Quiz 6

11/14/2018

Name:

Instructions: Show your work. Circle your final answers. The quiz has two pages.

1. Consider a basis $S = \{v_1, v_2, v_3\}$ of \mathbb{R}^3 where 2 pt $v_1 = (2, 6, 5)$ $v_2 = (5, 3, -2)$ $v_3 = (7, 4, -3)$

Set up a formula to compute the coordinate of vector b = (2, 3, 1) in basis S. (You don't need to compute matrix inverse or matrix multiplication. Only set up a correct formula for $[b]_{S}$.)

$$\begin{bmatrix} b \end{bmatrix}_{S} = \begin{bmatrix} v_{1} & v_{2} & v_{3} \\ 1 & 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} b \end{bmatrix}_{S_{0}} = \begin{bmatrix} Z & S & 7 \\ J & 3 & 4 \\ S & -Z & -S \end{bmatrix}^{-1} \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix}$$

2. Consider the matrix

$$A = \begin{bmatrix} 4 & 1\\ 6 & 3 \end{bmatrix}$$

2pt (a) Compute $det(A - \lambda I_2)$.

$$\operatorname{det}(A - \lambda \overline{1}_{\mathcal{L}}) = \begin{vmatrix} 4 - \lambda & 1 \\ 6 & 3 - \lambda \end{vmatrix} = (4 - \lambda)(3 - \lambda) - 6 = \lambda^{2} - 7\lambda + 6$$

(c) Determine $E(\lambda_1)$, the eigenspace corresponding to λ_1 . Determine a basis and the dimen- 2pt sion. null space of $A - I_z = \begin{bmatrix} 3 & 1 \\ 1 & -1 \end{bmatrix}$

$$\begin{bmatrix} 3 & | \\ 6 & 2 \end{bmatrix} \xrightarrow{R_2 = R_2 - 2R_1} \begin{bmatrix} 1 & 1/3 \\ 0 & 0 \end{bmatrix}$$

non pivot column

$$\begin{aligned} x_{2} &= t \\ x_{1} &= -43 \\ E(\lambda_{1}) &= \left\{ \begin{bmatrix} -1/3 \\ t \end{bmatrix} : t \in \mathbb{R} \right\} = span \left\{ \begin{bmatrix} -1/3 \\ 1 \end{bmatrix} \right\} \\ \begin{cases} t \\ t \end{bmatrix} \\ basis \end{aligned} \quad dim E(\lambda_{1}) = 1 \end{aligned}$$

 $2pt^{(d)} \text{ Determine } \underbrace{E(\lambda_2)}_{n \in \mathcal{U}}, \text{ the eigenspace corresponding to } \lambda_2. \text{ Determine a basis and the dimension.}$ $\begin{bmatrix} -2 & 1 \\ -6 & -3 \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} -2 & 1 \\ -6 & -3 \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} -2 & 1 \\ -6 & -3 \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ R_1 = R_1/(c_2) \\ R_1 = \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ R_1 = \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ R_1 = \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & -1/2 \\ R_1 = \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \begin{bmatrix} 1 & -1/2 \\ R_1 = \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)}$ $E(\lambda_2) = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \xrightarrow{R_2 = R_2 + 3R_1}_{R_1 = R_1/(c_2)} \xrightarrow{R_2 = R_2}_{R_1 = R_1/(c_2)} \xrightarrow{R_2 = R_2}_{R_2 = R_1/(c_2)} \xrightarrow{R_2 = R_1/(c_2)}_{R_2 = R_1/(c_2)}_{R_2 = R_1/(c_2)} \xrightarrow{R_1/(c_2)}_{R_2 = R_1/(c_2)}_{R_2 =$