Name: Answer Key

Recitation time:

Show your work for each problem.

1. Consider \mathbb{R}^3 as an inner product space with the standard inner product denoted by (\cdot, \cdot) . Let *E* be the subspace of \mathbb{R}^3 given by

$$E = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3 : a - b + c = 0 \right\}.$$

(a) Find an orthonormal basis for E. Solution: First we need to find a basis for E (not necessarily orthogonal). Notice that we can rewrite E as

$$E = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3 : a - b + c = 0 \right\} = \left\{ \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3 : a = b - c \right\}$$
$$= \left\{ \begin{bmatrix} b - c \\ b \\ c \end{bmatrix} : b, c \in \mathbb{R} \right\}$$
$$= \left\{ b \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} : b, c \in \mathbb{R} \right\}$$
$$= \operatorname{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

A basis for E is given by

$$\{u_1, u_2\} = \left\{ \begin{bmatrix} 1\\1\\0\\\end{bmatrix}, \begin{bmatrix} -1\\0\\1\\\end{bmatrix} \right\}.$$

To find an orthogonal (not necessarily orthonormal) basis $\{w_1, w_2\}$, we apply the Gram-Schmidt process:

$$w_1 = u_1,$$

 $w_2 = u_2 - \text{proj}_{w_1}(u_2).$

In this case,

$$\operatorname{proj}_{w_1}(u_2) = \frac{(u_2, w_1)}{(w_1, w_1)} w_1 = \frac{(-1)(1) + (0)(1) + (1)(0)}{(-1)(-1) + (1)(1) + (0)(0)} \begin{bmatrix} 1\\1\\0 \end{bmatrix} = -\frac{1}{2} \begin{bmatrix} 1\\1\\0 \end{bmatrix}$$

Therefore

$$w_2 = \begin{bmatrix} -1\\0\\1 \end{bmatrix} - \left(-\frac{1}{2}\right) \begin{bmatrix} 1\\1\\0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2}\\\frac{1}{2}\\1 \end{bmatrix}$$

Now $\{w_1, w_2\}$ is an orthogonal (but not orthonormal) basis for E. We can scale any of the vectors without affecting the orthogonality, so we will multiply w_2 by 2 to get the orthogonal basis

$$\{z_1, z_2\} = \left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\1\\2 \end{bmatrix} \right\}.$$

To find an orthonormal basis $\{v_1, v_2\}$, we simply normalize w_1 and w_2 :

$$v_{1} = \frac{z_{1}}{\|z_{1}\|} = \frac{z_{1}}{\sqrt{(z_{1}, z_{1})}} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\1\\0 \end{bmatrix} = \frac{\sqrt{2}}{2} \begin{bmatrix} 1\\1\\0 \end{bmatrix}.$$
$$v_{2} = \frac{z_{2}}{\|z_{2}\|} = \frac{z_{2}}{\sqrt{(z_{2}, z_{2})}} = \frac{1}{\sqrt{6}} \begin{bmatrix} -1\\1\\2 \end{bmatrix} = \frac{\sqrt{6}}{6} \begin{bmatrix} -1\\1\\2 \end{bmatrix}.$$

(b) Find the orthogonal projection of $v = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ onto E. Solution: Consider the orthogonal basis

$$\{z_1, z_2\} = \left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\1\\2 \end{bmatrix} \right\}.$$

for E that we found in part (a). Then

$$proj_{E}(v) = proj_{z_{1}}(v) + proj_{z_{2}}(v)$$

$$= \frac{(v, z_{1})}{(z_{1}, z_{1})} z_{1} + \frac{(v, z_{2})}{(z_{2}, z_{2})} z_{2}$$

$$= \frac{3}{2} \begin{bmatrix} 1\\1\\0 \end{bmatrix} + \frac{7}{6} \begin{bmatrix} -1\\1\\2 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 2\\16\\14 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 1\\8\\7 \end{bmatrix}.$$

2. Consider the following set of points in the x-y plane:

$$\{(1,2), (3,4), (4,-2), (5,5), (-1,5)\}.$$

Set up an equation to find the best fit quadratic polynomial for these points. That is, find a matrix \mathbf{A} and a vector \mathbf{b} such that the least squares solution to

$$\mathbf{A}\begin{bmatrix}a\\b\\c\end{bmatrix} = \mathbf{b}$$

defines the best fit polynomial $f(x) = ax^2 + bx + c$. Recall that the least squares solution to $\mathbf{Ax} = \mathbf{b}$ is the ordinary solution to $\mathbf{A^*Ax} = \mathbf{A^*b}$.

Solution: Given the unknown quadratic polynomial ax^2+bx+c , we want to choose $a, b, c \in \mathbb{R}$ to minimize the quantity

$$\sum_{k=1}^{n} |ax_k^2 + bx_k + c - y_k|^2.$$

This is equivalent to minimizing

$$\begin{vmatrix} x_1^2 & x_1 & 1 \\ x_2^2 & x_2 & 1 \\ \vdots & \vdots & \vdots \\ x_n^2 & x_n & 1 \end{vmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} - \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \end{vmatrix}.$$

That is, we want to find the least squares solution to

$$\mathbf{A}\begin{bmatrix}a\\b\\c\end{bmatrix} = \mathbf{b}$$

where

$$\mathbf{A} = \begin{bmatrix} 1^2 & 1 & 1 \\ 3^2 & 3 & 1 \\ 4^2 & 4 & 1 \\ 5^2 & 5 & 1 \\ (-1)^2 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 9 & 3 & 1 \\ 16 & 4 & 1 \\ 25 & 5 & 1 \\ 1 & -1 & 1 \end{bmatrix}$$

and

$$\mathbf{b} = \begin{bmatrix} 1\\4\\-2\\5\\5 \end{bmatrix}.$$

To find a, b, c, you need to solve

$$\mathbf{A}^*\mathbf{A}\begin{bmatrix}a\\b\\c\end{bmatrix}=\mathbf{A}^*\mathbf{b}.$$

This is a standard augmented matrix row-reduction exercise, so I will leave it to you to finish.

