

Lecture 26 (11/26/2018)

Application of matrix diagonalization in differential equations.

How do we solve $\dot{x} = x$?



Let $x(0) = 1$. What is $x(1)$?

Discretize the interval $[0, 1]$ into segments of length h (step size).

Denote $x_n = x(t_n)$ x at step n

$$x' \approx \frac{x_{n+1} - x_n}{h} \quad \dots \quad x' \text{ (approximated) at step } n$$

At step n :
$$\frac{x_{n+1} - x_n}{h} = x_n$$

$$\Rightarrow x_{n+1} = (1+h)x_n$$

Put $N = 1/h$ this is the number of time steps from $t=0$ to $t=1$.

$$\begin{aligned} x(1) &\approx x_N = (1+h)^N \underbrace{x_0}_{\text{the initial cond. } x(0)} \\ &= (1+h)^{\frac{1}{h}} x_0 \end{aligned}$$

Recall:

$$\lim_{h \rightarrow 0^+} (1+h)^{\frac{1}{h}} = e$$

Then $x(1) = e x_0$. In general, $x(t) = e^t x_0$.

* Consider system of differential equations:

$$\begin{cases} x_1' = x_1 + 4x_2 \\ x_2' = 2x_1 + 3x_2 \end{cases}$$

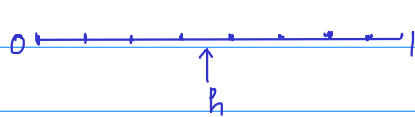
This type of systems is quite common in Mathematical Biology.

x_1 population of species (bacteria) 1, evolve with time.
 x_2 " " " " " "

The two species interact with each other. The population of one species supports the other.

How to solve?

$$X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow X' = \underbrace{\begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}}_A X$$



What is $X(1)$?

We repeat the above method.

$$\frac{X_{n+1} - X_n}{h} = AX_n$$

$$\Rightarrow X_{n+1} = (I + hA)X_n$$

Then

$$X_n = (I + hA)X_{n-1} = \dots = (I + hA)^n X_0 = (I + hA)^{\frac{1}{h}} X_0$$

How to take the limit $h \rightarrow 0^+$?

Suppose A is diagonalizable. $D = P^{-1}AP$
 $\Rightarrow A = PDP^{-1}$

$$I + hA = PIP^{-1} + P h D P^{-1} = P(I + hD)P^{-1}$$

$$\begin{aligned} \Rightarrow (I + hA)^n &= P(I + hD)^n P^{-1} \\ &= P \begin{bmatrix} (1 + h\lambda_1)^{\frac{1}{h}} & 0 \\ 0 & (1 + h\lambda_2)^{\frac{1}{h}} \end{bmatrix} P^{-1} \end{aligned}$$

$$\xrightarrow{h \rightarrow 0} P \begin{bmatrix} e^{\lambda_1} & 0 \\ 0 & e^{\lambda_2} \end{bmatrix} P^{-1}$$

$$\text{Thus, } X(1) = P \begin{bmatrix} e^{\lambda_1} & 0 \\ 0 & e^{\lambda_2} \end{bmatrix} P^{-1} X_0$$

In general,

$$X(t) = P \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix} P^{-1} X_0.$$

In this problem, $\lambda_1 = -1$, $\lambda_2 = 5$

$$v_1 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Then

$$x(t) = \begin{bmatrix} -2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} e^{-t} & 0 \\ 0 & e^{5t} \end{bmatrix} \begin{bmatrix} -2 & 1 \\ 1 & 1 \end{bmatrix}^{-1} x_0$$