

HW Note:

$$9.1 - iv) \frac{1}{u} \int u g dx = \frac{1}{e^{-x}} \int e^{-x} dx$$

$$y = e^x \left(\int e^{-x} dt + c \right)$$

$$\text{@ } y(0) = e$$

$$e = e^0 (0 + c) \rightarrow c = 1$$

Linear Dependence / Independence

(Think of a function like an infinite vector)

$$v = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$f(t) = t^2 \begin{bmatrix} 4 \\ 9 \\ \vdots \end{bmatrix}$$

BH of a stretch but still...

$x_1(t)$ and $x_2(t)$ are linearly independent if

$$c_1 x_1(t) + c_2 x_2(t) = 0 \text{ for all } t \text{ only have trivial solutions } c_1, c_2.$$

(Only have solutions if $c_1 = c_2 = 0$)

Ex) Are t and t^2 linearly independent?

$$c_1 t + c_2 t^2 = 0 \text{ for all } t.$$

Now we have infinitely many equations (for all t)

$$t=1 \Rightarrow c_1 + c_2 = 0 \quad \begin{matrix} (c_1 + c_2 = 0) \cdot 2 \\ \hline \end{matrix}$$

$$t=2 \Rightarrow 2c_1 + 4c_2 = 0 \quad \begin{matrix} 2c_1 + 4c_2 = 0 \\ \hline \end{matrix}$$

\vdots

$$2c_1 + 2c_2 = 0$$

$$-2c_1 + 4c_2 = 0$$

$$0 - 2c_2 = 0$$

$$c_2 = 0$$

$$c_1 = 0 - c_2 \rightarrow c_1 = 0 - 0 = 0$$

Because $c_1 = c_2 = 0$, then sometimes t & t^2 are linearly independent.

But $t = t + (-1)t^2 = 0$ So why does this not work?

$\rightarrow t$ is not constant \rightarrow It cannot be used as a constant scaling factor.

So we can't use \rightarrow to say t and t^2 are lin. dep.

Now with more equations:

$x_1(t), x_2(t), \dots, x_n(t)$ are lin. ind. if the equation $c_1 x_1(t) + c_2 x_2(t) + \dots + c_n x_n(t) = 0$ for all t only has trivial solutions $c_1 = c_2 = \dots = c_n = 0$.

Ex) $1, t, t^2, t^3, \dots, t^{10}$. Are lin. ind.?

$$c_0(1) + c_1(t) + c_2(t^2) + \dots + c_{10}(t^{10}) = 0 \quad \forall t.$$

We still have infinite equations to play with but if we use 11 equations to solve for 11 unknowns

Tuan will retire early.

Easier way: $t=0: c_0=0$

$$t(c_1 + c_2 t + c_3 t^2 + \dots + c_{10} t^9) = 0 \quad \forall t \quad (\text{So } t=0)$$

Plug in $t=0: c_1=0$

Like a sniper, isolate and kill one at a time.

OR

A 10^{th} degree polynomial has at most 10 roots and if one of the c_i 's is 0 then the # roots might change but can never exceed the degree.

Because this poly has ∞ many roots, $c_0 = c_1 = c_2 = \dots = c_{10} = 0$.

Now an example of lin dep.:

Ex) $\sin^2 t, \cos^2 t, 1$

$$(1)\sin^2(t) + (1)\cos^2 t + (-1)(1) = 0$$

So $c_1 = 1, c_2 = 1$ and $c_3 = -1$

(because $\sin^2 t + \cos^2 t = 1$)

But this is rare, linear independence is much more common

↳ Almost always.

Wronskian Function of $x_1(t), x_2(t), \dots, x_n(t)$ is

$$W(t) = \begin{bmatrix} x_1(t) & x_2(t) & x_3(t) & \dots & x_n(t) \\ x_1'(t) & x_2'(t) & x_3'(t) & \dots & x_n'(t) \\ x_1''(t) & x_2''(t) & x_3''(t) & \dots & x_n''(t) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ x_1^{(n-1)}(t) & x_2^{(n-1)}(t) & x_3^{(n-1)}(t) & \dots & x_n^{(n-1)}(t) \end{bmatrix}$$

Should be an $n \times n$ matrix.

If $W(t) \neq 0$ for some t then $x_1(t), x_2(t), \dots, x_n(t)$ are lin ind.

Why?

$$c_1 x_1(t) + c_2 x_2(t) + \dots + c_n x_n(t) = 0 \quad \forall t$$

$$\text{So } c_1 x_1'(t) + \dots + c_n x_n'(t) = 0 \quad \forall t$$

$$c_1 x_1''(t) + \dots + c_n x_n''(t) = 0 \quad \forall t \text{ for all derivatives.}$$

So if we scale each column by a constant in $W(t)$ then we get 0.

But we know the columns of $W(t)$ are lin ind because the $\det(W(t)) \neq 0 \quad \forall t$.

$$c_1 \begin{bmatrix} x_1(t) \\ x_1'(t) \\ \vdots \\ x_1^{(n-1)}(t) \end{bmatrix} + \dots + c_n \begin{bmatrix} x_n(t) \\ x_n'(t) \\ \vdots \\ x_n^{(n-1)}(t) \end{bmatrix} = 0$$

$\det(W(t)) = 0$ means

So the equations are lin. ind. because $c_1 \rightarrow c_n = 0$

This is a hard way to check this but it does work.

(We would need to find \det of $n \times n$ matrix)

(If $\det \neq 0$ then lin ind)

But we will use this equation later...