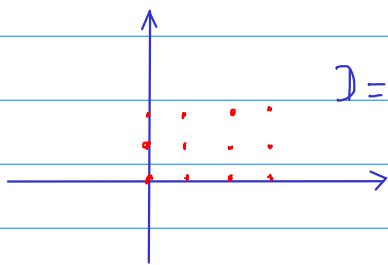


Lecture 12 (10/17/2018)

Review:

V subspace $\begin{cases} 0 \in V \\ v, w \in V \Rightarrow v + w \in V \\ c \in \mathbb{R}, v \in V \Rightarrow cv \in V \end{cases}$

Subspace of \mathbb{R}^3 $\begin{cases} \{0\} \\ \text{line through the origin} \\ \text{plane} \\ \mathbb{R}^3 \text{ itself} \end{cases}$

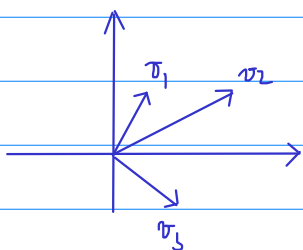


$D = \{(x, y) : x, y \in \mathbb{Z}\}$ is not a subspace. The third condition is violated.

$\text{Span}\{v_1, \dots, v_m\}$ consists of all linear combinations of v_1, \dots, v_m :

$$v = c_1 v_1 + c_2 v_2 + \dots + c_m v_m$$

The vectors v_1, \dots, v_m are said to be linearly independent if there are no nontrivial linear relations among them: if $c_1 v_1 + \dots + c_m v_m = 0$ then c_1, \dots, c_m must all equal to 0.



* A geometric way to explain linear independence:

Let's consider 3 vectors v_1, v_2, v_3 .

- Start at the origin
- walk distance c_1 along direction v_1
- then walk distance c_2 along direction v_2
- then c_3 v_3

These vectors are linearly ind. if you can never return to the origin unless you never move (i.e. when $c_1 = c_2 = c_3 = 0$).

* Check if a set of vectors is linearly independent.

Ex:

Consider $v_1 = (1, 2, 3)$
 $v_2 = (0, 1, 0)$
 $v_3 = (2, 3, -1)$

The system $c_1 v_1 + c_2 v_2 + c_3 v_3 = 0$ is equiv. to

$$c_1 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

This is a system of 3 eqs. and 3 unknowns. The matrix form is

$$\begin{array}{ccc} c_1 & c_2 & c_3 \\ \downarrow & \downarrow & \downarrow \\ \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 2 & 1 & 3 & 0 \\ 3 & 0 & -1 & 0 \end{array} \right] \end{array}$$

If this sys. has only trivial sol. ($c_1, c_2, c_3 = 0$)
then v_1, v_2, v_3 are linearly ind.
Otherwise (when the sys. has inf. many sols.),
 v_1, v_2, v_3 are linearly dep.

• General rule:

Given vectors v_1, \dots, v_m in \mathbb{R}^n . Establish matrix

$$A = \begin{bmatrix} \vdots & \vdots & \dots & \vdots \\ v_1 & v_2 & \dots & v_m \\ \vdots & \vdots & \dots & \vdots \end{bmatrix} \quad n \times m \text{ matrix}$$

Then find RREF of A .

If all cols. are pivot, the system $[A|0]$ has only one sol. (the trivial sol.). In this case, v_1, \dots, v_m are linearly independent.

If there is a nonpivot col., there are ∞ -many sol. Thus, v_1, \dots, v_m are lin. dep.

Special cases:

• $m > n$: A is a "flat" matrix RREF must have a nonpivot column.

m vectors in \mathbb{R}^n must be linearly dependent.
(there are too many vectors in \mathbb{R}^n to be lin. ind.)

• $m \leq n$: we have to go through the procedure.

If $m=n$, $\det A = 0$ lin. dep.
 $\det A \neq 0$ lin. ind.

Back to the example,

$$\begin{vmatrix} 1 & 0 & 2 \\ 2 & 1 & 3 \\ 3 & 0 & -1 \end{vmatrix} = -7 \neq 0. \text{ Thus } v_1, v_2, v_3 \text{ are lin. ind.}$$

* Another problem:

$$\text{Let } v_1 = (1, 2, 0)$$

$$v_2 = (2, 1, 1)$$

$$v = (1, 5, -1)$$

Is v a linear comb. of v_1 and v_2 ?

We want to solve the eq. $v = c_1 v_1 + c_2 v_2$ for c_1, c_2 . If this sys. is consistent, then v is indeed a linear comb. of v_1 and v_2 .

$$c_1 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ -1 \end{bmatrix}$$

Matrix form:

$$\left[\begin{array}{cc|c} 1 & 2 & 1 \\ 2 & 1 & 5 \\ 0 & 1 & -1 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{array} \right]$$

This sys. is consistent. Solution is $c_1 = 3$, $c_2 = -1$.

$$v = 3v_1 - v_2$$