

Lecture 13

Wednesday, February 5, 2020

Last time, we defined invariant subspace of a vector space with respect to a linear map. Consider a linear map $f: V \rightarrow V$. A subspace W of V is said to be invariant under f if $f(W) \subset W$.

A special invariant subspace of V is known as the eigenspace. Let $\lambda \in F$, which is the base field of V . The set

$$E_\lambda = \{v \in V : f(v) = \lambda v\}$$

consists of all vectors in V that get scaled by a factor of λ when applying f .

Ex: Show that E_λ is

(a) a subspace of V ,

(b) invariant under f .

The proof of (a) follows from the standard procedure: to check if E_λ is a subspace of V , knowing that it is already a subset of V , we only need to check 3 properties:

1) $0 \in E_\lambda$

2) E_λ is closed under addition.

3) E_λ is closed under scaling

How to check 2)? Let $v, w \in E_\lambda$. We want to show $v+w \in E_\lambda$.

Because $v, w \in V$, we have

$$f(v) = \lambda v,$$

$$f(w) = \lambda w.$$

To show that $v+w \in E_\lambda$, we need to show $f(v+w) = \lambda(v+w)$.

We have

$$\text{LHS} = f(v) + f(w) \quad (\text{because } f \text{ is linear})$$

$$= \lambda v + \lambda w \quad (\text{because } v, w \in E_\lambda)$$

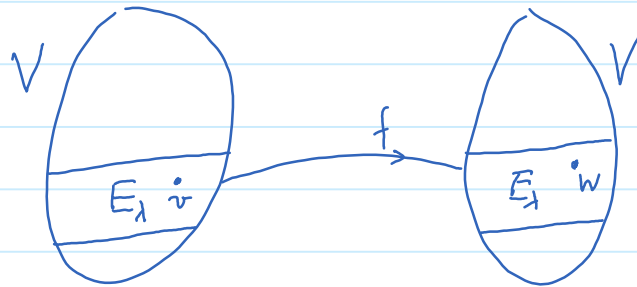
$$= \lambda(v+w)$$

$$= \text{RHS}.$$

Thus, we have proved 2) Why is 1) true? Notice that $f(0) = 0 = \lambda 0$.
 Thus, $0 \in E_\lambda$. Property 3) can be proven in the same manner as Property 2).

(b) How to show that E_λ is invariant under f ?

Let $v \in E_\lambda$. We show that $f(v) \in E_\lambda$.



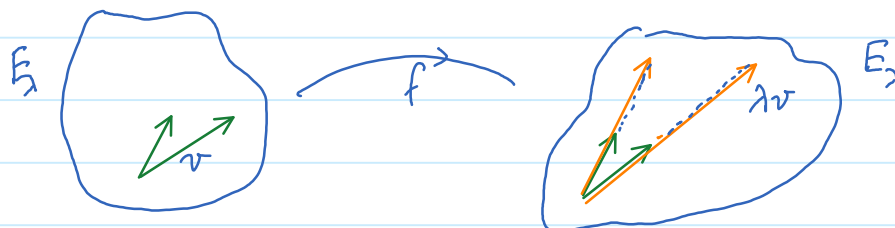
But $w = f(v)$. To show that $w \in E_\lambda$, we need to show $f(w) = \lambda w$.
 Because $v \in E_\lambda$, we have $f(v) = \lambda v$. In other words, $w = \lambda v$.
 We have

$$f(w) = f(\lambda v) = \lambda f(v) = \lambda w$$

which is what we wanted to show. ■

For most λ , E_λ is equal to $\{0\}$, the trivial vector space. There are some very special values λ such that $E_\lambda \neq \{0\}$. Those values are called **eigenvalues** of f . If λ is an eigenvalue of f then E_λ is called **eigenspace** corresponding to λ . A nonzero element of E_λ is called an **eigenvector** corresponding to λ .

In other words, an eigenvector of f corresponding to λ is a vector that gets scaled by factor λ when applying f .



An eigenvector of f is not rotated by f , only scaled. In E_λ , every vector is scaled by factor λ .

The notion of eigenvalue and eigenvectors of a linear map is a generalization of the notion of eigenvalues and eigenvectors of a matrix, which we already learned in Linear Algebra I. The connection between them is as follows.

If $A \in M_{n \times n}(F)$ then the eigenvalues and eigenvectors of A are exactly the eigenvalues and eigenvectors of the linear map $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ given by $f(v) = Av$.

