

Lecture 4 (1/14/2019)

* Matrix:

$A + B$ A, B must be of the same size (same # rows, same # cols.)

cA any $c \in \mathbb{R}$, any matrix A

Combine: $A - B = A + (-1)B$

Ex

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 2 & 1 \\ 3 & 1 & 2 \end{bmatrix}$$

$$A - B = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 4 & 4 \end{bmatrix}$$

• Transpose:

A $m \times n$

A^T $n \times m$

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

rows of A are cols. of A^T

cols. of A are rows of A^T

• Multiplication:

$$\begin{array}{ccc} & AB & \dots \dots m \times p \\ \swarrow & \uparrow & \\ m \times n & & n \times p \end{array}$$

Ex

$$\underbrace{\begin{bmatrix} 1 & 2 & 3 \end{bmatrix}}_{1 \times 3} \underbrace{\begin{bmatrix} 2 & 0 & 1 \end{bmatrix}}_{1 \times 3} \dots \dots \text{not defined, sizes incompatible}$$

$$\underbrace{\begin{bmatrix} -1 \\ 0 \\ 4 \end{bmatrix}}_{3 \times 1} \underbrace{\begin{bmatrix} 5 & -3 & 7 \end{bmatrix}}_{1 \times 3} = \underbrace{\begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}}_{3 \times 3}$$

position (2,3):
2nd row \cdot 3rd col = $0 \times 7 = 7$

* Linear map: $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 want: $f(x) = Ax$

• Common practice:

View a vector in \mathbb{R}^n as an $n \times 1$ matrix (column vector).

Ex:

$$x = (2, 0, 3) \dots \dots x = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

• Know: a linear map from \mathbb{R}^2 to \mathbb{R}^2 has the form

$$f(x_1, x_2) = (a_1 x_1 + a_2 x_2, a_3 x_1 + a_4 x_2)$$

↑
matrix
↓

$$f\left(\underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x\right) = \begin{bmatrix} a_1 x_1 + a_2 x_2 \\ a_3 x_1 + a_4 x_2 \end{bmatrix} = \underbrace{\begin{bmatrix} a_1 & a_2 \\ a_3 & a_4 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x$$

$$f(x) = Ax$$

matrix column vector
 ↙ ↘
 matrix multiplication

• Ex:

linear maps from \mathbb{R}^2 to \mathbb{R} has the form

$$f(x_1, x_2) = ax_1 + bx_2$$

↑
matrix
↓

$$f\left(\underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_{f(x)}\right) = [ax_1 + bx_2] = \underbrace{[a \quad b]}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_x$$

- In general, $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear
 In matrix form, $f(x) = Ax$
 $m \times 1$ $m \times n$ $n \times 1$
 matrix representing f associated with f

How to find A ? two ways — list rows
 \ list cols.

Ex:

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^2, f(x_1, x_2, x_3) = (x_2 + x_3, x_1 - x_2 + x_3)$$

A ... 2×3 matrix

- Find A by listing its rows:

$$[0 \ 1 \ 1]$$

$$[1 \ -1 \ 1]$$

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}$$

Look at each output of f . List the factor in front of each variable (make sure in the right order).

- Find A by listing its cols:

$$e_1 = (1, 0, 0)$$

$$e_2 = (0, 1, 0)$$

$$e_3 = (0, 0, 1)$$

} standard basis of \mathbb{R}^3

$$f(e_1) = f(1, 0, 0) = (0, 1)$$

$$f(e_2) = f(0, 1, 0) = (1, -1)$$

$$f(e_3) = f(0, 0, 1) = (1, 1)$$

$$A = \begin{bmatrix} | & | & | \\ f(e_1) & f(e_2) & f(e_3) \\ | & | & | \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}$$

In general, $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 \uparrow standard basis $e_1 = (1, 0, \dots, 0)$
 $e_2 = (0, 1, 0, \dots, 0)$
 \dots
 $e_n = (0, 0, \dots, 0, 1)$

$$A = \left[\begin{array}{c|c|c|c} | & | & \dots & | \\ f(e_1) & f(e_2) & \dots & f(e_n) \\ | & | & & | \end{array} \right] \left. \vphantom{\begin{array}{c|c|c|c} | & | & \dots & | \\ f(e_1) & f(e_2) & \dots & f(e_n) \\ | & | & & | \end{array}} \right\} \begin{array}{l} m \text{ rows} \\ n \text{ cols.} \end{array}$$

* Algebra of linear maps:

$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$
 $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ } $f+g$ is a map defined by

$$(f+g)(x) = f(x) + g(x)$$

Ex:

$$f(x) = \sin x$$

$$g(x) = e^x$$

$f+g$ is a map that takes x to $\sin x + e^x$.

$$f \text{ } A$$

$$g \text{ } B$$

$$f+g \text{ } A+B$$

• Scaling:

cf the map that takes x to $cf(x)$

Ex:

$$f(x) = \sin x$$


$2f$ is the map that takes x to $2\sin x$

$$f \dots A$$

$$cf \dots cA$$

• Composition:

$$\mathbb{R}^p \xrightarrow{g} \mathbb{R}^n \xrightarrow{f} \mathbb{R}^m$$

$$x \mapsto g(x) \mapsto f(g(x))$$


Composite map, denoted by $f \circ g$

$f \circ g$: g takes argument, then f

Ex:

$$\mathbb{R}^2 \xrightarrow{g} \mathbb{R}^2 \xrightarrow{f} \mathbb{R}^3$$

$$g(x_1, x_2) = (x_1 + x_2, x_1)$$

$$f(x_1, x_2) = (0, x_1 - x_2, x_2)$$

What is $f \circ g$?

$$f \circ g(x_1, x_2) = f(g(x_1, x_2)) = f(x_1 + x_2, x_1)$$

$$f(y_1, y_2) = (0, y_1 - y_2, y_2)$$

$$\text{Here } y_1 = x_1 + x_2, \quad y_2 = x_1$$

$$= (0, x_1 + x_2 - x_1, x_1) = (0, x_2, x_1)$$

$$f \dots A = \begin{bmatrix} 0 & 0 \\ 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$$g \dots B = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

$$f \circ g \dots C = \begin{bmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = AB$$

Matrix multiplication is defined (the way we know) so that it represents the composition of linear maps.