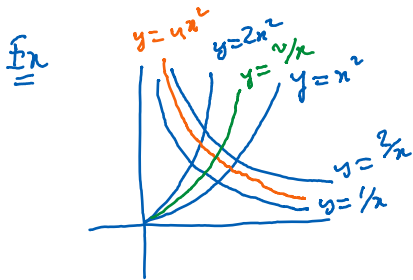


Lecture 31

Thursday, June 13, 2024 1:18 PM

Change of variables:

$$\iint_D f(x,y) dA = \iint_{D'} \bar{f}(u,v) \overbrace{J \, du \, dv}^{dA}, \text{ where } J = \left| \frac{\partial(x,y)}{\partial(u,v)} \right|$$



$$\begin{cases} y = u^2 \\ y = \frac{v}{x} \end{cases} \quad 1 \leq u \leq 2, \quad 1 \leq v \leq 2$$

$$u^2 = \frac{v}{x} \Rightarrow x = \left(\frac{v}{u}\right)^{1/3} = \frac{v^{1/3}}{u^{1/3}} = u^{-1/3} v^{1/3}$$

$$y = u^2 = u \frac{v^{1/3}}{u^{1/3}} = u^{2/3} v^{1/3}$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \left| \det \begin{pmatrix} \frac{1}{3} u^{-4/3} v^{1/3} & \frac{1}{3} u^{-1/3} v^{-2/3} \\ \frac{1}{3} u^{-2/3} v^{1/3} & \frac{2}{3} u^{1/3} v^{-1/3} \end{pmatrix} \right| = \left| -\frac{2}{9} u^{-1} - \frac{1}{9} u^{-1} \right| = \frac{1}{3u}$$

$$\begin{aligned} \iint_D xy \, dA &= \iint_{[1,2] \times [1,2]} v \, J \, du \, dv = \int_1^2 \int_1^2 v \frac{1}{3u} \, du \, dv = \int_1^2 v \frac{1}{3} \ln(u) \Big|_{u=1}^{u=2} \, dv \\ &= \frac{1}{3} \ln 2 \int_1^2 v \, dv \\ &= \frac{1}{3} \ln 2 \frac{v^2}{2} \Big|_1^2 = \frac{\ln 2}{2} \end{aligned}$$

* Change of variable for triple integral:

$$\iiint_E f(x,y,z) \, dV = \iiint_{E'} \bar{f}(u,v,w) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| \, du \, dv \, dw$$

$$\text{where } \frac{\partial(x,y,z)}{\partial(u,v,w)} = \det \begin{pmatrix} \nabla_{u,v,w} x \\ \nabla_{u,v,w} y \\ \nabla_{u,v,w} z \end{pmatrix} = \det \begin{pmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{pmatrix}$$

For cylindrical coords, $\frac{\partial(x,y,z)}{\partial(r,\theta,z)} = r$

For spherical coords, $\frac{\partial(x,y,z)}{\partial(\rho,\phi,\theta)} = \rho^2 \sin\phi$

Vector fields

$F: D \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2$ 2D-vector field

$F: E \subset \mathbb{R}^3 \rightarrow \mathbb{R}^3$ 3D-vector field

Practice sketching vector fields

use Mathematica to plot vector fields ...

* Line integral of scalar functions

$$\int_C f(x,y) ds = \int_a^b f(t) |r'(t)| dt$$

where $r(t)$, $a \leq t \leq b$, is the parametrization of the curve C .