Why so? If λ is an eigenvalue of A then there is some $v \neq 0$ such that $(A - \lambda I_n)v = 0$. This is equivalent to $Av - \lambda I_n v = 0$, or simply $Av = \lambda v$. Thus, $f(v) = \lambda v$. This means $v \in E_\lambda$ and $v \neq 0$. Then λ is an eigenvalue of f . One can also show that the converse is true: an eigenvalue of f is also an eigenvalue of A .

More generally, we have the following:

Let $f: V \rightarrow V$ be a linear map. Let \mathcal{B} be a basis of V , and $A = [f]_{\mathcal{B}}$ be the matrix that represents f in basis \mathcal{B} . Then the eigenvalues of f are the same as the eigenvalues of A and vice versa.

How do we see this? Let $\lambda \in F$ be an eigenvalue of f . By the definition of eigenvalues, we have $E_\lambda \neq \{0\}$. This means there is a nonzero vector $v \in V$ such that

$$f(v) = \lambda v.$$

Let us take the coordinate of both sides in basis \mathcal{B} .

$$[f(v)]_{\mathcal{B}} = [\lambda v]_{\mathcal{B}}$$

We know that

$$\text{LHS} = [f(v)]_{\mathcal{B}} = [f]_{\mathcal{B}} [v]_{\mathcal{B}} = A [v]_{\mathcal{B}},$$

$$\text{RHS} = [\lambda v]_{\mathcal{B}} = \lambda [v]_{\mathcal{B}}.$$

Hence, we obtain an equation

$$A[v]_{\mathcal{B}} = \lambda [v]_{\mathcal{B}}. \quad (*)$$

Note that $[v]_{\mathcal{B}} \neq 0$ because $v \neq 0$. From (*), we realize that $[v]_{\mathcal{B}}$ is an eigenvector of A and λ is the corresponding eigenvalue. We have showed that an eigenvalue of f is an eigenvalue of A . The converse can be shown similarly: an eigenvalue of A is also an eigenvalue of f .

We have found a connection between the eigenvalues of f and the eigenvalues of the matrix that represents f : they are the same.

How about the eigenspace E_{λ} of f and the eigenspace \tilde{E}_{λ} of $A = [f]_{\mathcal{B}}$? What is the relation between them? We know that

$$E_{\lambda} = \{v \in V : f(v) = \lambda v\},$$

$$\tilde{E}_{\lambda} = \{x \in \mathbb{R}^n : Ax = \lambda x\}. \quad (\text{Here } n = \dim V.)$$

From (*), we have

$$\tilde{E}_{\lambda} = \{[v]_{\mathcal{B}} : v \in E_{\lambda}\}$$

In other words, \tilde{E}_{λ} is the set of all the coordinates (in basis \mathcal{B}) of the eigenvectors of f .

This observation gives us a method to find the eigenvalues and eigenvectors of f by finding the eigenvalues and eigenvectors of the matrix $A = [f]_{\mathcal{B}}$. The procedure is as follows

- 1) Given a function $f: V \rightarrow V$, fix a basis \mathcal{B} of V and find the matrix $[f]_{\mathcal{B}}$. Call it A .
- 2) Find the eigenvalue λ 's and the corresponding eigenspaces \tilde{E}_{λ} of A . We know how to do this in Linear Algebra I.
- 3) For each eigenvalue λ , find a basis of \tilde{E}_{λ} .
- 4) Then convert this basis to a basis of E_{λ} .

Ex: Let $f: M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ be a linear map given by

$$f\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

Find the eigenvalues and the corresponding eigenspaces of f .

Fix a standard basis of $M_{2 \times 2}(\mathbb{R})$:

$$\mathcal{B} = \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}_{E_1}, \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{E_2}, \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}_{E_3}, \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{E_4} \right\}$$

We have

$$f(E_1) = f\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = E_4$$

$$f(E_2) = f\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & -1 \\ 0 & 0 \end{bmatrix} = -E_2$$

$$f(E_3) = f\left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & 0 \\ -1 & 0 \end{bmatrix} = -E_3$$

$$f(E_4) = f\left(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = E_1$$

Thus, the matrix that represents f in basis \mathcal{B} is

$$\begin{aligned} [f]_{\mathcal{B}} &= \begin{bmatrix} | & | & | & | \\ [f(E_1)]_{\mathcal{B}} & [f(E_2)]_{\mathcal{B}} & [f(E_3)]_{\mathcal{B}} & [f(E_4)]_{\mathcal{B}} \\ | & | & | & | \end{bmatrix} \\ &= \underbrace{\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}}_A \end{aligned}$$

