

$$Y' = f(Y), \quad Y(t_0) = \boxed{Y_0}$$

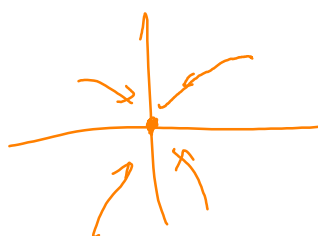
$$\underline{\text{Ex:}} \quad \begin{cases} y_1' = y_1 + y_2^2 \\ y_2' = y_1 y_2 + 2y_2 \end{cases} \quad f \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y_1 + y_2^2 \\ y_1 y_2 + 2y_2 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \vec{0}$$

An equilibrium state is the point where $f(Y) = 0$.

$$\underline{\text{Ex:}} \quad \begin{cases} y_1' = y_1 + 2y_2 \\ y_2' = 3y_1 + 2y_2 \end{cases}$$



$$\textcircled{2} \quad \begin{cases} y_1' = y_1 + y_2 \\ y_2' = 2y_2 \end{cases}$$



$$\textcircled{3} \quad \begin{cases} y_1' = -y_1 \\ y_2' = -y_1 - 2y_2 \end{cases}$$



$$Y' = AY$$

has eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$

This ODE has a fundamental set of sol. $Y^{(1)} = v_1 e^{\lambda_1 t}, \dots, Y^{(n)} = v_n e^{\lambda_n t}$.

0 is a hyperbolic equilibrium
 $\left\{ \begin{array}{l} \text{If } \lambda_1, \dots, \lambda_n < 0 \text{ then } \vec{0} \text{ is a stable equilibrium.} \\ \text{If } \lambda_1, \dots, \lambda_n > 0 \text{ then } \vec{0} \text{ is an unstable equilibrium.} \end{array} \right\} \vec{0} \text{ is a } \underline{\underline{\text{node}}}$.

If some of λ_k 's are positive, some are negative, then 0 is semistable equilibrium $\rightarrow \vec{0}$ is a saddle point.

If one of the λ_k 's is equal to 0 then $\vec{0}$ is called a non-hyperbolic equilibrium.

Ex: $Y' = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} Y \rightsquigarrow \lambda_1 = -1, \lambda_2 = 4$ $\vec{0}$ is a saddle point,

$Y' = \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix} Y \rightsquigarrow \lambda_1 = 1, \lambda_2 = 2$ $\vec{0}$ is an unstable node.

$Y' = \begin{bmatrix} -1 & 0 \\ 2 & -2 \end{bmatrix} \rightsquigarrow \lambda_1 = -1, \lambda_2 = -2$ $\vec{0}$ is a stable node.