

But, the good news is that Vertex Buffers are really just ordinary Data Buffers, so some of the functions will look familiar to you.

First, a quick review of computer graphics geometry . . .
Geometry: Where things are (e.g., coordinates)

Topology: How things are connected

Original Object

Geometry = changed
Topology = same (1-2-3-4-1)

Geometry = same
Topology = changed (1-2-4-3-1)
typedef enum VkPrimitiveTopology
{
    VK_PRIMITIVE_TOPOLOGY_POINT_LIST = 0,
    VK_PRIMITIVE_TOPOLOGY_LINE_LIST = 1,
    VK_PRIMITIVE_TOPOLOGY_LINE_STRIP = 2,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST = 3,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP = 4,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_FAN = 5,
    VK_PRIMITIVE_TOPOLOGY_LINE_LIST_WITH_ADJACENCY = 6,
    VK_PRIMITIVE_TOPOLOGY_LINE_STRIP_WITH_ADJACENCY = 7,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST_WITH_ADJACENCY = 8,
    VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP_WITH_ADJACENCY = 9,
    VK_PRIMITIVE_TOPOLOGY_PATCH_LIST = 10,
} VkPrimitiveTopology;
Vulkan Topologies

- VK_PRIMITIVE_TOPOLOGY_POINT_LIST
- VK_PRIMITIVE_TOPOLOGY_LINE_LIST
- VK_PRIMITIVE_TOPOLOGY_LINE_STRIP
- VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST
- VK_PRIMITIVE_TOPOLOGY_TRIANGLE_STRIP
- VK_PRIMITIVE_TOPOLOGY_TRIANGLE_FAN
Vulkan Topologies – Requirements and Orientation

Polygons must be:
• **Convex** and
• **Planar**

Polygons are traditionally:
• **CCW when viewed from outside the solid object**

It’s not absolutely necessary, but there are possible optimizations if you are **consistent**
OpenGL Topologies – Vertex Order Matters

VK_PRIMITIVE_TOPOLOGY_LINE_STRIP

VK_PRIMITIVE_TOPOLOGY_LINE_STRIP
What does “Convex Polygon” Mean?

We could go all mathematical here, but let’s go visual instead. In a convex polygon, a line between any two points inside the polygon never leaves the inside of the polygon.
What does “Convex Polygon” Mean?

OK, now let’s go all mathematical. In a convex polygon, every interior angle is between 0° and 180°.
Why is there a Requirement for Polygons to be Convex?

Graphics polygon-filling hardware can be highly optimized if you know that, no matter what direction you fill the polygon in, there will be two and only two intersections between the scanline and the polygon’s edges.
What if you need to display Polygons that are not Convex?

There is an open source library to break a non-convex polygon into convex polygons. It is called *Polypartition*, and is found here:

https://github.com/ivanfratric/polypartition

If you ever need to do this, contact me. I have working code …
Why is there a Requirement for Polygons to be Planar?

Graphics hardware assumes that a polygon has a definite front and a definite back, and that you can only see one of them at a time.
Vertex Orientation Issues

Thanks to OpenGL, we are all used to drawing in a right-handed coordinate system. Internally, however, the Vulkan pipeline uses a left-handed system:

The best way to handle this is to continue to draw in a RH coordinate system and then fix it up in the GLM projection matrix, like this:

```
ProjectionMatrix[1][1] *= -1.;
```

This is like saying “Y’ = -Y”.
static GLuint CubeTriangleIndices[ ][3] =
{ 
    { 0, 2, 3 },
    { 0, 3, 1 },
    { 4, 5, 7 },
    { 4, 7, 6 },
    { 1, 3, 7 },
    { 1, 7, 5 },
    { 0, 4, 6 },
    { 0, 6, 2 },
    { 2, 6, 7 },
    { 2, 7, 3 },
    { 0, 1, 5 },
    { 0, 5, 4 }
};

static GLfloat CubeColors[ ][3] =
{ 
    { 0., 0., 0. },
    { 1., 0., 0. },
    { 0., 1., 0. },
    { 1., 1., 0. },
    { 0., 0., 1. },
    { 1., 0., 1. },
    { 0., 1., 1. },
    { 1., 1., 1. },
};

static GLfloat CubeVertices[ ][3] =
{ 
    { -1., -1., -1. },
    { 1., -1., -1. },
    { -1., 1., -1. },
    { 1., 1., -1. },
    { -1., -1., 1. },
    { 1., -1., 1. },
    { -1., 1., 1. },
    { 1., 1., 1. }
};
Triangles in an Array of Structures

