Name:

1. Given an integer n and numbers α_j , β_j , γ_j for j = 1, 2, ..., n - 1, how would you solve for $M_1, M_2, ..., M_n$ from the following system?

$$\begin{array}{rcl} \alpha_1 M_1 + \beta_1 M_2 & = & \gamma_1, \\ \alpha_2 M_2 + \beta_2 M_3 & = & \gamma_2 \\ \dots & \dots & \dots \\ \alpha_{n-1} M_{n-1} + \beta_{n-1} M_n & = & \gamma_{n-1}. \end{array}$$

Can you write an algorithm to solve it?

Decause there are n unknowns and n-1 equations, we have the greedom to choose one unknown. Let us choose $M_1 = 0$. Then M_2 can be found from the first equation: $M_2 = \frac{Y_1 - \alpha_1 M_1}{\beta_1}$. Then M_3 can be found from the second equation $M_3 = \frac{Y_2 - \alpha_2 M_2}{\beta_2}$ and so on. One can write the procedure as an algorithm as

follows.

$$M_{i} = a ; \quad (some specific number, for j = 2: n)$$

$$M_{j} = \frac{\eta_{j-1} - \varkappa_{j-1} M_{j-1}}{\beta_{j-1}}$$
end

* Matrix method:

One can solve the system using matrix method. With M, considered as being known, we can write the system as

In matrix form,

$$\begin{pmatrix} \beta_{1} & 0 & \cdots & 0 \\ \alpha_{2} & \beta_{2} & 0 & \cdots & 0 \\ 0 & \alpha_{3} & \beta_{3} & 0 & \cdots & 0 \\ \vdots & \vdots & & \\ 0 & 0 & \cdots & \beta_{n-1} \end{pmatrix} \begin{bmatrix} M_{2} \\ M_{3} \\ \vdots \\ \vdots \\ M_{n} \end{bmatrix} = \begin{bmatrix} 0_{1} - \alpha_{1} M_{1} \\ T_{2} \\ \vdots \\ \vdots \\ T_{n-1} \end{bmatrix}$$

$$(h-1) \times (n-1) \qquad (n-1) \times 1 \qquad (h-1) \times 1$$

This is the form AX = b. The solution is $X = A^{-1}b$. One can enter matrix A in Matlab by first initializing A as an $(n-1) \times (n-1)$ matrix whose entries are all zeros.

$$A = zeros(n-1);$$

Then we fix the coefficients on the diagonal:
for $j = 1: n-1$
 $A(j,j) = \beta_j,$
end

Then we fix the coefficients on the sub-diagonal
for
$$j = l: n-2$$

 $A(j_1j+l) = \alpha_{j+1} j$
end

2. How would you plot the following functions on the interval [0,3] on the same graph using Matlab? (Use the command **hold on**)

$$s_1(t) = -t^2 + t$$

$$s_2(t) = t^2 - 3t + 2$$

$$s_3(t) = t^2 - 5t + 6.$$

```
See Lecture 24 (toward the end).
```