





Reinforcement Learning Prediction Intervals with Guaranteed Fidelity

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Prospective MDP Performance Guarantee

Human decision maker must decide whether to command an AI assistant to execute policy π starting in state s_0 for *H* steps

Al assistant provides a trajectory-wise prediction interval that guarantees with probability $1 - \delta$ that its behavior will be inside the interval







- Generate a set of trajectories
 - Repeat N times
 - Sample a starting state $s_0 \sim P_0(\cdot)$
 - Execute π for h steps to obtain a trajectory
- Apply our new technique
 - Perform quantile regression to learn two functions
 - $F_t^{-1}\left(s_0, \frac{\delta}{2}\right)$ an estimate of the $\frac{\delta}{2}$ quantile of the return at time t
 - $F_t^{-1}\left(s_0, 1-\frac{\delta}{2}\right)$ an estimate of the $1-\frac{\delta}{2}$ quantile of the return at time t
 - Adjust these to obtain valid prediction intervals using a new method, SDSCALEDBOX







- Background: Conformal Prediction Intervals
- Core Problem: Multivariate Prediction Interval
- Prediction Intervals for MDP Trajectories
- Experimental Results
 - Tamarisk invasions
 - StarCraft battles
- Assessment





- Let $x_1, \ldots, x_n, x_{n+1} \sim P(\cdot) \ x_i \in \mathbb{R}$ "exchangeable draws"
- Define $S = \{x_1, \dots, x_n\}$ "training data"
- Goal:
 - Determine hi(S) such that
 - $\Pr_{x_{n+1} \sim P}[x_{n+1} \le hi(S)] \ge 1 \delta$
- Method
 - Let $x_{(1)}$, ..., $x_{(n)}$ be the order statistics (sorted order) of x_1 , ..., x_n
 - $hi(S) \coloneqq x_{(\lceil (1-\delta)(n+1)\rceil)}$





- Suppose we computed
 - $x_{(1)}, \dots, x_{(n)}, x_{(n+1)}$
 - The rank of x_{n+1} will be uniformly distributed within these ranks (exchangeability)
 - The 1δ quantile will be $x_{([(1-\delta)(n+1)])}$
 - $\Pr[x_{n+1} \le x_{([(1-\delta)(n+1)])}] \ge 1 \delta$
 - Where would the corresponding quantile be in $x_{(1)}, \dots, x_{(n)}$?
 - At quantile $(1 \delta) \frac{n+1}{n}$, because we now have only n points
 - This will be position $[(1 \delta)(n + 1)]$
- This works as long as $\delta \ge \frac{1}{n+1}$







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- Given:
 - $D_1 = \mathbf{x}_1, \dots, \mathbf{x}_m \sim P \text{ iid}$ $D_2 = \mathbf{x}_{m+1}, \dots, \mathbf{x}_n \sim P \text{ iid}$ $\mathbf{x}_i \in \mathbb{R}^d \quad \forall i$ δ
- Find
 - *lo*, $hi \in \mathbb{R}^d$
 - $\Pr_{x_{n+1} \sim P}[lo \le x_{n+1} \le hi] \ge 1 \delta$
- Challenge: Avoid thinking of this as d separate prediction intervals, as that requires a Bonferonni correction (or related method)
- Trick: Convert to a one-dimensional problem and apply conformal methods





SDSCALEDBOX

- Compute mean and sample standard deviation from D₁
 - $\hat{\mu}_j \ \forall j$
 - $\hat{\sigma}_j \ \forall j$
- Proposed prediction interval:
 - $\hat{\mu}_j \pm \beta \hat{\sigma}_j$
 - β is our one-dimensional parameter
- Rescale the D₂ data along each dimension

•
$$x'_{ij} \coloneqq 0$$
 if $\hat{\sigma}_j = 0$
• $x'_{ij} \coloneqq \frac{|x_{ij} - \hat{\mu}_j|}{\hat{\sigma}_j}$ else

- Let $c_i \coloneqq \max_i x'_{ij}$
 - "widest dimension of standardized x_i "
- Sort to obtain $c_{(1)}$, ..., $c_{(14)}$

$$\beta = c_{(\lceil (1-\delta) \cdot 15 \rceil)}$$







Theorem 1. Let $x_1, ..., x_n, x_{n+1} \in \mathbb{R}^d$ be independent random variables with distribution *P*. Let [*lo*, *hi*] be the multidimensional interval computed by SDSCALEDBOX when applied to $x_1, ..., x_n$ with $2 \le m < n$ and confidence parameter $\delta \in \left[\frac{1}{n-m}, 1\right)$. Then with probability $1 - \delta$ $lo \le x_{n+1} \le hi$.