3. Let $B = A^*A$ where

$$A = \begin{bmatrix} 1 & i \\ 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

Find the eigenvalues and eigenvectors of *B*. Is *B* orthogonally diagonalizable (under the standard inner product $(x, y) = x_1\overline{y_1} + x_2\overline{y_2}$ on \mathbb{C}^2)?

Solution: First calculate A^* :

$$A^* = \begin{bmatrix} 1 & 1 & 0 \\ -i & 0 & 1 \end{bmatrix}.$$

Now

$$B = A^*A = \begin{bmatrix} 1 & 1 & 0 \\ -i & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & i \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & i \\ -i & 2 \end{bmatrix}.$$

Calculating the eigenvalues and eigenvectors of B should be a standard exercise by now, so I will omit the details. You should get eigenvalues $\lambda_1 = 1$ and $\lambda_2 = 3$ with associated eigenspaces

$$E_1 = \left\{ a \begin{bmatrix} -i \\ 1 \end{bmatrix} : a \in \mathbb{C} \right\}$$

and

$$E_3 = \left\{ b \begin{bmatrix} i \\ 1 \end{bmatrix} : b \in \mathbb{C} \right\}.$$

Notice that the geometric multiplicity matches the algebraic multiplicity for each eigenvalue, so B is diagonalizable. To see that it is *orthogonally* diagonalizable, note that

$$\left(\begin{bmatrix} -i \\ 1 \end{bmatrix}, \begin{bmatrix} i \\ 1 \end{bmatrix} \right) = (-i)(\overline{i}) + (1)(\overline{1}) = (-i)(-i) + (1)(1) = -1 + 1 = 0,$$

so these eigenvalues are orthogonal.

We didn't need to calculate the eigenspaces to know that B was orthogonally diagonalizable. Notice that B satisfies

$$B^* = (A^*A) = A^*(A^*)^* = A^*A = B,$$

so B is self-adjoint. It is a fact that every self-adjoint matrix is orthogonally diagonalizable.

4. Let V be the set of continuous functions from [0,1] to \mathbb{R} . Equip V with the inner product

$$(f(x), g(x)) = \int_0^1 f(x)g(x) \, dx.$$

Let $E = \text{span}\{1, x\}$. Find $\text{proj}_E(g)$ where $g(x) = \frac{1}{x^2 + 1}$.

Solution: First we need to find an orthogonal basis for E by applying the Gram-Schmidt process. We start with the basis

$$\{w_1, w_2\} = \{1, x\}$$

Our orthogonal basis is $\{v_1, v_2\}$ where

$$v_1 = w_1,$$

 $v_2 = w_2 - \operatorname{proj}_{v_1}(w_2)$

We need to calculate two inner products:

$$(w_2, v_1) = (x, 1) = \int_0^1 x \, dx = \frac{1}{2}$$

and

$$(v_1, v_1) = \int_0^1 1 \, dx = 1.$$

Therefore

$$v_2 = w_2 - \operatorname{proj}_{v_1}(w_2) = x - \frac{(x,1)}{(1,1)} 1 = x - \frac{1}{2},$$

so our orthogonal basis for ${\cal E}$ is

$$\{v_1, v_2\} = \{1, x - \frac{1}{2}\}$$

To calculate $\operatorname{proj}_E(g)$ we will need to calculate a few more inner products:

$$(g, v_1) = \int_0^1 \frac{1}{x^2 + 1} dx = \tan^{-1}(x) \Big|_0^1 = \frac{\pi}{4} - 0 = \frac{\pi}{4}$$
$$(g, v_2) = \int_0^1 \frac{x}{x^2 + 1} - \frac{1}{2} \cdot \frac{1}{x^2 + 1} dx$$
$$= \frac{1}{2} \ln(x^2 + 1) - \frac{1}{2} \tan^{-1}(x) \Big|_0^1$$
$$= \frac{1}{2} \ln(2) - \frac{\pi}{8}$$

$$(v_2, v_2) = \int_0^1 (x - \frac{1}{2})^2 dx = \frac{1}{12}$$

We can now calculate $\operatorname{proj}_E(g)$:

$$\operatorname{proj}_{E}(g) = \frac{(g, v_{1})}{(v_{1}, v_{1})} v_{1} + \frac{(g, v_{2})}{(v_{2}, v_{2})} v_{2}$$
$$= \frac{\pi}{4} v_{1} + \frac{\frac{1}{2} \ln(2) - \frac{\pi}{8}}{\frac{1}{12}} v_{2}$$
$$= \frac{\pi}{4} + \left(6 \ln(2) - \frac{3}{2}\pi\right) (x - \frac{1}{2}).$$