

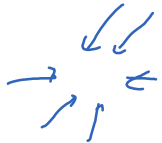
# Lecture 37

Wednesday, December 1, 2021 12:03 AM

\* Irager

\* Spiritual thought

Types of equilibrium states :  $Y' = AY$



stable node

all eigenvalues  $< 0$



unstable node

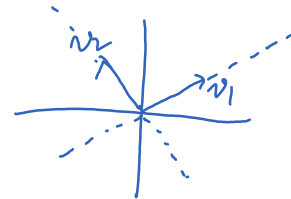
all eigenvalues  $> 0$



saddle point

some eigenvalues  $< 0$

some eigenvalues  $> 0$



What if eigenvalues are complex?

$$\underline{\underline{Ex}} \quad Y' = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} Y$$

$\rightarrow \vec{0}$  is a center point

Use Mathematica to draw....

$$\underline{\underline{Ex}} \quad Y' = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} Y$$

$\rightarrow \vec{0}$  is a spiral point

Use Mathematica to draw....

$$\lambda = \alpha + i\beta$$

If  $\alpha > 0$  : unstable spiral point

If  $\alpha = 0$  : center point

If  $\alpha < 0$  : stable spiral point

How to get real solutions (instead of complex solution) ?

$$\lambda_1 \xleftrightarrow[\text{conjugate}]{\text{Complex}} \lambda_2$$

$$v_1 \xleftrightarrow[\text{Conjugate}]{\text{Complex}} v_2$$

$$Y^{(1)} = v_1 e^{\lambda_1 t} \quad Y^{(2)} = v_2 e^{\lambda_2 t}$$

We replace these two complex solutions by a pair of real solutions.

How?  $Y^{(1)} = v_1 e^{\lambda_1 t} = u + i v$

↑      ↗  
vectors

$$Y^{(2)} = u - i v$$

$$\leadsto u = \frac{Y^{(1)} + Y^{(2)}}{2} \text{ is a solution}$$

$$\leadsto v = \frac{Y^{(1)} - Y^{(2)}}{2i} \text{ is a solution}$$

} the pair  $(Y^{(1)}, Y^{(2)})$  is replaced by the pair  $(u, v)$ .

Ex:  $Y' = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & -1 & 1 \end{bmatrix}}_A Y \rightsquigarrow \lambda_1 = 1, \lambda_{2,3} = 1 \pm i$  ( $d_2 = -1$ )

$v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Find  $v_2$ :

$$A - \lambda_2 I_3 = \begin{bmatrix} i & 0 & 0 \\ 0 & i & 1 \\ 0 & -1 & i \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & i & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = 0, \quad ix_2 + x_3 = 0$$

$$x_2 = 1, \quad x_3 = -i$$

$$v_2 = \begin{bmatrix} 0 \\ 1 \\ -i \end{bmatrix}$$

$$Y^{(2)} = v_2 e^{\lambda_2 t} = \begin{bmatrix} 0 \\ 1 \\ -i \end{bmatrix} e^{(1-i)t} = \begin{bmatrix} 0 \\ 1 \\ i \end{bmatrix} e^t (\cos t - i \sin t)$$

$$= e^t \begin{bmatrix} 0 \\ \cos t - i \sin t \\ i \cos t + \sin t \end{bmatrix}$$

$$= e^t \underbrace{\begin{bmatrix} 0 \\ \cos t \\ \sin t \end{bmatrix}}_u + i e^t \underbrace{\begin{bmatrix} 0 \\ -\sin t \\ \cos t \end{bmatrix}}_v$$

New fundamental set of sols:

$$e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, e^t \begin{bmatrix} 0 \\ \cos t \\ \sin t \end{bmatrix}, e^t \begin{bmatrix} 0 \\ -\sin t \\ \cos t \end{bmatrix}.$$

How to find the suitable coefficients to satisfy the initial conditions?

$$Y' = AY, \quad Y(t_0) = Y_0 \text{ given}$$

$$Y = c_1 Y^{(1)} + \dots + c_n Y^{(n)}$$

$$= \underbrace{\begin{bmatrix} | & & | \\ Y^{(1)} & \dots & Y^{(n)} \\ | & & | \end{bmatrix}}_{\Phi \text{-fundamental matrix}} \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

Substitute  $t = t_0$ :

$$Y_0 = \Phi(t_0) \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \rightsquigarrow \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = \Phi(t_0)^{-1} Y_0.$$