From the file SampleVertexData.cpp:

```cpp
struct vertex
{
    glm::vec3    position;
    glm::vec3    normal;
    glm::vec3    color;
    glm::vec2    texCoord;
};

struct vertex VertexData[ ] =
{
    // triangle 0-2-3:
    // vertex #0:
    {
        { -1., -1., -1. },
        {  0.,  0., -1. },
        {  0.,  0.,  0. },
        {  1., 0. }
    },
    // vertex #2:
    {
        { -1.,  1., -1. },
        {  0.,  0., -1. },
        {  0.,  1.,  0. },
        {  1., 1. }
    },
    // vertex #3:
    {
        {  1.,  1., -1. },
        {  0.,  0., -1. },
        {  1.,  1.,  0. },
        {  0., 1. }
    }
};
```

Modeled in right-handed coordinates
Vertex Orientation Issues

This object was modeled such that triangles that face the viewer will look like their vertices are oriented CW (this is detected by looking at vertex orientation at the start of the rasterization).

Because this 3D object is closed, Vulkan can save rendering time by not even bothering with triangles whose vertices look like they are oriented CW. This is called **backface culling**.

Vulkan’s change in coordinate systems can mess up the backface culling.

So I recommend, at least at first, that you do **no culling**.

```cpp
VkPipelineRasterizationStateCreateInfo vprsci;

... vprsci.cullMode = VK_CULL_MODE_NONE
vprsci.frontFace = VK_FRONT_FACE_COUNTER_CLOCKWISE;
```
Filling the Vertex Buffer

MyBuffer MyVertexDataBuffer;

Init05MyVertexDataBuffer( sizeof(VertexData), &MyVertexDataBuffer );
Fill05DataBuffer( MyVertexDataBuffer, (void *) VertexData );

VkResult
Init05MyVertexDataBuffer( IN VkDeviceSize size, OUT MyBuffer * pMyBuffer )
{
    VkResult result = Init05DataBuffer( size, VK_BUFFER_USAGE_VERTEX_BUFFER_BIT, pMyBuffer );
    return result;
}
A Reminder of What Init05DataBuffer Does

```c
VkResult
Init05DataBuffer( VkDeviceSize size, VkBufferUsageFlags usage, OUT MyBuffer * pMyBuffer )
{
    VkResult result = VK_SUCCESS;
    VkBufferCreateInfo vbci;
    vbci.sType = VK_STRUCTURE_TYPE_BUFFER_CREATE_INFO;
    vbci.pNext = nullptr;
    vbci.flags = 0;
    vbci.size = pMyBuffer->size = size;
    vbci.usage = usage;
    vbci.sharingMode = VK_SHARING_MODE_EXCLUSIVE;
    vbci.queueFamilyIndexCount = 0;
    vbci.pQueueFamilyIndices = (const uint32_t *)nullptr;
    result = vkCreateBuffer ( LogicalDevice, IN &vbci, PALLOCATOR, OUT &pMyBuffer->buffer );

    VkMemoryRequirements vmr;
    vkGetBufferMemoryRequirements( LogicalDevice, IN pMyBuffer->buffer, OUT &vmr ); // fills vmr

    VkMemoryAllocateInfo vmai;
    vmai.sType = VK_STRUCTURE_TYPE_MEMORY_ALLOCATE_INFO;
    vmai.pNext = nullptr;
    vmai.allocationSize = vmr.size;
    vmai.memoryTypeIndex = FindMemoryThatIsHostVisible( );

    VkDeviceMemory vdm;
    result = vkAllocateMemory( LogicalDevice, IN &vmai, PALLOCATOR, OUT &vdm );
    pMyBuffer->vdm = vdm;

    result = vkBindBufferMemory( LogicalDevice, pMyBuffer->buffer, IN vdm, 0 ); // 0 is the offset
    return result;
}
```
We will come to the Pipeline later, but for now, know that a Vulkan pipeline is essentially a very large data structure that holds (what OpenGL would call) the state, including how to parse its input.

```c
struct vertex
{
    glm::vec3 position;
    glm::vec3 normal;
    glm::vec3 color;
    glm::vec2 texCoord;
};
```

```
layout( location = 0 ) in vec3 aVertex;
layout( location = 1 ) in vec3 aNormal;
layout( location = 2 ) in vec3 aColor;
layout( location = 3 ) in vec2 aTexCoord;
```

```c
VkVertexInputBindingDescription vvibd[1]; // one of these per buffer data buffer
    vvibd[0].binding = 0; // which binding # this is
    vvibd[0].stride = sizeof( struct vertex ); // bytes between successive structs
    vvibd[0].inputRate = VK_VERTEX_INPUT_RATE_VERTEX;
```
Telling the Pipeline Data Structure about its Input

```cpp
struct vertex {
    glm::vec3 position;
    glm::vec3 normal;
    glm::vec3 color;
    glm::vec2 texCoord;
};
```

```cpp
VkVertexInputAttributeDescription vviad[4]; // array per vertex input attribute
    // 4 = vertex, normal, color, texture coord
vviad[0].location = 0; // location in the layout decoration
vviad[0].binding = 0; // which binding description this is part of
vviad[0].format = VK_FORMAT_VEC3; // x, y, z
vviad[0].offset = offsetof( struct vertex, position ); // 0

vviad[1].location = 1;
vviad[1].binding = 0;
vviad[1].format = VK_FORMAT_VEC3; // nx, ny, nz
vviad[1].offset = offsetof( struct vertex, normal ); // 12

vviad[2].location = 2;
vviad[2].binding = 0;
vviad[2].format = VK_FORMAT_VEC3; // r, g, b
vviad[2].offset = offsetof( struct vertex, color ); // 24

vviad[3].location = 3;
vviad[3].binding = 0;
vviad[3].format = VK_FORMAT_VEC2; // s, t
vviad[3].offset = offsetof( struct vertex, texCoord ); // 36
```

