Homework 2 Answer Key

1. Let V be a vector space over a field $F = \mathbb{Q}, \mathbb{R}, \mathbb{C}$. Suppose $v_1, v_2 \in V$ are linearly independent of each other. Show that vectors $v_1 + 2v_2$ and $2v_1 + 3v_2$ are linearly independent.

Solution: Let $c_1, c_2 \in \mathbb{R}$ and consider the equation

$$c_1(v_1 + 2v_2) + c_2(2v_1 + 3v_2) = \mathbf{0}$$

To show these vectors are linearly independent, we must show that $c_1 = 0$ and $c_2 = 0$.

$$c_{1}(v_{1} + 2v_{2}) + c_{2}(2v_{1} + 3v_{2}) = \mathbf{0}$$

$$\downarrow$$

$$c_{1}v_{1} + 2c_{1}v_{2} + 2c_{2}v_{1} + 3c_{2}v_{2} = \mathbf{0}$$

$$\downarrow$$

$$(c_{1} + 2c_{2})v_{1} + (2c_{1} + 3c_{2})v_{2} = \mathbf{0}$$

Now since v_1 and v_2 are linearly independent, we must have both the v_1 and v_2 coefficients from this last equation be equal to 0:

$$c_1 + 2c_2 = 0$$

 $2c_1 + 3c_2 = 0$

Now solve the system of equations (there are many ways to do this). Subtract 2 times the first equation from the second equation to get

$$-c_2 = 0 \qquad \rightarrow \qquad c_2 = 0.$$

Now that we know $c_2 = 0$, the first equation becomes

$$c_1 + 0 = 0 \qquad \rightarrow \qquad c_1 = 0.$$

Therefore $v_1 + 2v_2$ and $2v_1 + 3v_2$ are linearly independent.

2. Show that the functions $y_1 = \sin(x)$, $y_2 = \cos(x)$ and $y_3 = \sin(2x)$ are linearly independent over \mathbb{R} .

Solution: Let $c_1, c_2, c_3 \in \mathbb{R}$ and set an arbitrary linear combination equal to **0**:

$$c_1\sin(x) + c_2\cos(x) + c_3\sin(2x) = 0.$$

This must hold for all $x \in \mathbb{R}$. We want to show that $c_1 = c_2 = c_3 = 0$. To find these coefficients, we can plug in different values for x:

(notice that the last equation gives $c_3 = 0$, because we already knew that $c_1 = c_2 = 0$ from the first two equations). Therefore $\sin(x)$, $\cos(x)$, and $\sin(2x)$ are linearly independent.

3. Consider the set

$$V = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : a, b, c, d \in \mathbb{R}, a + d = 0 \right\}$$

(a) Show that V is a vector space over \mathbb{R} .

Solution: Notice that V is a subset of the vector space $M_{2\times 2}(\mathbb{R})$ of 2×2 real matrices. To show that V is a vector space, we only need to show that it is a subspace of $M_{2\times 2}(\mathbb{R})$. There are three axioms to check:

A0 - Closed under addition: Let $A, B \in V$ and write

$$A = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}$$
$$B = \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}$$

Then

$$A + B = \begin{bmatrix} a_1 + a_2 & b_1 + b_2 \\ c_1 + c_2 & d_1 + d_2 \end{bmatrix}$$

and

$$a_1 + a_2 + d_1 + d_2 = (a_1 + d_1) + (a_2 + d_2)$$

= 0 + 0 since $A, B \in V$
= 0

so $A + B \in V$.

S0 - Closed under scalar multiplication: Let

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in V$$

and let $\beta \in \mathbb{R}$. Then

$$\beta A = \begin{bmatrix} \beta a & \beta b \\ \beta c & \beta d \end{bmatrix}$$

and

$$\beta a + \beta d = \beta(a + d) = \beta(0) = 0,$$

so $\beta A \in V$.

A3 - V contains the zero vector: The zero vector is the matrix

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

with every coordinate equal to 0. Then a + d = 0 + 0 = 0, so the zero vector is in V.

(b) Find a basis for V.

Solution: A basis for V is a linearly independent subset that spans V. To ensure linear independence we want to find the smallest number of vectors we can that span V. The condition a + d = 0 gives d = -a, so any matrix in V can be written in the form

$$\begin{bmatrix} a & b \\ c & -a \end{bmatrix}$$

for some $a, b, c \in \mathbb{R}$. This can be rewritten as

$$\begin{bmatrix} a & b \\ c & -a \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & -a \end{bmatrix} + \begin{bmatrix} 0 & b \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ c & 0 \end{bmatrix}$$
$$= a \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

Which is a linear combination of three matrices. The set of these matrices

$$\{A, B, C\} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right\}$$

will be our proposed basis. To prove this is a basis we need to show three things:

- (i) $\{A, B, C\}$ is a subset of V: This is easy to check. For the matrix A, we have a = 1 and d = -1, so a + d = 0. For matrices B and C, a = 0 and d = 0, so again a + d = 0.
- (ii) {A, B, C} spans V (i.e., every element of V is a linear combination of A, B, and C): We saw above that any element of V can be written as

$$aA + bB + cC$$

which is a linear combination of A, B, and C.

(iii) $\{A, B, C\}$ is linearly independent: Set an arbitrary linear combination equal to 0:

$$aA + bB + cC = \mathbf{0}_{2 \times 2}$$

$$\downarrow$$

$$\begin{bmatrix} a & b \\ c & -a \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

where $a, b, c \in \mathbb{R}$. Looking at each matrix coordinate separately, we find that a = 0, b = 0, and c = 0. Therefore the set $\{A, B, C\}$ is linearly independent.

Thus all of the requirements for a basis are satisfied by $\{A, B, C\}$.

4. Are the functions $y_1 = \sin(x)$, $y_2 = \cos(x)$, and $y_3 = \sin(x+1)$ linearly independent over \mathbb{R} ? Verify your answer.

Solution: No. The functions are linearly dependent. To prove this, we need to find a nontrivial linear combination that is equal to zero. That is, we need to find numbers $c_1, c_2, c_3 \in \mathbb{R}$ (at least one of which is nonzero) such that

$$c_1 \sin(x) + c_2 \cos(x) + c_3 \sin(x+1) = 0.$$

for all $x \in \mathbb{R}$. The trick is to remember the sum-of-angles trig. identity:

$$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta.$$

Applying this to $\sin(x+1)$, we get

$$\sin(x+1) = \sin(x)\cos(1) + \cos(x)\sin(1).$$

Subtracting $\sin(x+1)$ from both sides gives

$$0 = \cos(1)\sin(x) + \sin(1)\cos(x) - \sin(x+1)$$

Now cos(1) and sin(1) are just constants, so this is a nontrivial linear combination that is equal to zero $(c_1 = cos(1), c_2 = sin(1), and c_3 = -1)$. Therefore these functions are linearly dependent.