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DARPA Prospective Prediction Intervals for MDP Policies

- Discrete time MDP with state space S, starting state distribution P_0 , and fixed policy π
- h-step trajectory au
 - sample $s_0 \sim P_0$
 - execute π for h steps
 - collect states, actions, and rewards into au
- Define a *behavior function* $B(\tau, t)$ to summarize the behavior of the policy at time t
 - some aspect of s_t
 - immediate reward
 - cumulative reward $r_1 + \cdots + r_{t-1}$
 - future reward $r_t + r_{t+1} + \dots + r_{h-1}$
 - $\boldsymbol{b}(\tau) = (b_{\tau,1}, \dots, b_{\tau,h})$ is the "behavior vector" of trajectory τ
- Prospective prediction interval
 - $lo(s_0) \le b(\tau) \le hi(s_0)$ with probability 1δ





- P(y|x) depends arbitrarily on x
- F(y|x)
 - cumulative distribution function of y at x
- $F^{-1}(q|x)$
 - the value of y such that F(y|x) = q
- Many algorithms for quantile regression
- We employ Quantile Random Forests (Meinshausen, 2006) to compute the $\delta/2$ and $1 \delta/2$ quantiles



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- Romano, Patterson & Candes (NeurIPS 2019) Conformalized Quantile Regression
- Idea: Compute the "error" between the observed values y_i and the predicted quantile F⁻¹(x_i; q) and conformalize to get a "correction"
- Two data sets:
 - D_1 : used for fitting $F^{-1}(x;q)$
 - D₂: used for conformalization
- For $(x_i, y_i) \in D_2$; i = 1, ..., n $c_i \coloneqq y_i - F^{-1}(x_i; q)$
- Sort to obtain $c_{(1)}$, ..., $c_{(n)}$
- Bound: $hi(x) \coloneqq F^{-1}(x;q) + c_{([(1-\delta)(n+1)])}$
- Let (x_{n+1}, y_{n+1}) be a new data point
 $c_{n+1} := y_{n+1} F^{-1}(x, q)$
- Claim: The c_i values are exchangeable → rank of c_{n+1} will be uniformly distributed in $c_{(1)}$, ..., $c_{(n+1)}$
- Therefore, $P[c_{n+1} \le hi(x_{n+1})] \ge 1 \delta$







Idea: Extend Conformalized Quantile Regression to Multiple Dimensions

- Three data sets
 - D₁: behavior vectors for quantile regression
 - D_2 : behavior vectors for computing $\hat{\sigma}_t$
 - D₃: behavior vectors for computing *lo*, *hi*
- Plan:
 - Fit quantile regression models $F_t^{-1}(s_0; \delta/2)$ and $F_t^{-1}(s_0; 1 \delta/2)$ to D_1 for each time step t
 - Compute "exceedances": the amount that each trajectory goes outside the quantile regression prediction
 - Compute $\hat{\sigma}_t$ for the exceedances at time t using D_2
 - Use $\hat{\sigma}_t$ to standardize the exceedances of D_3
 - Compute conformal prediction intervals on the exceedances





•
$$x_{i,t} = \max\left(0, F_t^{-1}\left(s_0(\tau_i), \frac{\delta}{2}\right) - b_{i,t}, b_{i,t} - F_t^{-1}\left(s_0(\tau_i), 1 - \frac{\delta}{2}\right)\right)$$







