

Lecture 25

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$$\dot{x}_1 = \underbrace{p_{11}(t)}_{\rightarrow} x_1 + \underbrace{p_{12}(t)}_{\rightarrow} x_2 + \dots + \underbrace{p_{1n}(t)}_{\rightarrow} x_n + g_1(t)$$

$$\dot{x}_2 = \underbrace{p_{21}(t)}_{\rightarrow} x_1 + \underbrace{p_{22}(t)}_{\rightarrow} x_2 + \dots + \underbrace{p_{2n}(t)}_{\rightarrow} x_n + g_2(t)$$

$$\dot{x}_n = \underbrace{p_{n1}(t)}_{\rightarrow} x_1 + \underbrace{p_{n2}(t)}_{\rightarrow} x_2 + \dots + \underbrace{p_{nn}(t)}_{\rightarrow} x_n + g_n(t)$$

$$\dot{x} = \underbrace{P(t)}_{\leftarrow} x + \underbrace{g}_{\leftarrow}$$

$$\underbrace{\begin{bmatrix} p_{11} & p_{12} & \dots \\ \vdots & \vdots & \ddots \\ p_{n1} & p_{n2} & \dots \end{bmatrix}}_{n \times n} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \end{bmatrix}$$

If P is a diagonal matrix then there is no coupling

$$P = \begin{bmatrix} t & 0 \\ 0 & t^2 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix}}_{x'} = \underbrace{\begin{bmatrix} t & 0 \\ 0 & t^2 \end{bmatrix}}_{P(t)} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

$$\dot{x}_1 = t x_1 + \sin t$$

$$\dot{x}_2 = t^2 x_2 + \cos t$$

P ... diagonal matrix \rightarrow done!

P is not diagonal: if P is diagonalizable then

$$P = Q D Q^{-1}$$

↑
diagonal matrix

$$z' = Pz + g = Q D \underbrace{Q^{-1}z}_y + g$$

$$\underbrace{Q^{-1}z'}_{? y'} = Q^{-1}(Q D y + g) = D y + Q^{-1}g$$

$$y = \underbrace{Q^{-1}z} \quad \dots \quad y' = \underbrace{Q^{-1}z'}$$

$$(fg)' = f'g + fg'$$

$$P = \begin{bmatrix} t & 2t \\ t^2 & -t \end{bmatrix} = \underline{Q} \underline{D} \underline{Q}^{-1}$$

$$y' = \underline{D} y + Q^{-1}g$$

$$x' = Px + \dots$$

$$x' = Px$$

constant matrix

$$x' = ax$$

$$\frac{dx}{dt} = ax \rightarrow \frac{dx}{x} = a dt$$

$$\ln|x| = at + C$$

$$|x| = e^{at+C}$$

$$x = \pm e^C e^{at}$$

$$x = k e^{at}$$

$$X \frac{x'}{x} = P$$

$$x' = v e^{at} = e^{at} v$$

$$x' = Px$$

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix}$$

What are a and v so that $x = e^{at} v$ solve the eq.

$$x' = Px$$

$$\left. \begin{aligned} \rightarrow x' &= \left(e^{at} v \right)' = a e^{at} v \\ Px &= P e^{at} v = e^{at} P v \end{aligned} \right\} \underline{av = Pv}$$

Suppose v is a constant vector:

$$P = \begin{bmatrix} 1 & -1 \\ 4 & 1 \end{bmatrix}$$

If v is an eigenvector & λ is the corresponding eigenvalue then

$$x = e^{\lambda t} v \text{ is a sol. of } x' = Px$$

$$P - \lambda I_2 = \begin{bmatrix} 1-\lambda & -1 \\ 4 & 1-\lambda \end{bmatrix}$$

$$|P - \lambda I_2| = (1-\lambda)^2 - 4 = (1-\lambda)^2 - 2^2 = (1-\lambda)(3-\lambda)$$

$$\lambda_1 = -1, \lambda_2 = 3$$

$$\lambda_1 = -1$$

$$(P - \lambda_1 I_2)v = 0 \iff Pv = \lambda_1 v$$

$$\left[\begin{array}{cc|c} 2 & 1 & 0 \\ 4 & 2 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{cc|c} 1 & 1/2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$v = \begin{bmatrix} a \\ b \end{bmatrix}$$

$$a + \frac{1}{2}b = 0$$

$$b = -2, a = 1$$

$$v = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$v_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \lambda_1 = -1$$

$$v_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \lambda_2 = 3$$

$$x^{(1)} = e^{\lambda_1 t} v_1 = e^{-t} \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$x^{(2)} = e^{\lambda_2 t} v_2 = e^{3t} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Thm

Consider the equation $x' = P(t)x$, where P is an $n \times n$ matrix. There are n linearly independent solutions

$x^{(1)}, x^{(2)}, \dots, x^{(n)}$. Moreover, any solution to the ODE

is a linear comb. of $x^{(1)}, x^{(2)}, \dots, x^{(n)}$.

$x^{(1)}, x^{(2)}, \dots$

lin. ind.

$$x^{(1)} = \begin{bmatrix} x_{11} \\ x_{12} \\ \vdots \\ x_{1n} \end{bmatrix}$$

if the eq.

$$c_1 x^{(1)} + c_2 x^{(2)} + \dots + c_n x^{(n)} = 0 \quad \forall t$$

const.

implies $c_1 = c_2 = \dots = c_n = 0$.

$$x^{(1)} = \begin{bmatrix} 1 \\ t \end{bmatrix}, \quad x^{(2)} = \begin{bmatrix} t \\ t^2 \end{bmatrix} = t \begin{bmatrix} 1 \\ t \end{bmatrix} = t x^{(1)}$$

$$t x^{(1)} - x^{(2)} = 0$$

How can we determine if given vectors are lin. ind.

Ex. $v_1 = \begin{bmatrix} t \\ 2t \end{bmatrix}, v_2 = \begin{bmatrix} t^2 \\ 3t \end{bmatrix}$

$$\det \left(\begin{bmatrix} v_1 & v_2 \end{bmatrix} \right) = \det \begin{pmatrix} t & t^2 \\ 2t & 3t \end{pmatrix} = 3t^2 - 2t^3 \quad \leftarrow$$

$c_1 v_1 + c_2 v_2 = 0$
for $(c_1, c_2) \neq (0, 0)$ $\rightarrow \det \begin{pmatrix} v_1 & v_2 \end{pmatrix} = 0 \quad \forall t$

pick $t=1$. $\det \neq 0 \rightsquigarrow v_1, v_2$ are lin. ind.

$$v_1 = \begin{bmatrix} 1 \\ t \end{bmatrix}, v_2 = \begin{bmatrix} t \\ t^2 \end{bmatrix}$$

$$\det \begin{pmatrix} 1 & t \\ t & t^2 \end{pmatrix} = 0 \quad \forall t$$

$$f^{(1)} = \begin{bmatrix} f_{11} \\ f_{12} \\ \vdots \\ f_{1n} \end{bmatrix}, f^{(2)} = \begin{bmatrix} \phantom{f_{11}} \\ \phantom{f_{12}} \\ \\ \phantom{f_{1n}} \end{bmatrix}, \dots, f^{(k)} = \begin{bmatrix} \phantom{f_{11}} \\ \phantom{f_{12}} \\ \\ \phantom{f_{1n}} \end{bmatrix}$$

$$W[f^{(1)}, \dots, f^{(k)}] = \det \left(\begin{bmatrix} f^{(1)} & f^{(2)} & \dots & f^{(k)} \\ \hline 1 & 1 & \dots & 1 \end{bmatrix} \right) \neq 0 \text{ for some } t$$