layout( location = 0 ) in vec3 aVertex;
layout( location = 1 ) in vec3 aNormal;
layout( location = 2 ) in vec3 aColor;
layout( location = 3 ) in vec2 aTexCoord;
We will come to the Pipeline later, but for now, know that a Vulkan Pipeline is essentially a very large data structure that holds (what OpenGL would call) the state, including how to parse its input.

```cpp
VkPipelineVertexInputStateCreateInfo vpvisci; // used to describe the input vertex attributes
vpvisci.sType = VK_STRUCTURE_TYPE_PIPELINE_VERTEX_INPUT_STATE_CREATE_INFO;
vpvisci.pNext = nullptr;
vpvisci.flags = 0;
vpvisci.vertexBindingDescriptionCount = 1;
vpvisci.pVertexBindingDescriptions = vvibd;
vpvisci.vertexAttributeDescriptionCount = 4;
vpvisci.pVertexAttributeDescriptions = vviad;

VkPipelineInputAssemblyStateCreateInfo vpiasci;
vpasci.sType = VK_STRUCTURE_TYPE_PIPELINE_INPUT_ASSEMBLY_STATE_CREATE_INFO;
vpasci.pNext = nullptr;
vpasci.flags = 0;
vpasci.topology = VK_PRIMITIVE_TOPOLOGY_TRIANGLE_LIST;
```
Telling the Pipeline Data Structure about its Input

We will come to the Pipeline later, but for now, know that a Vulkan Pipeline is essentially a very large data structure that holds (what OpenGL would call) the state, including how to parse its input.

```cpp
VkGraphicsPipelineCreateInfo vgpci;
    vgpci.sType = VK_STRUCTURE_TYPE_GRAPHICS_PIPELINE_CREATE_INFO;
    vgpci.pNext = nullptr;
    vgpci.flags = 0;
    vgpci.stageCount = 2;                // number of shader stages in this pipeline
    vgpci.pStages = vpssci;
    vgpci.pVertexInputState = &vpvisci;
    vgpci.pInputAssemblyState = &vpiasci;
    vgpci.pTessellationState = (VkPipelineTessellationStateCreateInfo *)nullptr;            // &vptsci
    vgpci.pViewportState = &vpvsci;
    vgpci.pRasterizationState = &vprsci;
    vgpci.pMultisampleState = &vpmsci;
    vgpci.pDepthStencilState = &vpdssci;
    vgpci.pColorBlendState = &vpcbsci;
    vgpci.pDynamicState = &vpdsci;
    vgpci.layout = IN GraphicsPipelineLayout;
    vgpci.renderPass = IN RenderPass;
    vgpci.subpass = 0;                              // subpass number
    vgpci.basePipelineHandle = (VkPipeline) VK_NULL_HANDLE;
    vgpci.basePipelineIndex = 0;

result = vkCreateGraphicsPipelines( LogicalDevice, VK_NULL_HANDLE, 1, IN &vgpci,
                                          PALLOCATOR, OUT pGraphicsPipeline );
```
We will come to Command Buffers later, but for now, know that you will specify the vertex buffer that you want drawn.

```c
VkBuffer buffers[1] = MyVertexDataBuffer.buffer;

vkCmdBindVertexBuffers(CommandBuffers[nextImageIndex], 0, 1, buffers, offsets);

const uint32_t vertexCount = sizeof(VertexData) / sizeof(VertexData[0]);
const uint32_t instanceCount = 1;
const uint32_t firstVertex = 0;
const uint32_t firstInstance = 0;

vkCmdDraw(CommandBuffers[nextImageIndex], vertexCount, instanceCount, firstVertex, firstInstance);
```

Don’t ever hardcode the size of an array! Always get the compiler to generate it for you.

```c
const uint32_t vertexCount = 100;
```