What are the eigenvalues of A ?

$$\det(A - \lambda I_4) = \begin{vmatrix} -\lambda & 0 & 0 & 1 \\ 0 & -1-\lambda & 0 & 0 \\ 0 & 0 & -1-\lambda & 0 \\ 1 & 0 & 0 & -\lambda \end{vmatrix}$$

$$= \dots \\ = (\lambda+1)^3 (\lambda-1).$$

One can use Matlab to compute the eigenvalues of A as follows:

$$\gg A = [0 \ 0 \ 0 \ 1; \ 0 \ -1 \ 0 \ 0; \ 0 \ 0 \ -1 \ 0; \ 1 \ 0 \ 0 \ 0]$$

$$\gg \text{eig}(A)$$

A has two eigenvalues: $\lambda = \pm 1$.

Find eigenspace \tilde{E}_1 (corresponding to $\lambda = 1$):

To find \tilde{E}_1 , we find all vectors $x \in \mathbb{R}^4$ that satisfy

$$Ax = 1 \cdot x$$

This equation is equivalent to $(A - I_4)x = 0$

We are finding the null space of matrix $A - I_4$.

$$A - I_4 = \begin{bmatrix} -1 & 0 & 0 & 1 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 1 & 0 & 0 & -1 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\begin{matrix} \uparrow & \uparrow & \uparrow & \uparrow \\ x_1 & x_2 & x_3 & x_4 \end{matrix}$

 $\begin{matrix} \uparrow & \uparrow & \uparrow & \uparrow \\ x_1 & x_2 & x_3 & x_4 \end{matrix}$

We get $x_1 = x_4$, $x_2 = x_3 = 0$. Thus,

$$\tilde{E}_1 = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 : x_1 = x_4, x_2 = x_3 = 0\}$$

$$= \{(x_1, 0, 0, x_1) : x_1 \in \mathbb{R}\}$$

$$= \text{span}\{(1, 0, 0, 1)\}.$$

Thus, \tilde{E}_1 has basis $\{(1, 0, 0, 1)\}$.

Find eigenspace \tilde{E}_{-1} of A :

$$\text{We get } \tilde{E}_{-1} = \{(x_1, x_2, x_3, x_4) \in \mathbb{R}^4 : x_1 = -x_4\}$$

$$= \{(x_1, x_2, x_3, -x_1) : x_1, x_2, x_3 \in \mathbb{R}\}$$

$$= \text{span}\{(1, 0, 0, -1), (0, 1, 0, 0), (0, 0, 1, 0)\}.$$

One can use Matlab to assist the computation of the eigenvalues and eigenvectors of A as follows:

$$\gg A = [0 \ 0 \ 0 \ 1; \ 0 \ -1 \ 0 \ 0; \ 0 \ 0 \ -1 \ 0; \ 1 \ 0 \ 0 \ 0]$$

$$\gg [a, b] = \text{eig}(A)$$

Matlab returns:

$$a = \begin{bmatrix} 0 & 0 & 0.7071 & 0.7071 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & -0.7071 & 0.7071 \end{bmatrix}$$

$$b = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Matrix b is a diagonal matrix that contains the eigenvalues of A on the diagonal. Matrix a consists of eigenvectors of A (aligned as columns) corresponding to the eigenvalues in b . For example, the vector

$$v_1 = \begin{bmatrix} 0 \\ 0 \\ -1 \\ 0 \end{bmatrix}$$

which is the first column of a is an eigenvector of $\lambda = -1$.

Vectors

$$v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{and} \quad v_3 = \begin{bmatrix} 0.7071 \\ 0 \\ 0 \\ -0.7071 \end{bmatrix}$$

are also eigenvectors of $\lambda = -1$. Why does the entries of v_3 look so ugly? This is because Matlab tried to rescale eigenvector to be of magnitude 1. The magnitude of v_3 is

$$\sqrt{(0.7071)^2 + 0^2 + 0^2 + (-0.7071)^2} = 1$$

One can replace v_3 by $v'_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}$

which is a nicer scaling of v_3 . Continue next time.