Conformalized Quantile Regression: SDSCALEDQUANTILES

- Given:
 - *D*₁: behavior vectors for quantile regression
 - D_2 : behavior vectors for computing $\hat{\sigma}_t$
 - D₃: behavior vectors for computing *lo*, *hi*
- Fit quantile regression models $F_t^{-1}(s_0; \delta/2)$ and $F_t^{-1}(s_0; 1 \delta/2)$ to D_1 for each time step t
- Compute "exceedances": x_{i,t} the amount that trajectory i goes outside the quantile regression prediction at time t
- Compute $\hat{\sigma}_t$ of the exceedances $x_{i,t}$ at time t using D_2
- Rescale exceedances: $x'_{i,t} \coloneqq \frac{x_{i,t}}{\widehat{\sigma}_t}$
- Compute c_i for each trajectory in D_3

•
$$c_i \coloneqq \max_t x'_{i,t}$$

- Compute order statistics $c_{(1)}$, ..., $c_{(n)}$
- $\beta \coloneqq (1 \delta) \left(\frac{n+1}{n}\right)$ quantile of the *c* values
- $lo_t \coloneqq F_t^{-1}(s_0; \delta/2) \beta \hat{\sigma}_t$
- $hi_t \coloneqq F_t^{-1}(s_0; 1 \delta/2) + \beta \hat{\sigma}_t$





Theorem 2. The behavior vector $\boldsymbol{b}(\tau_{n+1})$ will fall within the prediction interval $[\boldsymbol{lo}, \boldsymbol{hi}]$ returned by SDSCALEDQUANTILES with probability $1 - \delta$

See also: Lei, Rinaldo & Wasserman (2013). Related result for general functional data





- The $c_{(\lceil (1-\delta)(n+1)\rceil)}$ estimate of the $(1-\delta)\frac{n+1}{n}$ quantile is unbiased but often low for small samples
- We want the estimation error to be ≥ 0 with probability $1-\delta$
- Solution: Use the 1δ upper bound confidence interval on the target quantile (heuristic)

Strict estimation error 0.90 quantile of t(df=1)



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- Fraction of 1000 trials in which Strict and CI methods exceeded the true target quantile
- CI computed according to Nyblom (1992)





- 1. Quantile regression
- 2. $(1 \delta) \frac{n+1}{n}$ quantile of *c* from conformalization
- 3. (1δ) upper confidence bound on #2





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- States:
 - 7 edge river network
 - edge can be
 - I: invaded with tamarisk tree
 - N: occupied by native tree
 - E: empty
- Actions:
 - Plant native
 - Eradicate tamarisk
 - Eradicate + Plant
 - No-Op
- Budget restricts us to one action on one edge per time step
- See Hall, Albers, Alkaee-Taleghan, Dietterich (2018)





DARPA Example Prospective Intervals and Actual Trajectories



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Tamarisk Prediction Interval Coverage

Raw QR: 0/16 Strict: 16/16 CI: 16/16





Prediction Interval Widths





- Blue units: unif(5, 20)
- Red units: unif(5, 10)
- At time 14, Red receives reinforcements unif(0, N) where $N \sim unif(0, 15)$







Starcraft Prediction Interval Coverage

Raw QR: 2/16 Strict: 5/16 CI: 14/16





Starcraft Prediction Interval Widths







- Guarantee: With probability 1δ the total exceedance along the trajectory will be T
- Compute the Quantile Regression predictions
- Let c_i = the *total exceedance* of each trajectory in D_3
- Sort to obtain $c_{(1)}, \ldots, c_{(n)}$
- Compute the $\left[(1 \delta) \left(\frac{n+1}{n} \right) \right]$ quantile of these as the upper bound



DARPA Tamarisk Total Exceedance Coverage

Both methods achieve target coverage in all cases





DARPA Tamarisk Total Exceedance Bounds







Strict method fails 3 times CI method covers all 16 cases







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- Conformal Prediction Intervals for *d*-dimensional data
- Trajectory-wise Prediction Intervals
- Excellent performance on two MDPs
- Alternative of Total Exceedance Bounds is ok for Starcraft but not for Tamarisk





- The guarantees are semi-conditional
 - The quantile regressions are conditioned on s_0
 - The conformal corrections are unconditional ("marginal") and are taken over P_0
- If the failures are scattered throughout the state space, this is not a serious issue
- But if the failures are concentrated in one region, then the claim is misleading
- Additional techniques are required to address this shortcoming





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